FCC ID: VUJAT287UHF

Report No.: DRTFCC1312-1171

Total 55pages

SAR TEST REPORT

	Test item	:	UHF RFID Reader		
	Model No.	:	AT287-UHF		
	Order No.	:	DEMC1212-02951		
	Date of receipt		2012-12-17		
	Test duration	:	2013-11-21		
	Date of issue	:	2013-12-11		
	Use of report	:	FCC Original Grant		
Applicant	: ATID Co., Ltd	ł.			
			yungin digital valley II	#481-10	0Gasan-Dong,
	Gumchon-Gu	ı,Sec	oul153-803, Korea		
Test laboratory	: Digital EMC (Co I	td		
root laboratory				n-Si Gv	veonggi-Do, 449-080, Korea
	000 0, 145411	g D	ong, oncom ou, rong	., 0, 0	roonggi bo, Tro ooo, Koroa
	Test rule part	:	47CFR §2.1093		
	Test environment	;	See appended test r	eport	
	Test result	:	□ Pass	☐ Fa	il
The	test results presented i	n this	test report are limited only to	the samp	le supplied by applicant and
	nis test report is inhibited	dothe	than its purpose. This tes	t report sh	all not be reproduced except in full,
	withou	ut the	written approval of DIGITAL	. EMC CO	., LID.
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Engineer		Engir	neer		Technical Director
NoKyun, Im	V	N/A			Harvey Sung

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Test Report Version

Test Report No.	Date	Description
DRTFCC1312-1171	Dec. 11, 2013	Final version for approval

1. DESCRIPTION OF DEVICE

Environmental evaluation measurements of specific absorption rate (SAR) distributions in emulated human head and body tissues exposed to radio frequency (RF) radiation from wireless portable devices for compliance with the rules and regulations of the U.S. Federal Communications Commission (FCC).

General Information:

Equipment type	UHF RFID Read	UHF RFID Reader				
FCC ID	VUJAT287UHF					
Equipment model name	AT287-UHF					
Equipment add model name	N/A					
Equipment serial no.	Identical prototy	pe				
Mode(s) of Operation	RFID					
TX Frequency Range	902.75 ~ 927.25	MHz (RFID)				
RX Frequency Range	902.75 ~ 927.25 MHz (RFID)					
		Measured	Reported SAR			
Equipment Class	Band	Conducted Power	1g SAR (W/kg)			
Olass		[dBm]	Body			
DSS	RFID	23.799	1.456			
DSS/DTS	Bluetooth	1.62	N/A			
Simultaneous SAR pe	er KDB 690783 D0	1v01r03	1.540			
FCC Equipment Class	DSS - Spread S	pectrum Trans	smitter			
Date(s) of Tests	2013-11-21					
Antenna Type	Internal Type Antenna					
Functions	BT(2.4GHz)RFID is sup					

1.1 Guidance Applied

- IEEE 1528-2003
- FCC KDB Publication 447498 D01v05r01 (General SAR Guidance)
- FCC KDB Publication 865664 D01-D02 (SAR Measurements up to 6 GHz)

1.2 Device Overview

Band & Mode	Operating Modes	Tx Frequency
RFID	Data	902.75 ~ 927.25 MHz
Bluetooth	Data	2402 ~ 2480 MHz

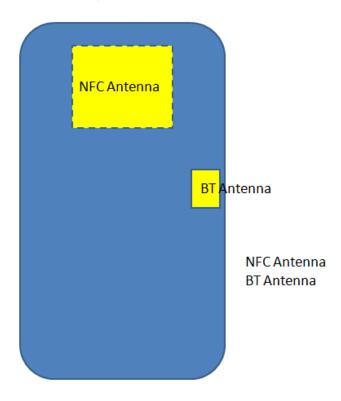
1.3 Nominal and Maximum Output Power Specifications

This device operates using the following maximum and nominal output power specifications. SAR values were scaled to the maximum allowed power to determine compliance per KDB Publication 447498 D01v05r01.

Ban	Modulated Average [dBm]	
DEID	Maximum	24.0
RFID	Nominal	22.5
Division at his A Miles a	Maximum	2.5
Bluetooth 1 Mbps	Nominal	1.0
Divistanth 2 Mhm	Maximum	-1.5
Bluetooth 2 Mbps	Nominal	- 3.0
Bluetooth 3 Mbps	Maximum	-1.5
	Nominal	- 3.0

1.4 DUT Antenna Locations

DUT Antenna Locations (Front Side View):



Note: Exact antenna dimensions and separation distances are shown in the Technical Descriptions in the FCC Filing.

1.5 SAR Test Exclusions Applied

(A) BT

Per FCC KDB 447498 D01v05r01, the SAR exclusion threshold for distances < 50 mm is defined by the following equation:

$$\frac{\textit{Max Power of Channel (mW)}}{\textit{Test Separation Dist (mm)}} * \sqrt{\textit{Frequency(GHz)}} \le 3.0$$

Based on the maximum conducted power of **Bluetooth** (rounded to the nearest mW) and the antenna to user separation distance, **Bluetooth SAR was not required**; $[(2.5/5) * \sqrt{2.480}] = 0.6 < 3.0$.

Per KDB Publication 447498 D01v05r01, the maximum power of the channel was rounded to the nearest mW before calculation.

(B) RFID

Per FCC KDB 447498 D01v05r01, the SAR exclusion threshold for 10g Extremity SAR for distances < 50 mm is defined by the following equation:

$$\frac{Max\ Power\ of\ Channel\ (mW)}{Test\ Separation\ Dist\ (mm)}*\sqrt{Frequency(GHz)} \leq 3.0$$

Based on the maximum conducted Power of **RFID** (rounded to the nearest mW) and the antenna to user separation distance, **RFID 10g Extremity SAR was required**; $[(251/5) * \sqrt{0.92725}] = 48.4 > 3.0$.

Per KDB Publication 447498 D01v05r01, the maximum power of the channel was rounded to the nearest mW before calculation.

1.6 Device Serial Numbers

Band & Mode	Body Serial Number
RFID	FCC #1

2. INTROCUCTION

The FCC and Industry Canada have adopted the guidelines for evaluating the environmental effects of radio frequency (RF) radiation in ET Docket 93-62 on Aug. 6, 1996 and Health Canada Safety Code 6 to protect the public and workers from the potential hazards of RF emissions due to FCC-regulated portable devices.

The FCC has adopted the guidelines for evaluating the environmental effects of radio frequency radiation in ET Docket 93-62 on Aug. 6, 1996 to protect the public and workers from the potential hazards of RF emissions due to FCC-regulated portable devices. The safety limits used for the environmental evaluation measurements are based on the criteria published by the American National Standards Institute (ANSI) for localized specific absorption rate (SAR) in IEEE/ANSI C95*.1-2005 Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz to 300 GHz. 1992 by the Institute of Electrical and Electronics Engineers, Inc., New York, New York 10017. The measurement procedure described in IEEE/ANSI C95.3-1992 Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic Fields - RF and Microwave is used for guidance in measuring SAR due to the RF radiation exposure from the Equipment Under Test (EUT). These criteria for SAR evaluation are similar to those recommended by the National Council on Radiation Protection and Measurements (NCRP) in Biological Effects and Exposure Criteria for Radio frequency Electromagnetic Fields," NCRP Report No. 86 NCRP, 1986, Bethesda, MD 20814. SAR is a measure of the rate of energy absorption due to exposure to an RF transmitting source. SAR values have been related to threshold levels for potential biological hazards.

