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Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 108**

Client **Auden**

Certificate No: **ER3-2302_May08**

CALIBRATION CERTIFICATE

Object **ER3DV6 - SN:2302**

Calibration procedure(s) **QA CAL-02.v5
Calibration procedure for E-field probes optimized for close near field
evaluations in air**

Calibration date: **May 19, 2008**

Condition of the calibrated item **In Tolerance**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	1-Apr-08 (No. 217-00788)	Apr-09
Power sensor E4412A	MY41495277	1-Apr-08 (No. 217-00788)	Apr-09
Power sensor E4412A	MY41498087	1-Apr-08 (No. 217-00788)	Apr-09
Reference 3 dB Attenuator	SN: S5054 (3c)	8-Aug-07 (No. 217-00719)	Aug-08
Reference 20 dB Attenuator	SN: S5086 (20b)	31-Mar-08 (No. 217-00787)	Apr-09
Reference 30 dB Attenuator	SN: S5129 (30b)	8-Aug-07 (No. 217-00720)	Aug-08
Reference Probe ER3DV6	SN: 2328	2-Oct-07 (No. ER3-2328_Oct07)	Oct-08
DAE4	SN: 654	24-Apr-08 (No. DAE4-654_Apr08)	Apr-09

Secondary Standards	ID #	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Oct-07)	In house check: Oct-09
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-07)	In house check: Oct-08

	Name	Function	Signature
Calibrated by:	Katja Pokovic	Technical Manager	
Approved by:	Niels Kuster	Quality Manager	

Issued: May 20, 2008

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Accreditation No.: **SCS 108**

Glossary:

NORM _{x,y,z}	sensitivity in free space
DCP	diode compression point
Polarization φ	φ rotation around probe axis
Polarization ϑ	ϑ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\vartheta = 0$ is normal to probe axis
Connector Angle	information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

- IEEE Std 1309-2005, "IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz", December 2005.

Methods Applied and Interpretation of Parameters:

- NORM_{x,y,z}*: Assessed for E-field polarization $\vartheta = 0$ for XY sensors and $\vartheta = 90$ for Z sensor ($f \leq 900$ MHz in TEM-cell; $f > 1800$ MHz: R22 waveguide).
- NORM(f)_{x,y,z}* = *NORM_{x,y,z}* * *frequency_response* (see Frequency Response Chart).
- DCP_{x,y,z}*: DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency.
- Spherical isotropy (3D deviation from isotropy)*: in a locally homogeneous field realized using an open waveguide setup.
- Sensor Offset*: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle*: The angle is assessed using the information gained by determining the *NORM_x* (no uncertainty required).

Probe ER3DV6

SN:2302

Manufactured:	November 6, 2002
Last calibrated:	March 21, 2007
Recalibrated:	May 19, 2008

Calibrated for DASY Systems

(Note: non-compatible with DASY2 system!)

DASY - Parameters of Probe: ER3DV6 SN:2302

Sensitivity in Free Space [$\mu\text{V}/(\text{V}/\text{m})^2$]		Diode Compression ^A	
NormX	1.45 ± 10.1 % (k=2)	DCP X	95 mV
NormY	1.32 ± 10.1 % (k=2)	DCP Y	95 mV
NormZ	1.45 ± 10.1 % (k=2)	DCP Z	98 mV

Frequency Correction

X	0.0
Y	0.0
Z	0.0

Sensor Offset (Probe Tip to Sensor Center)

