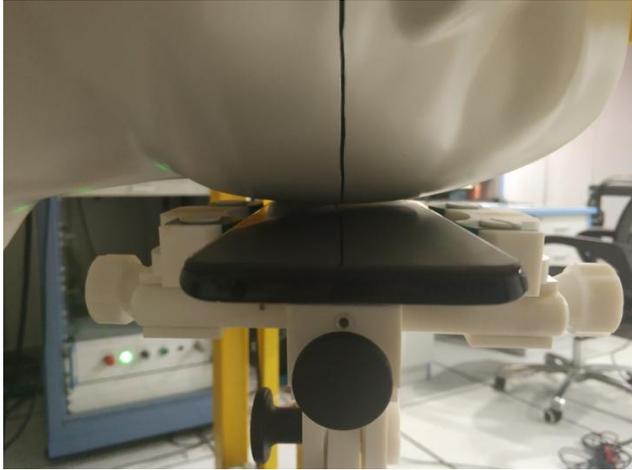
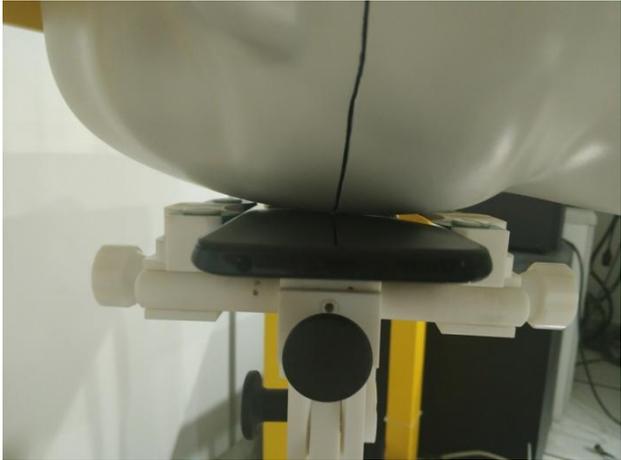
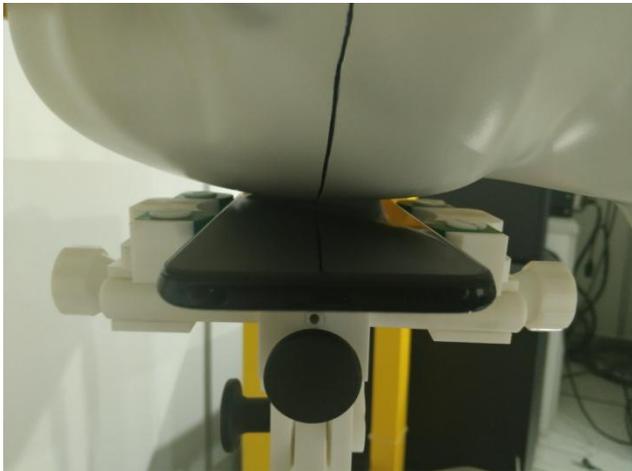
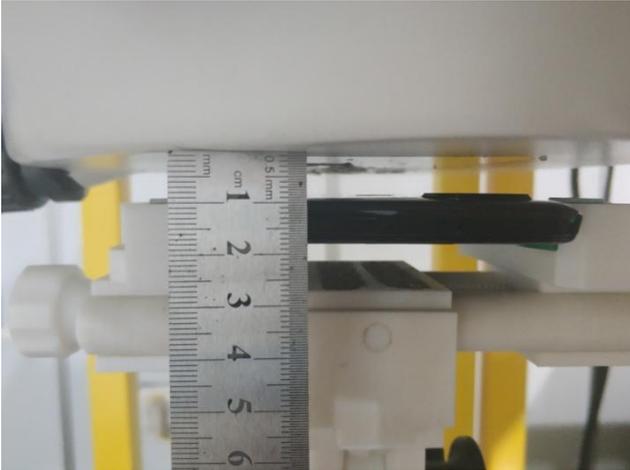


Appendix D: SAR Test Setup

<p>Photo 1: Measurement System SATIMO</p>	<p>Photo 2: Left Cheek</p>
 A photograph showing a white KUKA robotic arm mounted on a yellow table. The arm is holding a probe that is positioned over a white, head-shaped mannequin. In the background, there are various electronic equipment and a computer monitor.	 A close-up photograph of the left cheek area of the white mannequin. The mannequin is mounted on a black and white mechanical fixture. A black circular sensor or probe is visible in the foreground, positioned near the cheek.
<p>Photo 3: Left Tilt 15 °</p>	<p>Photo 4: Right Cheek</p>
 A close-up photograph of the left cheek area of the white mannequin, tilted at a 15-degree angle. The mannequin is mounted on a black and white mechanical fixture. A black circular sensor or probe is visible in the foreground, positioned near the cheek.	 A close-up photograph of the right cheek area of the white mannequin. The mannequin is mounted on a black and white mechanical fixture. A black circular sensor or probe is visible in the foreground, positioned near the cheek.
<p>Photo 5: Right Tilt 15 °</p>	<p>Photo 6: Face upward 10mm</p>
 A close-up photograph of the right cheek area of the white mannequin, tilted at a 15-degree angle. The mannequin is mounted on a black and white mechanical fixture. A black circular sensor or probe is visible in the foreground, positioned near the cheek.	 A close-up photograph of the white mannequin's face, oriented upwards. A ruler is placed vertically next to the mannequin's face, showing a measurement of 10mm. The mannequin is mounted on a black and white mechanical fixture.

<p>Photo 7: Back Upward 10mm</p>	<p>Photo 8: Edge A 10mm</p>
	
<p>Photo 9: Edge B 10mm</p>	<p>Photo 10: Edge C 10mm</p>
	
<p>Photo 11: Edge D 10mm</p>	<p>Photo 12: Liquid deep(15cm)</p>
	