SAR Definition

Specific Absorption Rate (SAR) is defined as the time derivative (rate) of the incremental energy (dU)absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dV) of a given density (ρ) It is also defined as the rate of RF energy absorption per unit mass at a point in an absorbing body (see Fig. 2.1)

$$SAR = \frac{d}{dt} \left(\frac{dU}{dm} \right) = \frac{d}{dt} \left(\frac{dU}{\rho dv} \right)$$

Fig. 2.1 SAR Mathematical Equation

SAR is expressed in units of Watts per Kilogram (W/kg).

$$SAR = \frac{\sigma \cdot E^2}{\rho}$$

where:

 σ = conductivity of the tissue-simulating material (S/m)

 ρ = mass density of the tissue-simulating material (kg/m³)

E = Total RMS electric field strength (V/m)

NOTE: The primary factors that control rate of energy absorption were found to be the wavelength of the incident field in relations to the dimensions and geometry of the irradiated organism, the orientation of the organism in relation to the polarity of field vectors, the presence of reflecting surfaces, and whether conductive contact is made by the organism with a ground plane.

3. DESCRIPTION OF TEST EQUIPMENT

3.1 SAR MEASUREMENT SETUP

Measurements are performed using the DASY4 automated dosimetric assessment system. The DASY4 is made by Schmid & Partner Engineering AG (SPEAG) in Zurich, Switzerland and consists of high precision robotics system (Staubli), robot controller, desktop computer, near-field probe, probe alignment sensor, and the generic twin phantom containing the brain equivalent material. The robot is a six-axis industrial robot performing precise movements to position the probe to the location (points) of maximum electromagnetic field (EMF) (see Fig. 3.1).

A cell controller system contains the power supply, robot controller teach pendant (Joystick), and a remote control used to drive the robot motors. The PC consists of the Intel Core i5-3570 3.40GHz desktop computer with Windows NT system and SAR Measurement Software DASY4, A/D interface card, monitor, mouse, and keyboard. The Staubli Robot is connected to the cell controller to allow software manipulation of the robot. A data acquisition electronic (DAE) circuit that performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. is connected to the Electro-optical coupler (EOC). The EOC performs the conversion from the optical into digital electric signal of the DAE and transfers data to the PC plug-in card.

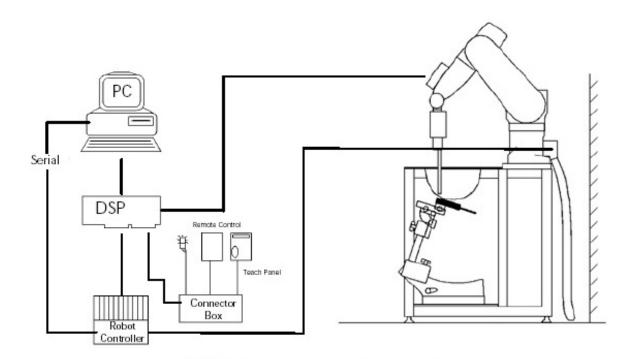


Figure 3.1 SAR Measurement System Setup

The DAE3 consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the PC-card is accomplished through an optical downlink for data and status information and an optical uplink for commands and clock lines. The mechanical probe mounting device includes two different sensor systems for frontal and sidewise probe contacts. They are also used for mechanical surface detection and probe collision detection. The robot uses its own controller with a built in VME-bus computer. The system is described in detail.

3.2 ET3DV6R Probe Specification

Calibration In air from 10 MHz to 3 GHz

In brain and muscle simulating tissue at Frequencies of 835 MHz, 900 MHz, 1750 MHz, 1900 MHz, 2450 MHz

Frequency 10 MHz to 3 GHz

Linearity $\pm 0.2 \text{ dB } (30 \text{ MHz to } 3 \text{ GHz})$

Optical Surface Detection ± 0.2 mm repeatability in air and clear liquids over

diffuse reflecting surfaces

Dynamic $5 \mu \text{W/g to} > 100 \text{ mW/g}$

Range Linearity: ±0.2dB

Dimensions Overall length: 330 mm

Tip length 16 mm

Body diameter 12 mm

Tip diameter 6.8 mm

Distance from probe tip to sensor center 2.7 mm

Application General dosimetric measurements up to 3 GHz

Compliance tests of mobile phones

Fast automatic scanning in arbitrary phantoms

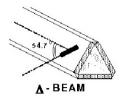


Figure 3.2 Triangular Probe Configurations



Figure 3.3 Frome Trick-Film recimique



The SAR measurements were conducted with the dosimetric probe ET3DV6R, designed in the classical triangular configuration(see Fig. 3.2) and optimized for dosimetric evaluation. The probe is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multitier line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY4 software reads the reflection during a software approach and looks for the maximum using a 2nd order fitting. The approach is stopped at reaching the maximum.

3.3 Probe Calibration Process

3.3.1 E-Probe Calibration

Dosimetric Assessment Procedure

Each probe is calibrated according to a dosimetric assessment procedure with accuracy better than +/- 10%. The spherical isotropy was evaluated with the procedure and found to be better than +/-0.25dB. The sensitivity parameters (NormX, NormY, NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe is tested.

Free Space Assessment

The free space E-field from amplified probe outputs is determined in a test chamber. This is performed in a TEM cell for frequencies below 1 GHz, and in a waveguide above 1GHz for free space. For the free space calibration, the probe is placed in the volumetric center of the cavity at the proper orientation with the field. The probe is then rotated 360 degrees.

Temperature Assessment *

E-field temperature correlation calibration is performed in a flat phantom filled with the appropriate simulated brain tissue. The measured free space E-field in the medium, correlates to temperature rise in a dielectric medium. For temperature correlation calibration a RF transparent the remits or based temperature probe is used in conjunction with the E-field probe.

$$SAR = C \frac{\Delta T}{\Delta t}$$

 $SAR = \frac{\left|E\right|^2 \cdot \sigma}{\rho}$

where: where:

 Δt = exposure time (30 seconds),

 σ = simulated tissue conductivity,

C = heat capacity of tissue (brain or muscle),

 ρ = Tissue density (1.25 g/cm³ for brain tissue)

 ΔT = temperature increase due to RF exposure.