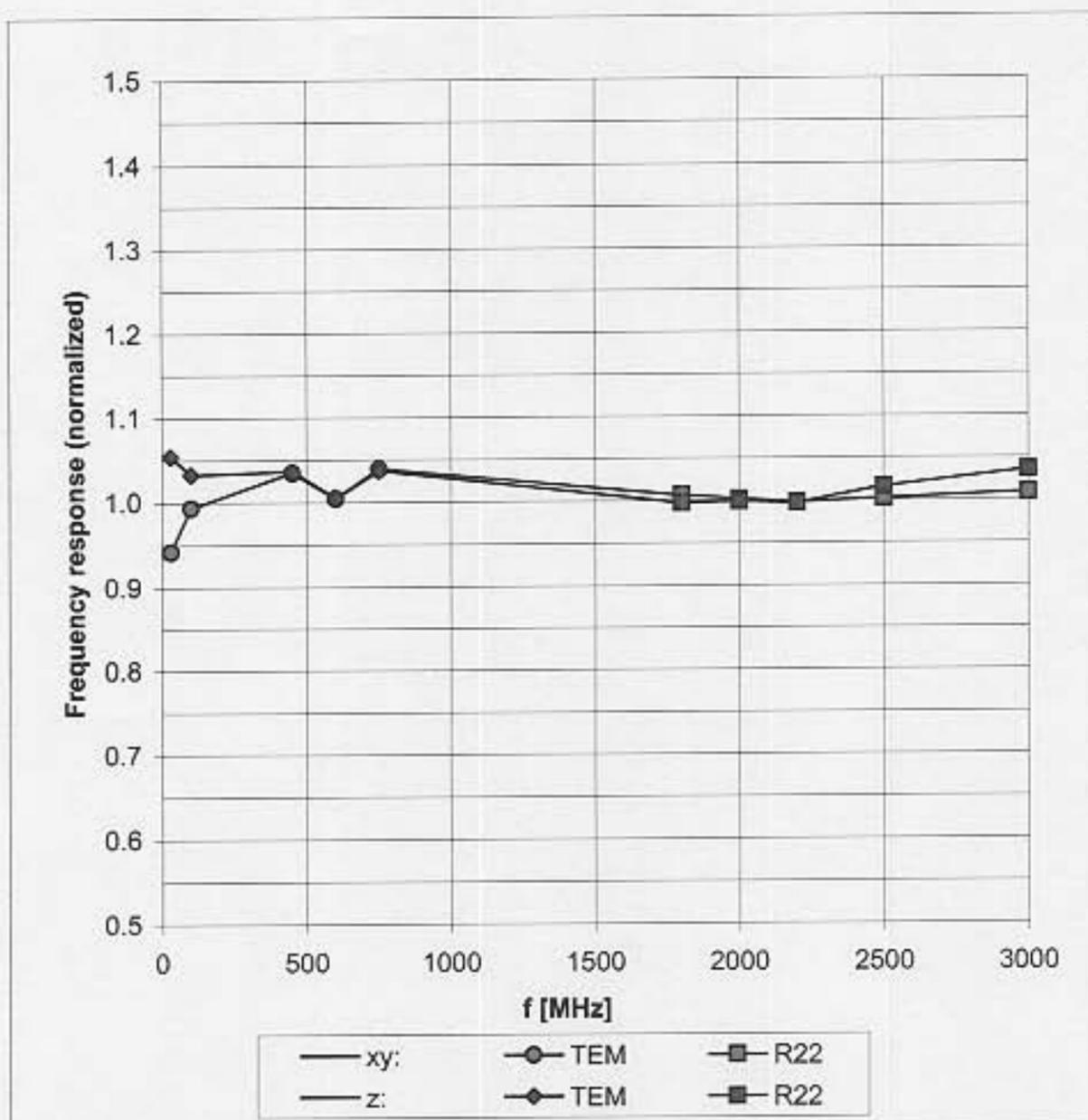
X	2.5 mm
Y	2.5 mm
Z	2.5 mm

Connector Angle 0 °

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

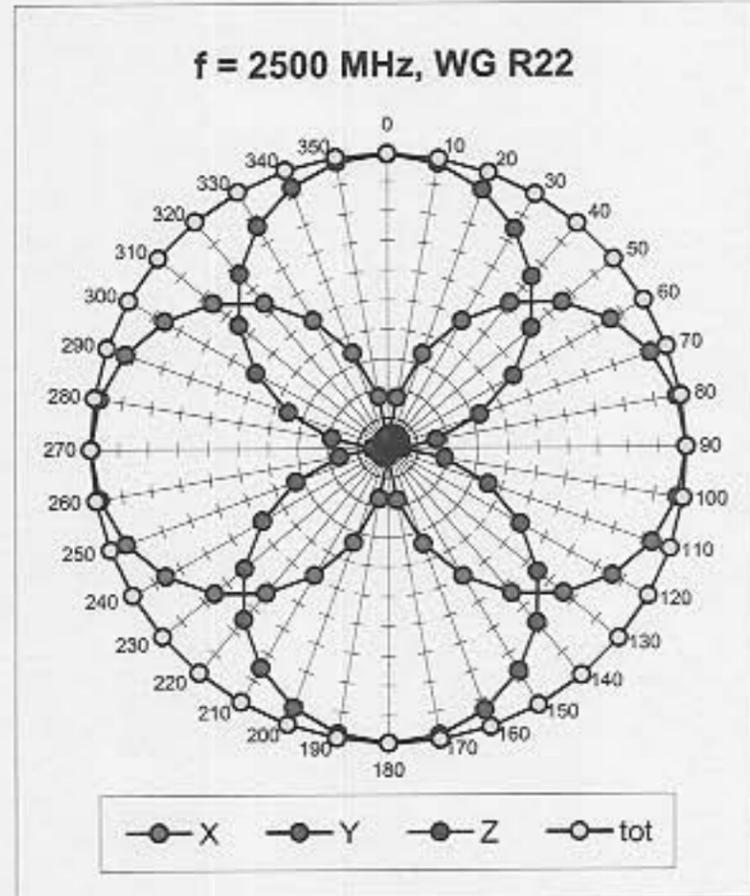
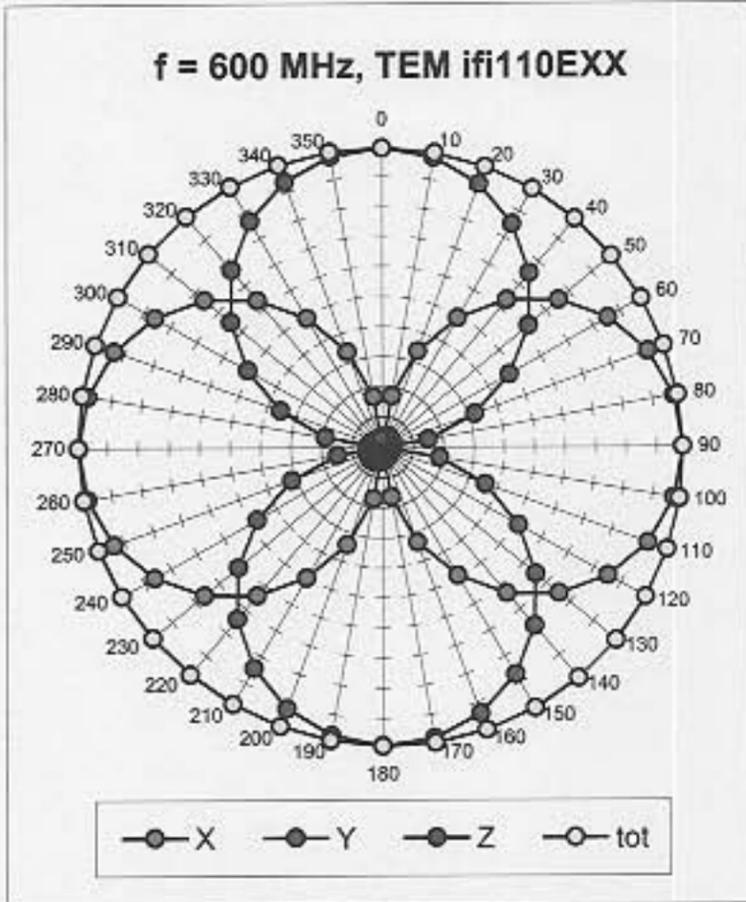
^A numerical linearization parameter: uncertainty not required

Frequency Response of E-Field (TEM-Cell:ifi110 EXX, Waveguide R22)