SAR is proportional to $\Delta T/\Delta t$, the initial rate of tissue heating, before thermal diffusion takes place. Now it's possible to quantify the electric field in the simulated tissue by equating the thermally derived SAR to the E- field;

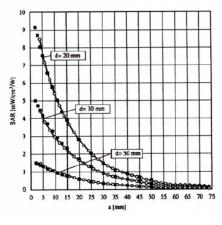


Figure 3.4 E-Field and Temperature Measurements at 900MHz

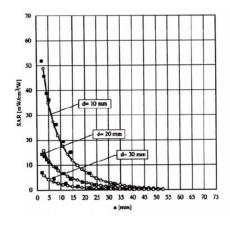


Figure 3.5 E-Field and Temperature Measurements at 1800MHz

3.4 Data Extrapolation

The DASY4 software automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given like below;

with
$$V_i$$
 = compensated signal of channel i (i=x,y,z)
 U_i = input signal of channel i (i=x,y,z)
 U_i = input signal of channel i (i=x,y,z)
 U_i = input signal of channel i (i=x,y,z)
 U_i = crest factor of exciting field (DASY parameter)
 U_i = compensated signal of channel i (i=x,y,z)
 U_i = input signal of channel i (i=x,y,z)

From the compensated input signals the primary field data for each channel can be evaluated:

E-field probes: with
$$V_i$$
 = compensated signal of channel i (i = x,y,z)
Norm_i = sensor sensitivity of channel i (i = x,y,z)
 $\mu V/(V/m)^2$ for E-field probes
ConvF = sensitivity of enhancement in solution
 E_i = electric field strength of channel i in V/m

The RSS value of the field components gives the total field strength (Hermetian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$
 with SAR = local specific absorption rate in W/g = total field strength in V/m = conductivity in [mho/m] or [Siemens/m] ρ = equivalent tissue density in g/cm³

The power flow density is calculated assuming the excitation field to be a free space field.

$$P_{pue} = \frac{E_{tot}^2}{3770}$$
 with $P_{pwe} = \text{equivalent power density of a plane wave in W/cm}^2$ = total electric field strength in V/m

3.5 SAM Twin PHANTOM

The SAM Twin Phantom V4.0 is constructed of a fiberglass shell integrated in a wooden table. The shape of the shell is based on data from an anatomical study designed to determine the maximum exposure in at least 90% of all users. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents the evaporation of the liquid.

Reference markings on the Phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points in the robot. (see Fig. 3.6)



Figure 3.6 SAM Twin Phantom

SAM Twin Phantom Specification:

Construction

The shell corresponds to the specifications of the Specific Anthropomorphic Mannequin (SAM) phantom defined in IEEE 1528 and IEC 62209-1. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents evaporation of the liquid. Reference markings on the phantom allow the complete setup of all predefined phantom positions and measurement grids by teaching

three points with the robot.

Twin SAM V5.0 has the same shell geometry and is manufactured from the same material as

Twin SAM V4.0, but has reinforced top structure.

Shell Thickness $2 \pm 0.2 \text{ mm}$

Filling Volume Approx. 25 liters
Dimensions Length: 1000 mm

Width: 500 mm

Height: adjustable feet

Specific Anthropomorphic Mannequin (SAM) Specifications:

The phantom for handset SAR assessment testing is a low-loss dielectric shell, with shape and dimensions derived from the anthropometric data of the 90th percentile adult male head dimensions as tabulated by the US Army. The SAM Twin Phantom shell is bisected alongthemid-sagittal plane into right and left halves (see Fig. 3.7). The perimeter sidewalls of each phantom halves are extended to allow filling with liquid to a depth that is sufficient to minimized reflections from the upper surface. The liquid depth is maintained at a minimum depth of 15cm to minimize reflections from the upper surface.

Figure 3.7 Sam Twin Phantom shell

3.6 Device Holder for Transmitters

In combination with the Twin SAM Phantom V4.0/V4.0c or ELI4, the Mounting Device enables the rotation of the mounted transmitter device in spherical coordinates. Rotation point is the ear opening point. Transmitter devices can be easily and accurately positioned according to IEC, IEEE, FCC or other specifications. The device holder can be locked for positioning at different phantom sections (left head, right head, flat).

Note: A simulating human hand is not used due to the complex anatomical and geometrical structure of the hand that may produce infinite number of configurations. To produce the worst-case condition (the hand absorbs antenna output power), the hand is omitted during the tests.



Figure 3.8 Mounting Device

3.7 Brain & Muscle Simulation Mixture Characterization

The brain and muscle mixtures consist of a viscous gel using hydrox-ethylcellulose (HEC) gelling agent and saline solution (see Table 3.1). Preservation with a bactericide is added and visual inspection is made to make sure air bubbles are not trapped during the mixing process. The mixture is calibrated to obtain proper dielectric constant (permittivity) and conductivity of the desired tissue. The mixture characterizations used for the brain and muscle tissue simulating liquids are according to the data by C. Gabriel and G. Harts grove.



Figure 3.9 Simulated Tissue

Table 3.1 Composition of the Tissue Equivalent Matter

Ingredients	Frequency (MHz)									
(% by weight)	835		900		1900		2450		5200 ~ 5800	
Tissue Type	Head	Body	Head	Body	Head	Body	Head	Body	Head	Body
Water	40.19	50.75	41.45	52.50	55.24	70.23	71.88	73.40	65.52	80.00
Salt (NaCl)	1.480	0.940	1.450	1.400	0.310	0.290	0.160	0.060	-	-
Sugar	57.90	48.21	56.00	45.00	-	-	-	-	-	-
HEC	0.250	-	1.000	1.000	-	-	-	-	-	-
Bactericide	0.180	0.100	0.100	0.100	-	-	-	-	-	-
Triton X-100	-	-	-	-	-	-	19.97	-	17.24	-
DGBE	-	-	-	-	44.45	29.48	7.990	26.54	-	-
Diethylene glycol hexyl ether	-	-	-	-	-	-	-	-	17.24	-
Polysorbate (Tween) 80	-	-	-	-	-	-	-	-	-	20.00
Target for Dielectric Constant	41.5	55.2	41.5	55.0	40.0	53.3	39.2	52.7	-	-
Target for Conductivity (S/m)	0.90	0.97	0.97	1.05	1.40	1.52	1.80	1.95	-	-

Salt: 99 % Pure Sodium Chloride Sugar: 98 % Pure Sucrose

Water: De-ionized, 16M resistivity HEC: Hydroxyethyl Cellulose

DGBE: 99 % Di(ethylene glycol) butyl ether,[2-(2-butoxyethoxy) ethanol]

Triton X-100(ultra pure): Polyethylene glycol mono[4-(1,1,3,3-tetramethylbutyl)phenyl] ether

3.8 SAR TEST EQUIPMENT

Table 3.2 Test Equipment Calibration

	Table 3.2 Test Equipment Calibration								
	Туре	Manufacturer	Model	Cal.Date	Next.Cal.Date	S/N			
	SEMITEC Engineering	SEMITEC	N/A	N/A	N/A	Shield Room			
\boxtimes	Robot	SCHMID	RX90BL	N/A	N/A	F02/5Q86A1/A/01			
\boxtimes	Robot Controller	SCHMID	CS7MB	N/A	N/A	F01/5N19A1/C/01			
	Joystick	SCHMID	N/A	N/A	N/A	D22134006			
	Intel Core i5-3570 3,40 GHz Windows XP Professional	N/A	N/A	N/A	N/A	N/A			
\boxtimes	Probe Alignment Unit LB	N/A	N/A	N/A	N/A	240			
\boxtimes	Mounting Device	SCHMID	SD000H01HA	N/A	N/A	N/A			
	Twin SAM Phantom	SCHMID	TP1220	N/A	N/A	N/A			
\boxtimes	Twin SAM Phantom	SCHMID	TP1221	N/A	N/A	N/A			
	Head/Body Equivalent Matter(835MHz)	N/A	N/A	2013-01-01	2014-01-01	N/A			
	Head/Body Equivalent Matter(900MHz)	N/A	N/A	2013-01-01	2014-01-01	N/A			
	Head/Body Equivalent Matter(1900MHz)	N/A	N/A	2013-01-01	2014-01-01	N/A			
	Head/Body Equivalent Matter(2450MHz)	N/A	N/A	2013-01-01	2014-01-01	N/A			
\boxtimes	Data Acquisition Electronics	SCHMID	DAE3V1	2013-07-30	2014-07-30	520			
\boxtimes	Dosimetric E-Field Probe	SCHMID	ET3DV6R	2013-07-29	2014-07-29	1703			
	Dummy Probe	N/A	N/A	N/A	N/A	N/A			
	835MHz SAR Dipole	SCHMID	D835V2	2013-09-05	2015-09-05	4d159			
\boxtimes	900MHz SAR Dipole	SCHMID	D900V2	2012-12-13	2014-12-13	1d146			
	1900MHz SAR Dipole	SCHMID	D1900V2	2013-09-05	2015-09-05	5d176			
	2450MHz SAR Dipole	SCHMID	D2450V2	2013-09-10	2015-09-10	920			
	5000MHz SAR Dipole	SCHMID	D5GHzV2	2013-03-15	2015-03-15	1103			
\boxtimes	Network Analyzer	Agilent	E5071C	2013-10-21	2014-10-21	MY46106970			
\boxtimes	Signal Generator	Rohde Schwarz	SMR20	2013-02-28	2014-02-28	101251			
\boxtimes	Amplifier	EMPOWER	BBS3Q7ELU	2013-09-12	2014-09-12	1020			
	High Power RF Amplifier	EMPOWER	BBS3Q8CCJ	2013-10-22	2014-10-22	1005			
\boxtimes	Power Meter	HP	EPM-442A	2013-02-28	2014-02-28	GB37170267			
\boxtimes	Power Meter	Anritsu	ML2495A	2013-03-06	2014-03-06	1306007			
\boxtimes	Wide Bandwidth Power Sensor	Anritsu	MA2490A	2013-03-06	2014-03-06	1249001			
\boxtimes	Power Sensor	HP	8481A	2013-02-28	2014-02-28	3318A96566			
\boxtimes	Power Sensor	HP	8481A	2013-02-14	2014-02-14	3318A96030			
\boxtimes	Dual Directional Coupler	Agilent	778D-012	2013-01-08	2014-01-08	50228			
	Directional Coupler	HP	773D	2013-06-27	2014-06-27	2389A00640			
\boxtimes	Low Pass Filter 1,5GHz	Micro LAB	LA-15N	2013-01-08	2014-01-08	N/A			
	Low Pass Filter 3,0GHz	Micro LAB	LA-30N	2013-09-12	2014-09-12	N/A			
	Low Pass Filter 6,0GHz	Micro LAB	LA-60N	2013-03-12	2014-03-12	03942			
\boxtimes	Attenuators(3 dB)	Agilent	8491B	2013-06-27	2014-06-27	MY39260700			
\boxtimes	Attenuators(10 dB)	WEINSCHEL	23-10-34	2013-01-08	2014-01-08	BP4387			
	Step Attenuator	HP	8494A	2013-09-12	2014-09-12	3308A33341			
\boxtimes	Dielectric Probe kit	SCHMID	DAK-3.5	2012-12-11	2013-12-11	1092			
	8960 Series 10 Wireless Comms. Test Set	Agilent	E5515C	2013-02-28	2014-02-28	GB43461134			

NOTE: The E-field probe was calibrated by SPEAG, by temperature measurement procedure. Dipole Verification measurement is performed by Digital EMC before each test. The brain and muscle simulating material are calibrated by Digital EMC using the dielectric probe system and network analyzer to determine the conductivity and permittivity (dielectric constant) of the brain-equivalent material.

4. TEST SYSTEM SPECIFICATIONS

Automated TEST SYSTEM SPECIFICATIONS:

Positioner

Robot Stäubli Unimation Corp. Robot Model: RX90L

Repeatability 0.02 mm

No. of axis 6

Data Acquisition Electronic (DAE) System

Cell Controller

Processor Intel Core i5-3570

Clock Speed 3.40 GHz

Operating System Windows XP Professional

Data Card DASY4 PC-Board

Data Converter

Features Signal, multiplexer, A/D converter. & control logic

Software DASY4

Connecting Lines Optical downlink for data and status info

Optical uplink for commands and clock

PC Interface Card

Function 24 bit (64 MHz) DSP for real time processing

Link to DAE 3

16 bit A/D converter for surface detection system

serial link to robot

direct emergency stop output for robot

E-Field Probes

Model ET3DV6R S/N: 1703

Construction Triangular core fiber optic detection system

Frequency 10 MHz to 3 GHz

Linearity \pm 0.2 dB (30 MHz to 3 GHz)

Phantom

Phantom SAM Twin Phantom (V4.0)

Shell MaterialCompositeThickness $2.0 \pm 0.2 \text{ mm}$



Figure 2.2 DASY4 Test System

5. SAR MEASUREMENT PROCEDURE

5.1 Measurement Procedure

The evaluation was performed using the following procedure:

- The SAR distribution at the exposed side of the head or body was measured at a distance no greater than 5.0 mm from the inner surface of the shell. The area covered the entire dimension of the device-head and body interface and the horizontal grid resolution was determined per FCC KDB Publication 865664D01v01 (See Table 5.1).
- 2. The point SAR measurement was taken at the maximum SAR region determined from Step 1 to enable the monitoring of SAR fluctuations / drifts during the 1g/10g cube evaluation. SAR at this fixed point was measured and used as a reference value.

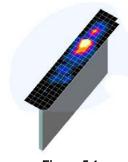


Figure 5.1 Sample SAR Area Scan

- 3. Based on the area scan data, the peak of the region with maximum SAR was determined by spline interpolation. Around this point, a volume was assessed according to the measurement resolution and volume size requirements of FCC KDB Publication 865664 D01v01 (See Table 5.1). On the basis of this data set, the spatial peak SAR value was evaluated with the following procedure (see references or the DASY manual online for more details):
 - a. The data was extrapolated to the surface of the outer-shell of the phantom. The combined distance extrapolated was the combined distance from the center of the dipoles 2.7mmaway from the tip of the probe housing plus the 1.2 mm distance between the surface and the lowest measuring point. The extrapolation was based on a least-squares algorithm. A polynomial of the fourth order was calculated through the points in the z-axis (normal to the phantom shell).
 - b. After the maximum interpolated values were calculated between the points in the cube, the SAR was averaged over the spatial volume (1g or 10g) using a 3D-Spline interpolation algorithm. The 3D-spline is composed of three one-dimensional splines with the "Not a knot" condition (in x, y, and z directions). The volume was then integrated with the trapezoidal algorithm. One thousand points (10 x 10 x 10) were obtained through interpolation, in order to calculate the averaged SAR.
 - c. All neighboring volumes were evaluated until no neighboring volume with a higher average value was found.
- 4. The SAR reference value, at the same location as step 2, was re-measured after the zoom scan was complete to calculate the SAR drift. If the drift deviated by more than 5%, the SAR test and drift measurements were repeated.