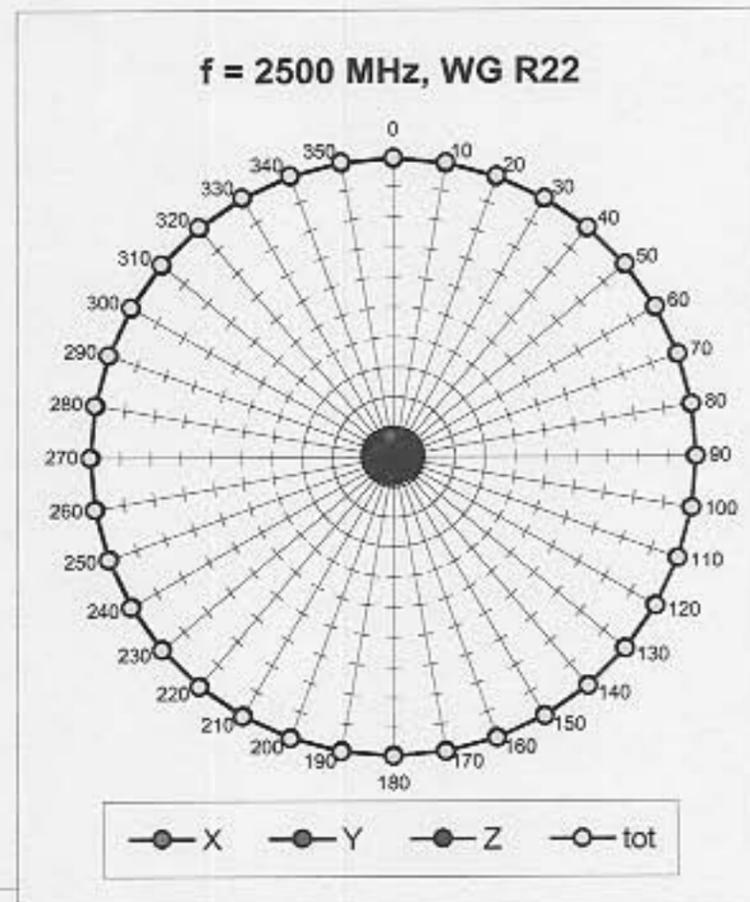
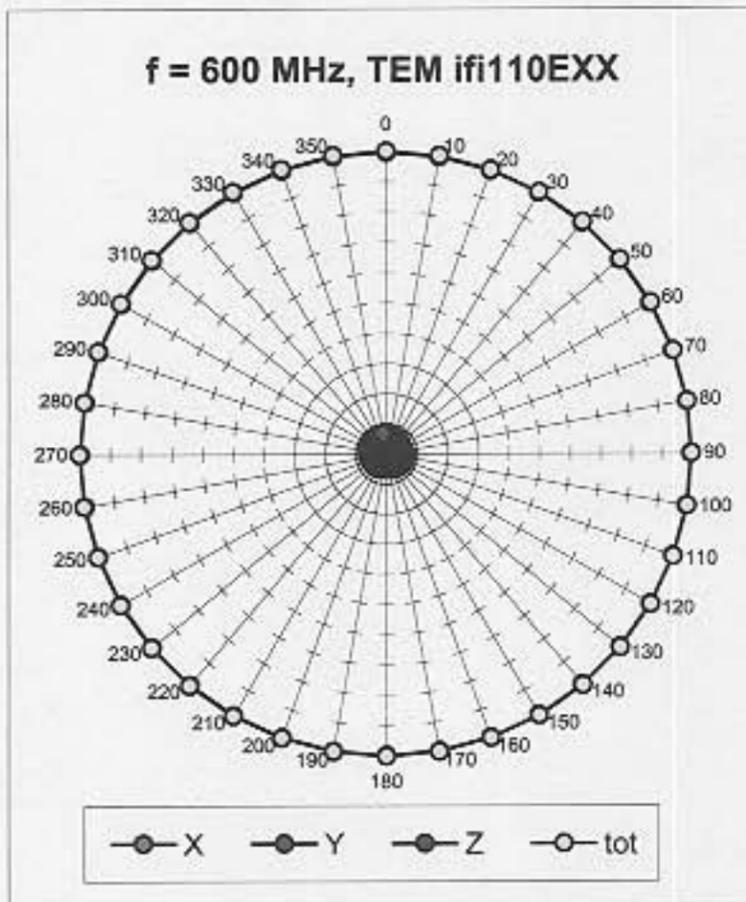


Uncertainty of Frequency Response of E-field: $\pm 6.3\%$ (k=2)

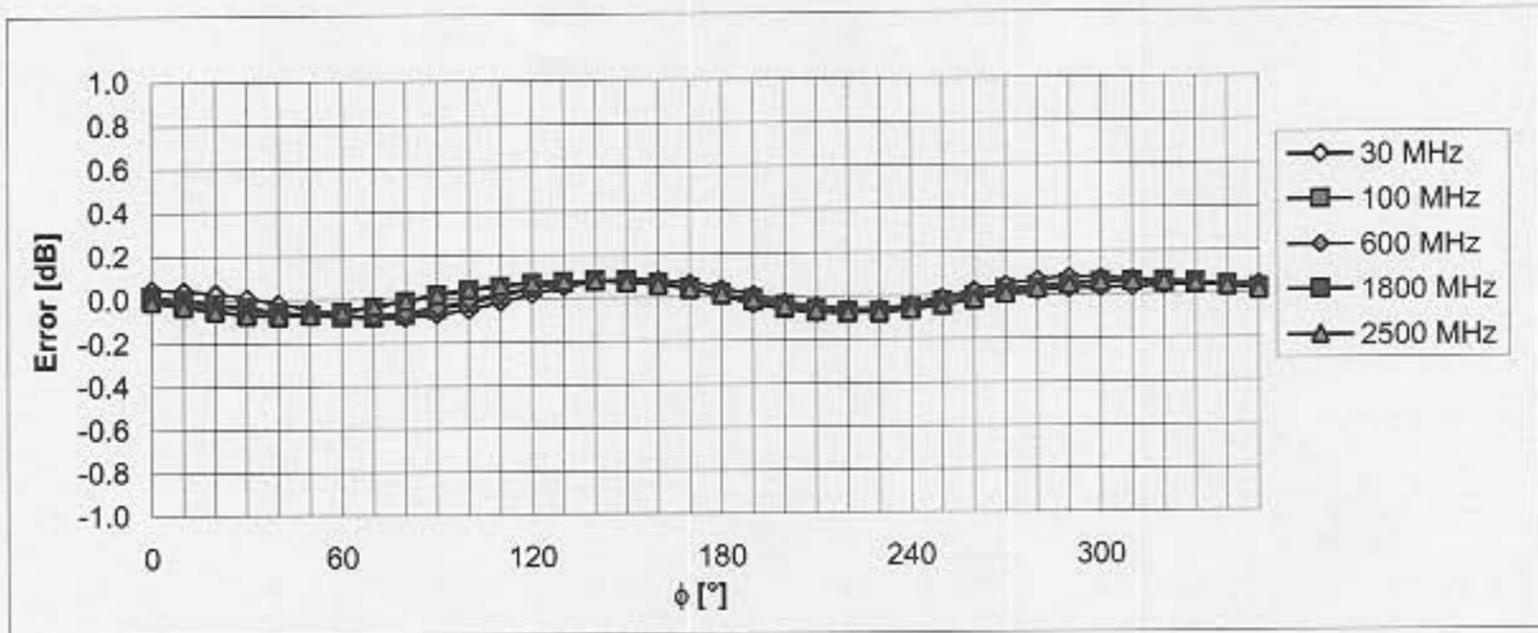
Receiving Pattern (ϕ), $\vartheta = 0^\circ$