Maximum Area Scan		Maximum Zoom Scan	Max	Minimum Zoom Scan		
Frequency	Resolution (mm) (Δx _{area} , Δy _{area})	Resolution (mm) (Δx _{zoom} , Δy _{zoom})	Uniform Grid Grad		raded Grid	Volume (mm) (x,y,z)
	, died- ydied-	, 200111	Δz _{zoom} (n)	Δz _{zoom} (1)*	Δz _{zoom} (n>1)*	
≤2GHz	≤ 15	≤8	≤5	≤4	≤1.5*∆z _{zoom} (n-1)	≥ 30
2-3 GHz	≤ 12	≤5	≤5	≤4	$\leq 1.5*\Delta z_{zoom}(n-1)$	≥ 30
3-4 GHz	≤ 12	≤5	≤4	≤3	$\leq 1.5*\Delta z_{zoom}(n-1)$	≥ 28
4-5 GHz	≤ 10	≤4	≤3	≤ 2.5	$\leq 1.5*\Delta z_{zoom}(n-1)$	≥ 25
5-6 GHz	≤ 10	≤4	≤2	≤2	$\leq 1.5*\Delta z_{zoom}(n-1)$	≥ 22

Table 5.1 Area and Zoom Scan Resolutions per FCC KDB Publication 865664 D01v01

6. TEST CONFIGURATION POSITIONS

6.1 Device Holder

The device holder is made out of low-loss POM material having the following dielectric parameters: relative permittivity ε = 3 and loss tangent δ = 0.02.

6.2 Body Configurations

In all cases SAR measurements are performed to investigate the worst-case positioning. Worst-case positioning is then documented and used to perform Body SAR testing.

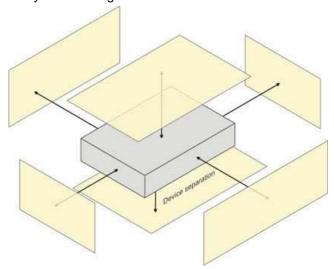


Figure 6.7 Sample Body Diagram

6.3 Extremity Exposure Configurations

Devices that are designed or intended for use on extremities or mainly operated in extremity only exposure conditions; i.e., hands, wrists, feet and ankles, may require extremity SAR evaluation. When the device also operates in close proximity to the user's body, SAR compliance for the body is also required. The 1-g body and 10-g extremity SAR Exclusion Thresholds found in KDB Publication 447498 D01v05r01 should be applied to determine SAR test requirements.

Because this device used at the body, extremity SAR is not required.

7. RF EXPOSURE LIMITS

Uncontrolled Environment:

UNCONTROLLED ENVIRONMENTS are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure. The general population/uncontrolled exposure limits are applicable to situations in which the general public may be exposed or in which persons who are exposed as a consequence of their employment may not be made fully aware of the potential for exposure or cannot exercise control over their exposure. Members of the general public would come under this category when exposure is not employment-related; for example, in the case of a wireless transmitter that exposes persons in its vicinity.

Controlled Environment:

CONTROLLED ENVIRONMENTS are defined as locations where there is exposure that may be incurred by persons who are aware of the potential for exposure, (i.e. as a result of employment or occupation). In general, occupational/controlled exposure limits are employment, who have been made fully aware of the potential for exposure and can exercise control over their exposure. This exposure category is also applicable when the exposure is of a transient nature due to incidental passage through a location where the exposure levels may be higher than the general population/uncontrolled limits, but the exposed person is fully aware of the potential for exposure and can exercise control over his or her exposure by leaving the area or by some other appropriate means.

Table 7.1.SAR Human Exposure Specified in ANSI/IEEE C95.1-2005

	HUMAN EXPOSURE LIMITS					
	General Public Exposure (W/kg) or (mW/g)	Occupational Exposure (W/kg) or (mW/g)				
SPATIAL PEAK SAR * (Brain)	1.60	8.00				
SPATIAL AVERAGE SAR ** (Whole Body)	0.08	0.40				
SPATIAL PEAK SAR *** (Hands / Feet / Ankle / Wrist)	4.00	20.0				

- 1. The Spatial Peak value of the SAR averaged over any 1 gram of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.
- 2. The Spatial Average value of the SAR averaged over the whole body.
- 3. The Spatial Peak value of the SAR averaged over any 10 grams of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.

Uncontrolled Environments are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure.

Controlled Environments are defined as locations where there is exposure that may be incurred by persons who are aware of the potential for exposure, (i.e.as a result of employment or occupation).

8. FCC MEASUREMENT PROCEDURES

Power measurements were performed using a base station simulator under digital average power.

8.1 Measured and Reported SAR

Per FCC KDB Publication 447498 D01v05r01, When SAR is not measured at the maximum power level allowed for production units, the results must be scaled to the maximum tune-up tolerance limit according to the power applied to the individual channels tested to determine compliance. For simultaneous transmission, the measured aggregate SAR must be scaled according to the sum of the differences between the maximum tune-up tolerance and actual power used to test each transmitter. When SAR is measured at or scaled to the maximum tune-up tolerance limit, the results are referred to as reported SAR. The highest reported SAR results are identified on the grant of equipment authorization according to procedures in KDB 690783 D01v01r02.

8.2 Procedures Used to Establish RF Signal for SAR

The device was placed in a RF shielded chamber. Establishing connections in this manner ensure a consistent means for testing SAR and are recommended for evaluating SAR. Devices under test were evaluated prior to testing, with a fully charged battery and were configured to operate at maximum output power. In order to verify that the device was tested throughout the SAR test at maximum output power, the SAR measurement system measures a "point SAR" at an arbitrary reference point at the start and end of the 1 gram SAR evaluation, to assess for any power drifts during the evaluation. If the power drift deviated by more than 5%, the SAR test and drift measurements were repeated.

This device's duty cycle had been set by manufacturer below table when it is sold in the market.