Receiving Pattern (ϕ), $\vartheta = 90^\circ$

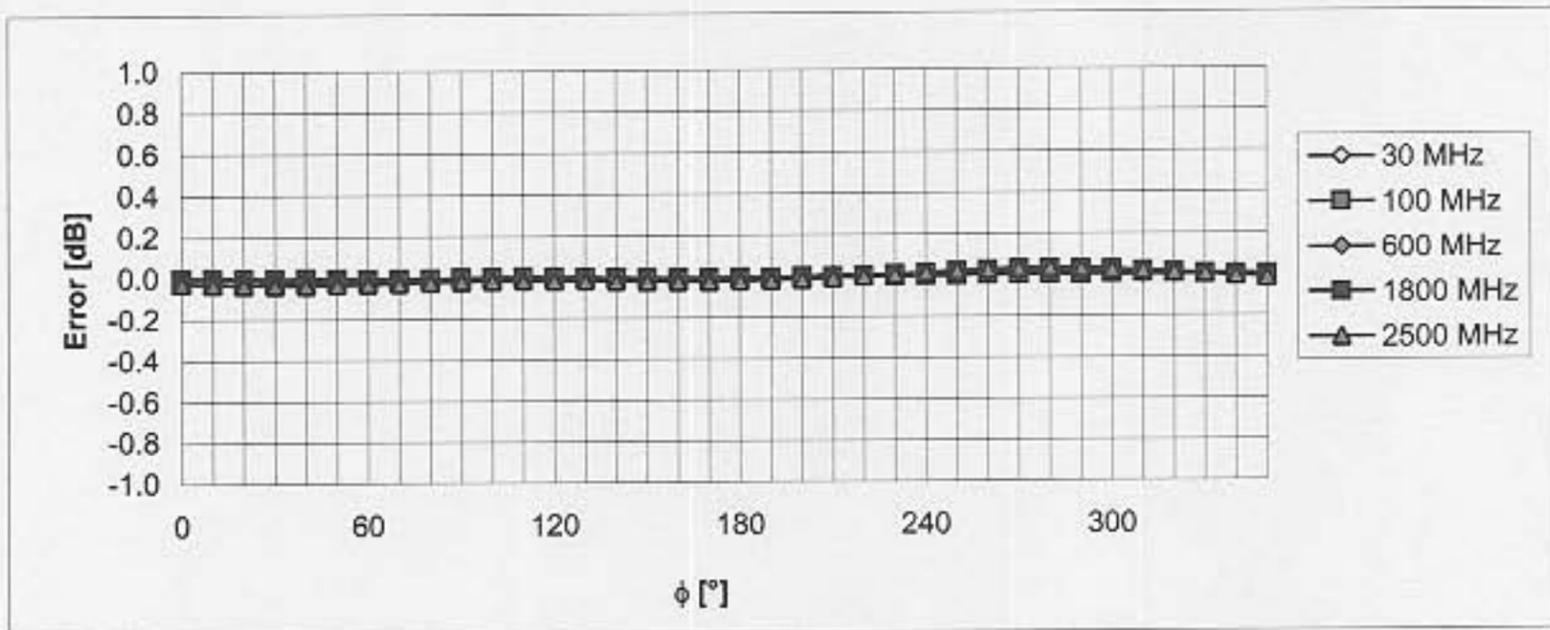


Receiving Pattern (ϕ), $\vartheta = 0^\circ$



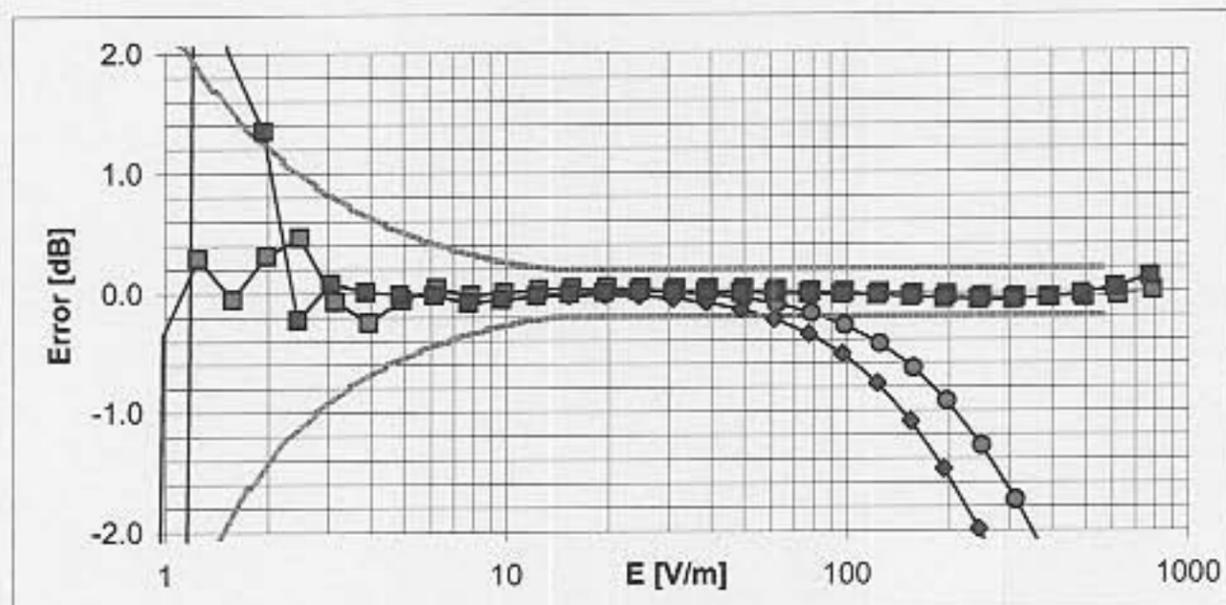
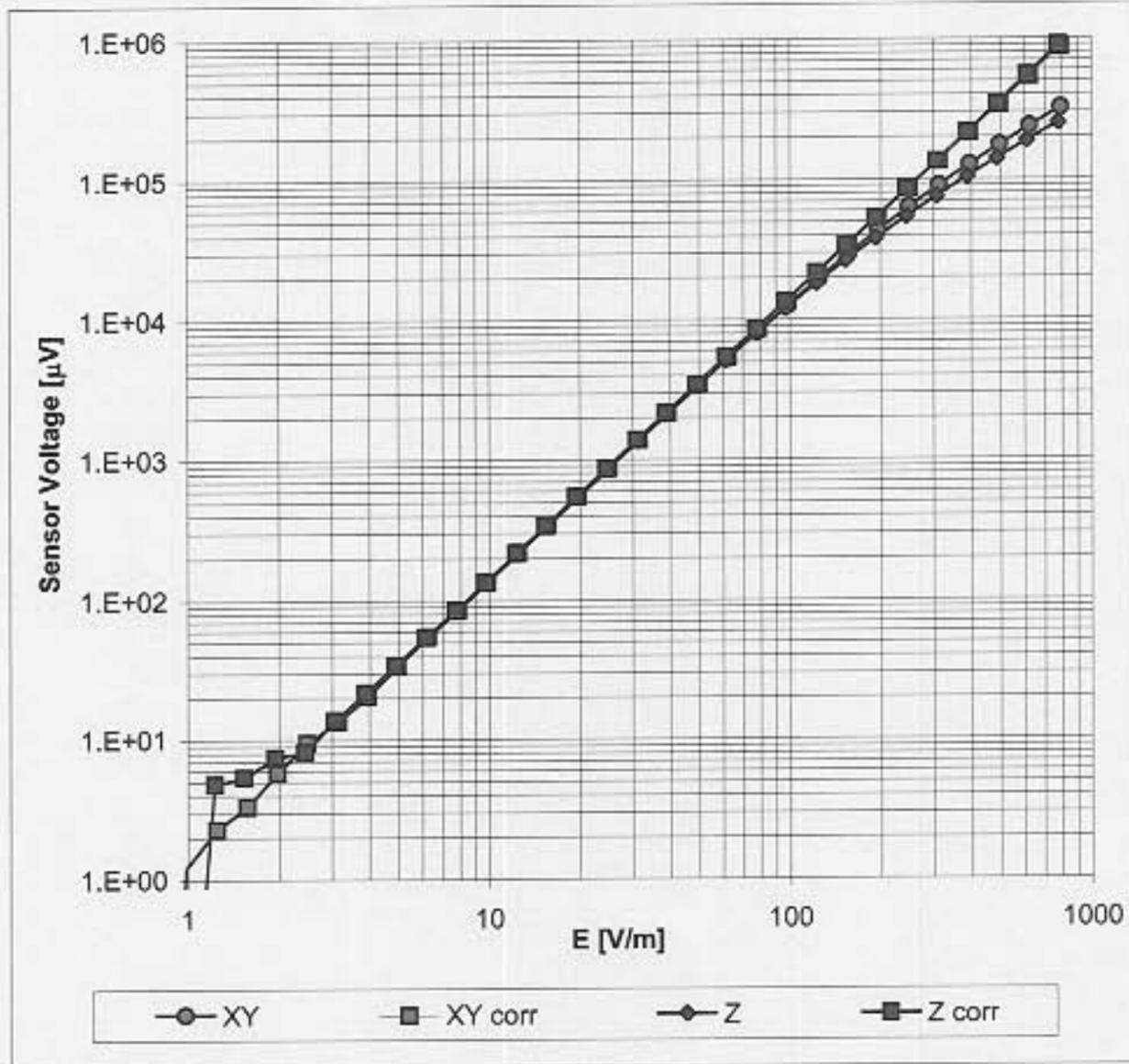
Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ (k=2)

Receiving Pattern (ϕ), $\vartheta = 90^\circ$



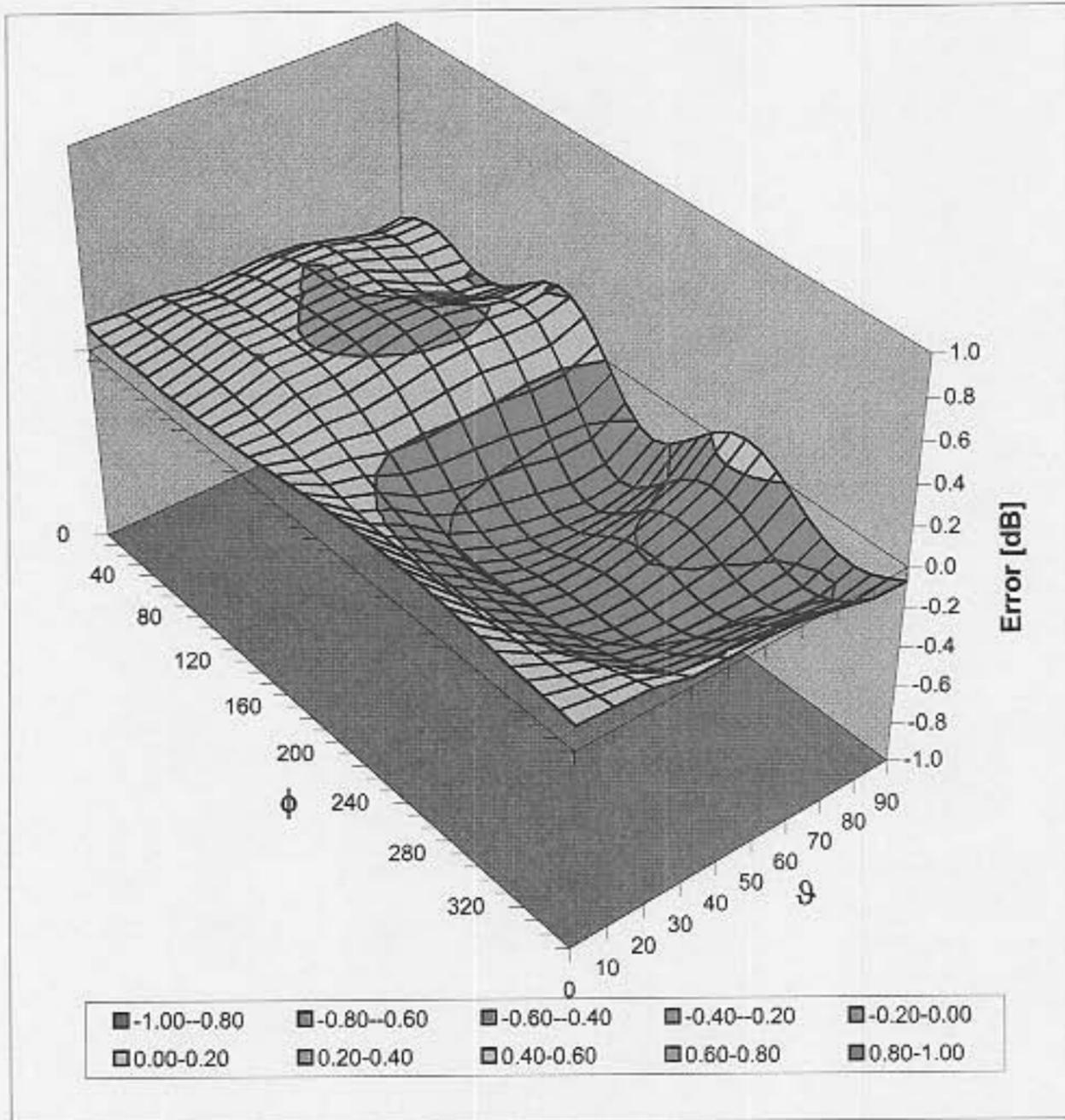
Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ (k=2)