- On time: 100ms(below)

- On time + OFF time: 750ms(below)

Channel	Frequency(MHz)	On time [ms]	On+Off time [ms]	Duty
1	902.75	97.37	737	0.133
25	915.25	98.44	736.8	0.134
49	927.25	98.22	737	0.134

9. RF CONDUCTED POWERS

9.1 RFID Conducted Powers

Band	Frequency (MHz)	Channel	RFID Conducted Power (dBm)
	902.75	1	23.561
RFID	915.25	25	23.799
	927.25	49	23.781

Table 9.1 RFID Average RF Power

9.2 Bluetooth Conducted Powers

Channel	Frequency	Output Power (1 Mbps)		Output (2 M	Power bps)	Output Power (3 Mbps)		
	(MHz)	(dBm)	(mW)	(dBm)	(mW)	(dBm)	(mW)	
Low	2402	0.79	1.199	-3.52	0.445	-3.51	0.446	
Mid	2441	1.34	1.361	-3.01	0.500	-2.96	0.506	
High	2480	1.62	1.452	-2.78	0.527	-2.76	0.530	

Table 9.2 Bluetooth Average RF Power



Figure 9.1 Power Measurement Setup

10. SYSTEM VERIFICATION

10.1 Tissue Verification

	MEASURED TISSUE PARAMETERS												
Date(s)	Tissue Type	Ambient Temp.[°C]	Liquid Temp.[°C]	Measured Frequency [MHz]	Target Dielectric Constant, εr	Target Conductivity, σ (S/m)	Measured Dielectric Constant, Er	Measured Conductivity, σ (S/m)	Er Deviation [%]	σ Deviation [%]			
		22.1	22.6	900.00	55.000	1.050	54.8	1.060	- 0.36	0.95			
Nov. 21. 2013	900			902.75	55.000	1.052	54.8	1.060	- 0.36	0.76			
NOV. 21. 2013	Body			915.25	55.000	1.060	54.6	1.080	- 0.73	1.89			
				927.25	54.980	1.065	54.5	1.090	- 0.87	2.35			

Tissue Verification Note:

Note: The above measured tissue parameters were used in the DASY software. The DASY software was used to perform interpolation to determine the dielectric parameters at the SAR test device frequencies (per IEEE 1528 6.6.1.2). The tissue parameters listed in the SAR test plots may slightly differ from the table above due to significant digit rounding in the software.

Measurement Procedure for Tissue verification:

- 1) The network analyzer and probe system was configured and calibrated.
- The probe was immersed in the sample which was placed in a nonmetallic container.
 Trapped air bubbles beneath the flange were minimized by placing the probe at a slight angle.
- The complex admittance with respect to the probe aperture was measured
- The complex relative permittivity , for example from the below equation (Pournaropoulos and Micra):

$$Y = \frac{j2\omega\varepsilon_{r}\varepsilon_{0}}{\left[\ln(b/a)\right]^{2}} \int_{a}^{b} \int_{a}^{b} \int_{0}^{\pi} \cos\phi' \frac{\exp\left[-j\omega r(\mu_{0}\varepsilon_{r}'\varepsilon_{0})^{1/2}\right]}{r} d\phi' d\rho' d\rho$$

where Y is the admittance of the probe in contact with the sample, the primed and unprimed coordinates refer to source and observation points, respectively, $r^2 = \rho^2 + \rho'^2 - 2\rho\rho'\cos\phi'$, ω is the angular frequency, and $j = \sqrt{-1}$.

10.2 Test System Verification

Prior to assessment, the system is verified to the± 10 % of the specifications at 900 MHz by using the SAR Dipole kit(s). (Graphic Plots Attached)

Table 10.1 System Verification Results

	SYSTEM DIPOLE VERIFICATION TARGET & MEASURED												
SAR System #	Freq. [MHz]	SAR Dipole kits	Date(s)	Liquid	Ambient Temp.[°C]	Liquid Temp.[°C]	Probe S/N	Input Power (mW)	1 W Target SAR _{1g} (W/kg)	Measured SAR _{1g} (W/kg)	1 W Normalized SAR _{1g} (W/kg)	Deviation [%]	
D	900	D900V2, SN: 1d146	Nov. 21. 2013	Body	22.1	22.6	1703	250	10.6	2.76	11.04	4.15	

Note1: System Verification was measured with input 250 mW and normalized to 1W.

Note2: To confirm the proper SAR liquid depth, the z-axis plots from the system verifications were included since the system verifications were performed using the same liquid, probe and DAE as the SAR tests in the same time period.

Note3: Full system validation status and results can be found in Attachment 3.

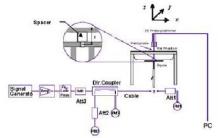




Figure 10.1 Dipole Verification Test Setup

11. SAR TEST RESULTS

11.1 Standalone Body SAR Results

Table 11.1 RFID Body SAR

	MEASUREMENT RESULTS												
FREQUI	ENCY	Mode/	Service	Maximum Allowed	Conducted Power	Drift Power	Spacing	Device Serial	Data Rate	Duty	1g SAR	Scaling	1g Scaled
MHz	Ch	Band		Power [dBm]	[dBm]	[dB]	[Side]	Number	[Mbps]	Cycle	(W/kg)	Factor	SAR (W/kg)
915.25	25	RFID	RFID	24.0	23.799	-0.173	0 mm [Top]	FCC #1	1	1:7.46	0.619	1.047	0.648
915.25	25	RFID	RFID	24.0	23.799	-0.094	0 mm [Bottom]	FCC #1	1	1:7.46	0.168	1.047	0.176
915.25	25	RFID	RFID	24.0	23.799	0.069	0 mm [Front]	FCC #1	1	1:7.46	0.327	1.047	0.342
902.75	1	RFID	RFID	24.0	23.561	0.072	0 mm [Rear]	FCC #1	1	1:7.52	1.160	1.106	1.283
915.25	25	RFID	RFID	24.0	23.799	0.064	0 mm [Rear]	FCC #1	1	1:7.46	1.390	1.047	1.456
927.25	49	RFID	RFID	24.0	23.781	0.185	0 mm [Rear]	FCC #1	1	1:7.46	1.190	1.052	1.252
915.25	25	RFID	RFID	24.0	23.799	-0.031	0 mm [Right]	FCC #1	1	1:7.46	0.601	1.047	0.629
915.25	25	RFID	RFID	24.0	23.799	0.050	0 mm [Left]	FCC #1	1	1:7.46	0.726	1.047	0.760
915.25	25	RFID	RFID	24.0	23.799	0.142	0 mm [Rear]	FCC #1	1	1:7.46	1.370	1.047	1.435
	ANSI / IEEE C95.1-2005— SAFETY LIMIT Spatial Peak Uncontrolled Exposure/General Population Exposure							Body 1.6 W/kg (mW/g) averaged over 1 gram					

Note: Blue entries represent repeatability measurements.

11.2 SAR Test Notes

General Notes:

- 1. The test data reported are the worst-case SAR values according to test procedures specified in IEEE 1528-2003, FCC KDB Publication 865664 D01v01r02 and FCC KDB Publication447498 D01v05r01.
- 2. Batteries are fully charged at the beginning of the SAR measurements. A standard battery was used for all SAR measurements.
- 3. Liquid tissue depth was at least 15.0 cm for all frequencies.
- 4. The manufacturer has confirmed that the device(s) tested have the same physical, mechanical and thermal characteristics and are within operational tolerances expected for production units
- 5. SAR results were scaled to the maximum allowed power to demonstrate compliance per FCC KDB Publication 447498 D01v05r01.
- 6. Device was tested using a fixed spacing for body testing. A separation distance of 0 mm was considered because the manufacturer has determined that there will be body available in the marketplace for users to support this separation distance.
- 7. Per FCC KDB 865664 D01v01, variability SAR tests were performed when the measured SAR results for a frequency band were greater than 0.8 W/kg. Repeated SAR measurements are highlighted in the tables above for clarity. Please see Section 14 for variability analysis.
- 8. This device does not support Voice, Hotspot and VOIP operation.