Dynamic Range f(E-field) (Waveguide R22, f = 1800 MHz)



Uncertainty of Linearity Assessment: $\pm 0.6\%$ ($k=2$)

Deviation from Isotropy in Air Error (ϕ, ϑ), $f = 900$ MHz



Uncertainty of Spherical Isotropy Assessment: $\pm 2.6\%$ ($k=2$)

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Accreditation No.: **SCS 108**

Client **Auden**

Certificate No: **H3-6187_May08**

CALIBRATION CERTIFICATE

Object **H3DV6 - SN:6187**

Calibration procedure(s) **QA CAL-03.v5
Calibration procedure for H-field probes optimized for close near field
evaluations in air**

Calibration date: **May 19, 2008**

Condition of the calibrated item **In Tolerance**

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Calibration Equipment used (M&TE critical for calibration)

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Reference 30 dB Attenuator	SN: S5129 (30b)	8-Aug-07 (No. 217-00720)	Aug-08
Reference Probe H3DV6	SN: 6182	2-Oct-07 (No. H3-6182_Oct07)	Oct-08
DAE4	SN: 654	24-Apr-08 (No. DAE4-654_Apr08)	Apr-09

Secondary Standards	ID #	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Oct-07)	In house check: Oct-09
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-07)	In house check: Oct-08

	Name	Function	Signature
Calibrated by:	Katja Pokovic	Technical Manager	

Approved by:	Niels Kuster	Quality Manager	
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NORM _{x,y,z}	sensitivity in free space
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Polarization φ	φ rotation around probe axis
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Connector Angle	information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

- IEEE Std 1309-2005, "IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz", December 2005.

Methods Applied and Interpretation of Parameters:

- X, Y, Z_{a0a1a2} : Assessed for E-field polarization $\vartheta = 90$ for XY sensors and $\vartheta = 0$ for Z sensor ($f \leq 900$ MHz in TEM-cell; $f > 1800$ MHz: R22 waveguide).
- $X, Y, Z(f)_{a0a1a2} = X, Y, Z_{a0a1a2} * frequency_response$ (see Frequency Response Chart).
- $DCP_{x,y,z}$: DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency.
- Spherical isotropy (3D deviation from isotropy)*: in a locally homogeneous field realized using an open waveguide setup.
- Sensor Offset*: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle*: The angle is assessed using the information gained by determining the X_{a0a1a2} (no uncertainty required).

Probe H3DV6

SN:6187

Manufactured:	June 8, 2004
Last calibrated:	March 21, 2007
Recalibrated:	May 19, 2008

Calibrated for DASY Systems

(Note: non-compatible with DASY2 system!)

DASY - Parameters of Probe: H3DV6 SN:6187

Sensitivity in Free Space [A/m / $\sqrt{\mu\text{V}}$]

	a0	a1	a2
X	3.157E-3	2.508E-5	3.858E-6 ± 5.1 % (k=2)
Y	2.435E-3	9.642E-5	3.239E-6 ± 5.1 % (k=2)
Z	2.952E-3	2.920E-5	4.880E-5 ± 5.1 % (k=2)

Diode Compression¹

DCP X	91 mV
DCP Y	91 mV
DCP Z	85 mV

Sensor Offset (Probe Tip to Sensor Center)