RFID Notes:

- 1. Only when the button is pressed, RFID operation works.
- 2. RFID operation does not support voice call and data transmission.

12. FCC MULTI-TX AND ANTENNA SAR CONSIDERATIONS

12.1 Introduction

The following procedures adopted from FCC KDB Publication 447498 D01v05r01 are applicable to handsets with built-in unlicensed transmitters such as 802.11a/b/g/n/ac and Bluetooth devices which may simultaneously transmit with the licensed transmitter.

12.2 Simultaneous Transmission Procedures

This device contains transmitters that may operate simultaneously. Therefore simultaneous transmission analysis is required. Per FCC KDB 447498 D01v05r01 IV.C.1.iii, simultaneous transmission SAR test exclusion may be applied when the sum of the 1-g SAR for all the simultaneous transmitting antennas in a specific a physical test configuration is \leq 1.6 W/kg. and when the sum of the 10g SAR for all simultaneous transmitting antennas in a specific physical test configuration is \leq 4.0 W/kg. When standalone SAR is not required to be measured, per FCC KDB 447498 D01v05r01 4.3.2 2), the following equation must be used to estimate the standalone 1g and 10g SAR for simultaneous transmission assessment involving that transmitter.

Estimated 1g SAR =
$$\frac{\sqrt{f(GHz)}}{7.5} * \frac{(Max Power of channel, mW)}{Min. Separation Distance, mm}$$

Table 12.1 Estimated SAR

Mode	Frequency	Allo	mum wed wer	Separation Distance (Body)	Estimated 1g SAR (Body)	
	[MHz]	[dBm]	[mW]	[mm]	[W/kg]	
Bluetooth	2480	2.5	2	5	0.084	

Note: Held-to ear configurations are not applicable to Bluetooth operations and therefore were not considered for simultaneous transmission. Per KDB Publication 447498 D01v05r01, the maximum power of the channel was rounded to the nearest mW before calculation.

Note: Per FCC KDB Publication 447498 D01v05r01, when the test separation distance is < 5 mm (Touching), a distance of 5 mm is applied to determine estimated SAR.

12.3 Simultaneous Transmission Capabilities

According to FCC KDB Publication 447498 D01v05r01, transmitters are considered to be transmitting simultaneously when there is overlapping transmission, with the exception of transmissions during network hand-offs with maximum hand-off duration less than 30 seconds. Possible transmission paths for the DUT are shown in Figure 13.1 and are color-coded to indicate communication modes which share the same path. Modes which share the same transmission path cannot transmit simultaneously with one another.



Figure 12.1 Simultaneous Transmission Paths

This device contains multiple transmitters that may operate simultaneously, and therefore requires a simultaneous transmission analysis according to FCC KDB Publication 447498 D01v05r01 3) procedures.

Table 12.2 Simultaneous Transmission Scenarios

Ref.	Simultaneous Transmit Configurations	Body
1	Bluetooth + RFID	Yes
	: This device not supports VoIP. RFID is not supported Voice call.	

12.4 Body Simultaneous Transmission Analysis

Table 12.3 Simultaneous Transmission Scenario with Bluetooth (Body at 0 mm)

Simult TX	Configuration	RFID 1g SAR (W/kg)	Bluetooth 10g SAR (W/kg)	ΣSAR (W/kg)
	Тор	0.648	0.084	0.732
	Bottom	0.176	0.084	0.260
Body	Front	0.342	0.084	0.426
SAR	Rear	1.456	0.084	1.540
	Right	0.629	0.084	0.713
	Left	0.760	0.084	0.844

Note: Bluetooth SAR was not required to be measured per FCC KDB 447498. Estimated SAR results were used in the above table to determine simultaneous transmission SAR test exclusion.

12.5 Simultaneous Transmission Conclusion

The above numerical summed SAR results for all the worst-case simultaneous transmission conditions were below the SAR limit. Therefore, the above analysis is sufficient to determine that simultaneous transmission cases will not exceed the SAR limit and therefore no measured volumetric simultaneous SAR summation is required per FCC KDB Publication 447498 D01v05r01.

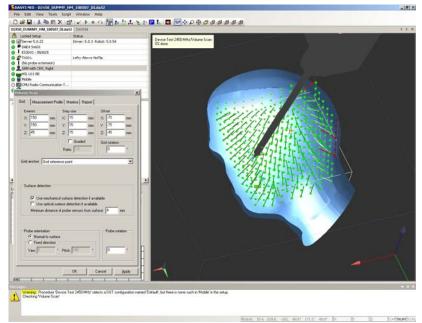
Description of Volume Scan:

In order to determine the EM field distribution in a three-dimensional spatial extension, volume scans are required. In free space, these assessments can help to gain more information on the performance of the DUT(e.g., to determine the degree of symmetry of the filed radiated from a horn antenna).

For dosimetric application, it is necessary to assess the peak spatial SAR value averaged over a volume. For this purpose, fine resolution volume scans need to be performed at the peak SAR location(s) determined during the Area Scan. In DASY4 software these scans are called Zoom Scan jobs. The default Zoom Scan measures 7 x 7 x 7 points with a step size of 5 mm. Faster evaluations can be achieved with a reduced number of measurement points. For example, a Zoom Scan with a grid step size in x- and y-directions of 7.5 mm (5 x 5 x 7cube configuration) reduces the measurement time to almost half with only 1-2% difference in SAR reading compared to the fine-resolution 7 x 7 x 7 scan.

For SAR evaluations with larger spatial extensions (e.g., within a complete phantom head section)a Volume Scan job should be used.

The Volume Scan job is compatible with DASY4 SAR, PRO and NEO system levels. Volume Scans are used to assess peak SAR and averaged SAR measurement in largely extended 3-dimensional volumes within any phantom. This measurement does not need any previous area scan. The grid can be anchored to a user specific point or to the current probe location With an Administrator access mode, the grid can be optionally graded in Z-direction, whereby the smallest grid step and the grading ratio can be defined. Chosen grading ratio is automatically adjusted so that the desired extent in Z-direction is fully covered.



Under the Report page, the quantity to be evaluated for an instant report may be selected. This quantity can be: field magnitude, SAR, interpolated SAR or averaged SAR.