X	3.0 mm
Y	3.0 mm
Z	3.0 mm

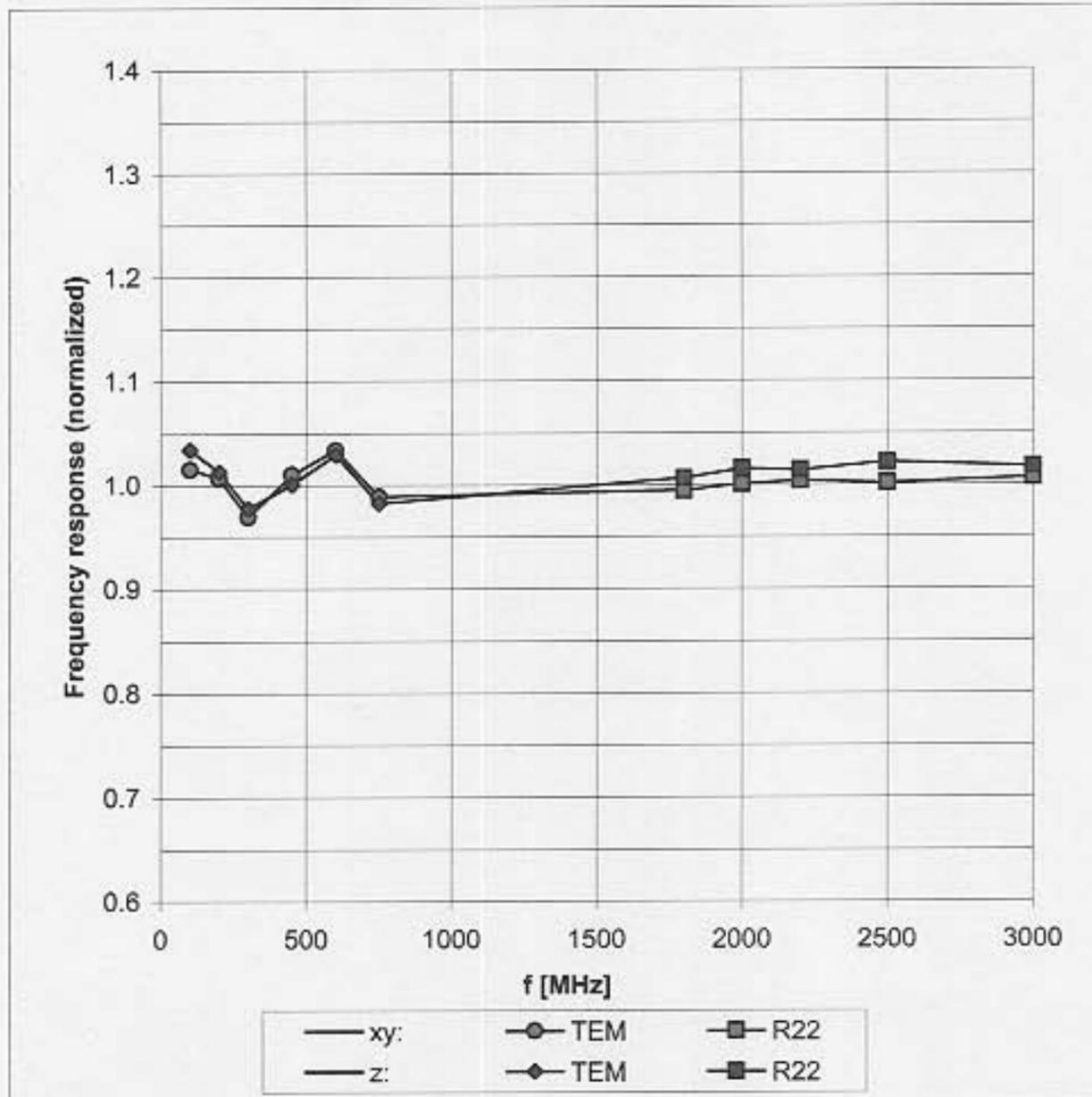
Connector Angle 66 °

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

¹ numerical linearization parameter: uncertainty not required

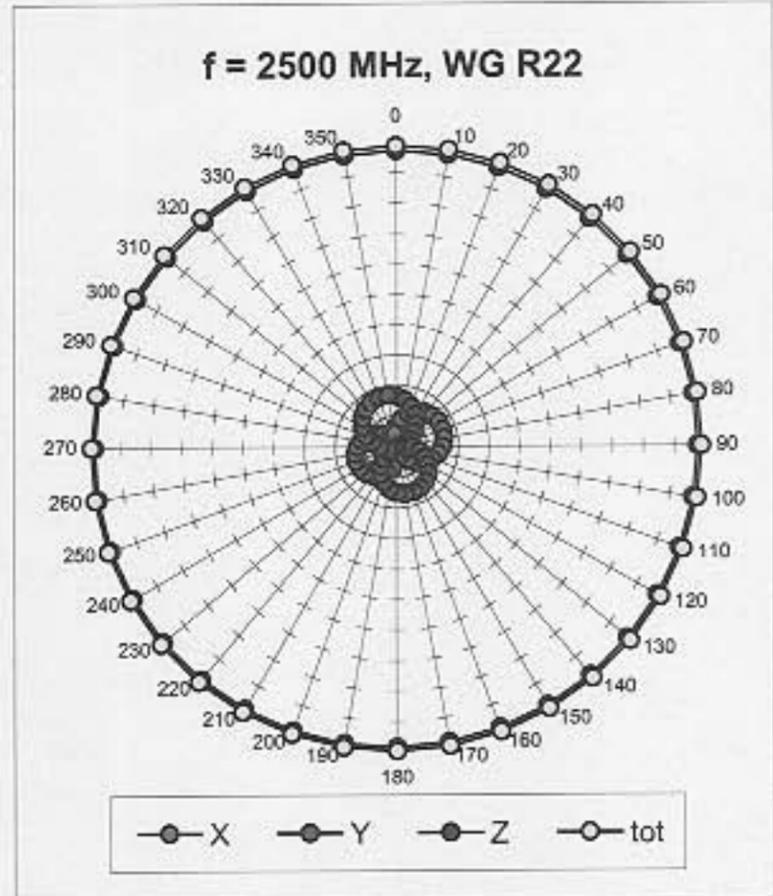
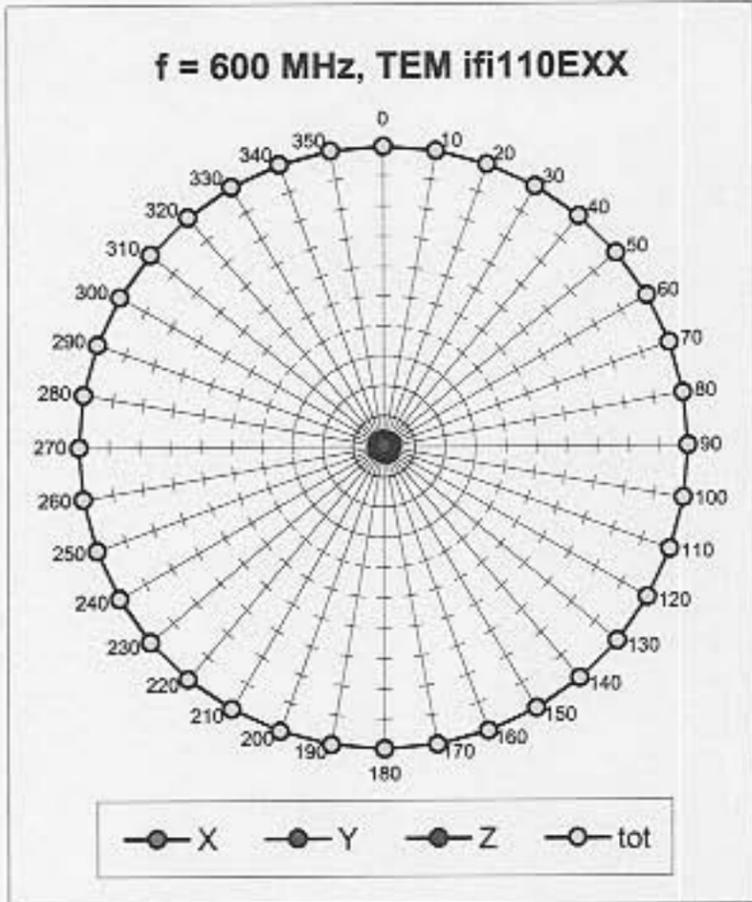
Frequency Response of H-Field

(TEM-Cell:ifi110 EXX, Waveguide R22)