SAR Assessment:

Alternative1

- Evaluation Method
 - Maximum summed SAR Value
- Description
 - Easiest and most conservative method to determine the upper limit of multi-band SAR
 - Example
 - F1's SAR Value is 0.9
 - F2's SAR Value is 1.3
 - Multi-band SAR Value is 0.9 + 1.3 = 2.2

Alternative2

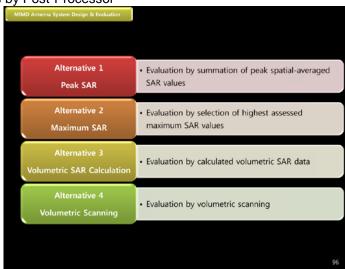
- Evaluation Method
 - Selection of highest assessed maximum SAR Value
- Description
 - Accurate estimate of the multi-band SAR
 - Example
 - F1's SAR Value is 0.9
 - F2's SAR Value is 1.3
 - Multi-band SAR Value is 1.3

Alternative3

- Evaluation Method
 - Combining existing Area and Zoom Scan results by Post-Processor
- Description
 - Rapid way of obtaining the multi-band SAR. It is always applicable.
 - Example
 - F1's SAR Value is 0.9
 - F2's SAR Value is 1.3
 - Combining results by Post-Processor

Alternative4

- Evaluation Method
 - Combining existing Area and Zoom Scan results by Post-Processor
- Description
 - The most accurate way of assessing the multi-band SAR and always applicable.
 - Example
 - F1's SAR Value is 0.9
 - F2's SAR Value is 1.3
 - Combining results by Post-Processor



13. SAR MEASUREMENT VARIABILITY

13.1 Measurement Variability

Per FCC KDB Publication 865664 D01v01r01, SAR measurement variability was assessed for each frequency band, which was determined by the SAR probe calibration point and tissue-equivalent medium used for the device measurements. When both head and body tissue-equivalent media were required for SAR measurements in a frequency band, the variability measurement procedures were applied to the tissue medium with the highest measured SAR, using the highest measured SAR configuration for that tissue-equivalent medium. These additional measurements were repeated after the completion of all measurements requiring the same head or body tissue-equivalent medium in a frequency band. The test device was returned to ambient conditions (normal room temperature) with the battery fully charged before it was re-mounted on the device holder for the repeated measurement(s) to minimize any unexpected variations in the repeated results.

SAR Measurement Variability was assessed using the following procedures for each frequency band:

- 1. When the original highest measured SAR is ≥ 0.80 W/kg, the measurement was repeated once.
- A second repeated measurement was preformed only if the ratio of largest to smallest SAR for the original and first repeated measurements was > 1.20 or when the original or repeated measurement was ≥ 1.45 W/kg (~ 10% from the 1-g SAR limit).
- A third repeated measurement was performed only if the original, first or second repeated measurement was ≥
 W/kg and the ratio of largest to smallest SAR for the original, first and second repeated measurements is >
 1.20.
- 4. Repeated measurements are not required when the original highest measured SAR is < 0.80 W/kg

Table 13.1 Body SAR Measurement Variability Results

Frequ	equency Mode				# of Time Spacing [Side]	Measured SAR (1g)	1st Repeated SAR(1g)	Ratio	2nd Repeated SAR(1g)	Ratio	3rd Repeated SAR(1g)	Ratio
MHz	Ch.			01013		(W/kg)	(W/kg)		(W/kg)		(W/kg)	
915.25	25	RFID	RFID	N/A	0 mm [Rear]	1.390	1.370	1.01	N/A	N/A	N/A	N/A
ANSI / IEEE C95.1-2005- SAFETY LIMIT Spatial Peak Uncontrolled Exposure/General Population Exposure						Body 1.6 W/kg (mW/g) averaged over 1 gram						

13.2 Measurement Uncertainty

The measured SAR was <1.5 W/kg for all frequency bands. Therefore, per KDB Publication 865664D01v01r01, the standard measurement uncertainty analysis per IEEE 1528-2003 was not required.

14. IEEE P1528 - MEASUREMENT UNCERTAINTIES

900 MHz Body

Error Description	Uncertaint	Probability	Divisor	(Ci)	Standard	vi 2 or
Error Description	value ±%	Distribution	Divisor	1g	(1g)	Veff
Measurement System						
Probe calibration	± 6.0	Normal	1	1	± 6.0 %	∞
Axial isotropy	± 4.7	Rectangular	√3	1	± 2.714 %	∞
Hemispherical isotropy	± 9.6	Rectangular	√3	1	± 5.543 %	8
Boundary Effects	± 0.8	Rectangular	√3	1	± 0.462 %	∞
Probe Linearity	± 4.7	Rectangular	√3	1	± 2.714 %	∞
Detection limits	± 0.25	Rectangular	√3	1	± 0.144 %	∞
Readout Electronics	± 1.0	Normal	1	1	± 1.0 %	∞
Response time	± 0.8	Rectangular	√3	1	± 0.462 %	∞
Integration time	± 2.6	Rectangular	√3	1	± 1.501 %	∞
RF Ambient Conditions	± 3.0	Rectangular	√3	1	± 1.732 %	∞
Probe Positioner	± 0.4	Rectangular	√3	1	± 0.231 %	∞
Probe Positioning	± 2.9	Rectangular	√3	1	± 1.674 %	∞
Algorithms for Max. SAR Eval.	± 1.0	Rectangular	√3	1	± 0.577 %	∞
Test Sample Related						
Device Positioning	± 2.9	Normal	1	1	± 2.9 %	145
Device Holder	± 3.6	Normal	1	1	± 3.6 %	5
Power Drift	± 5.0	Rectangular	√3	1	± 2.887 %	∞
Physical Parameters						
Phantom Shell	± 4.0	Rectangular	√3	1	± 2.309 %	∞
Liquid conductivity (Target)	± 5.0	Rectangular	√3	0.64	± 2.887 %	∞
Liquid conductivity (Meas.)	± 4.4	Normal	1	0.64	± 4.4 %	∞
Liquid permittivity (Target)	± 5.0	Rectangular	√3	0.6	± 2.887 %	8
Liquid permittivity (Meas.)	± 4.6	Normal	1	0.6	± 4.6 %	8
CombinedStandard Uncertainty					± 12.2 %	330
Expanded Uncertainty (k=2)					± 24.4 %	

The above measurement uncertainties are according to IEEE P1528 (2003)

15.CONCLUSION

Measurement Conclusion

The SAR measurement indicates that the EUT complies with the RF radiation exposure limits of the FCC. These measurements are taken to simulate the RF effects exposure under the worst-case conditions. Precise laboratory measures were taken to assure repeatability of the tests. The tested device complies with the requirements in respect to all parameters subject to the test. The test results and statements relate only to the item(s)tested.

Please note that the absorption and distribution of electromagnetic energy in the body are very complex phenomena that depend on the mass, shape, and size of the body, the orientation of the body with respect to the field vectors, and the electrical properties of both the body and the environment. Other variables that may play a substantial role impossible biological effect are those that characterize the environment (e.g. ambient temperature, air velocity, relative humidity, and body insulation) and those that characterize the individual (e.g. age, gender, activity level, debilitation, or disease).

Because innumerable factors may interact to determine the specific biological outcome of an exposure to electromagnetic fields, any protection guide shall consider maximal amplification of biological effects as a result of field-body interactions, environmental conditions, and physiological variables.

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