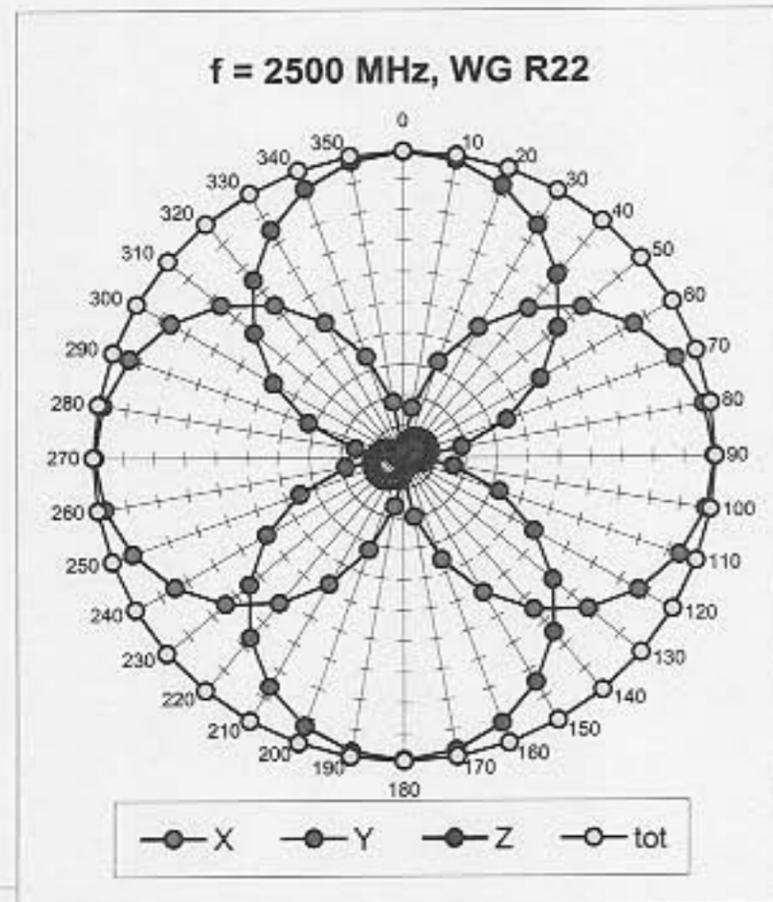
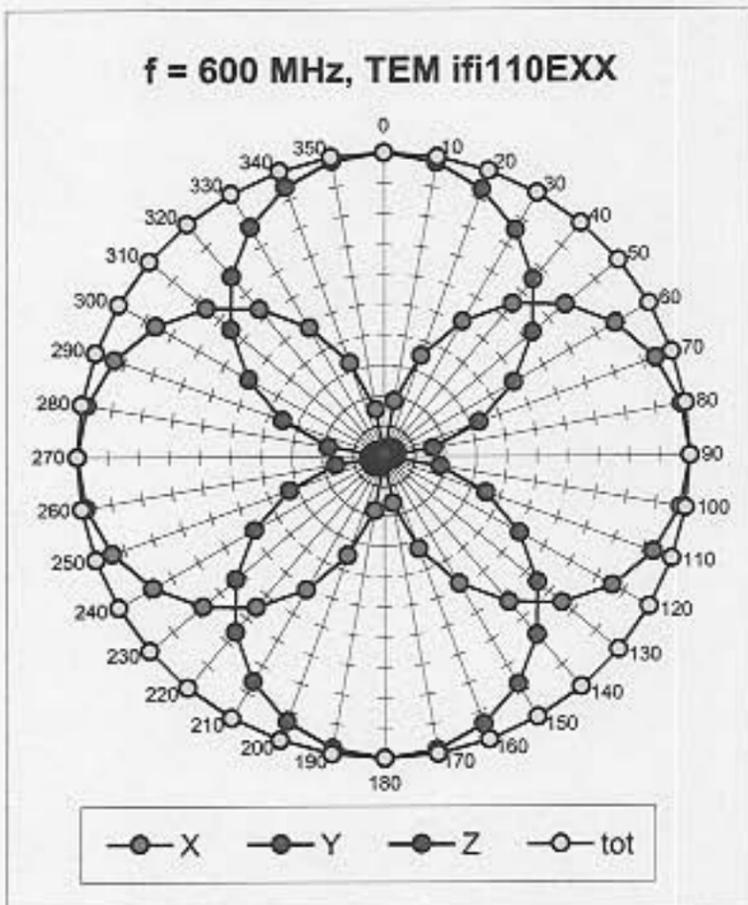


Uncertainty of Frequency Response of E-field: $\pm 6.3\%$ (k=2)

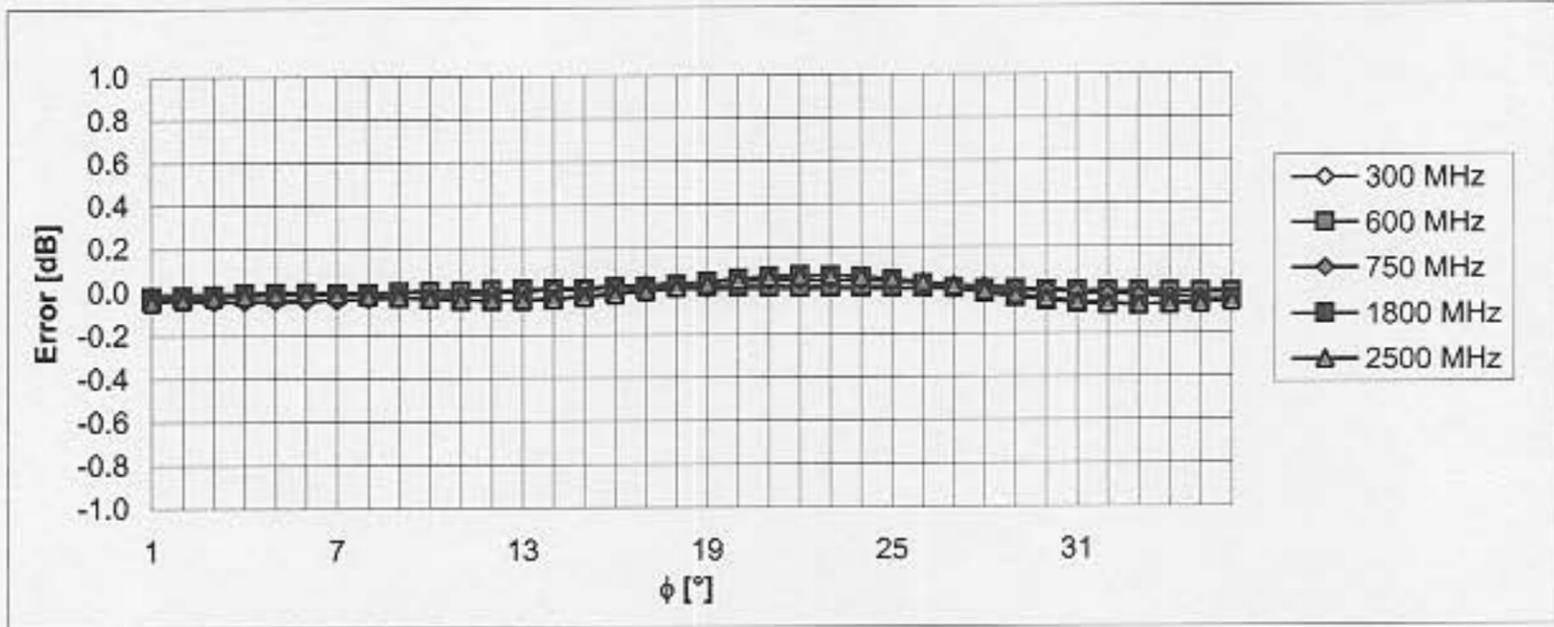
Receiving Pattern (ϕ), $\vartheta = 0^\circ$



Receiving Pattern (ϕ), $\vartheta = 90^\circ$

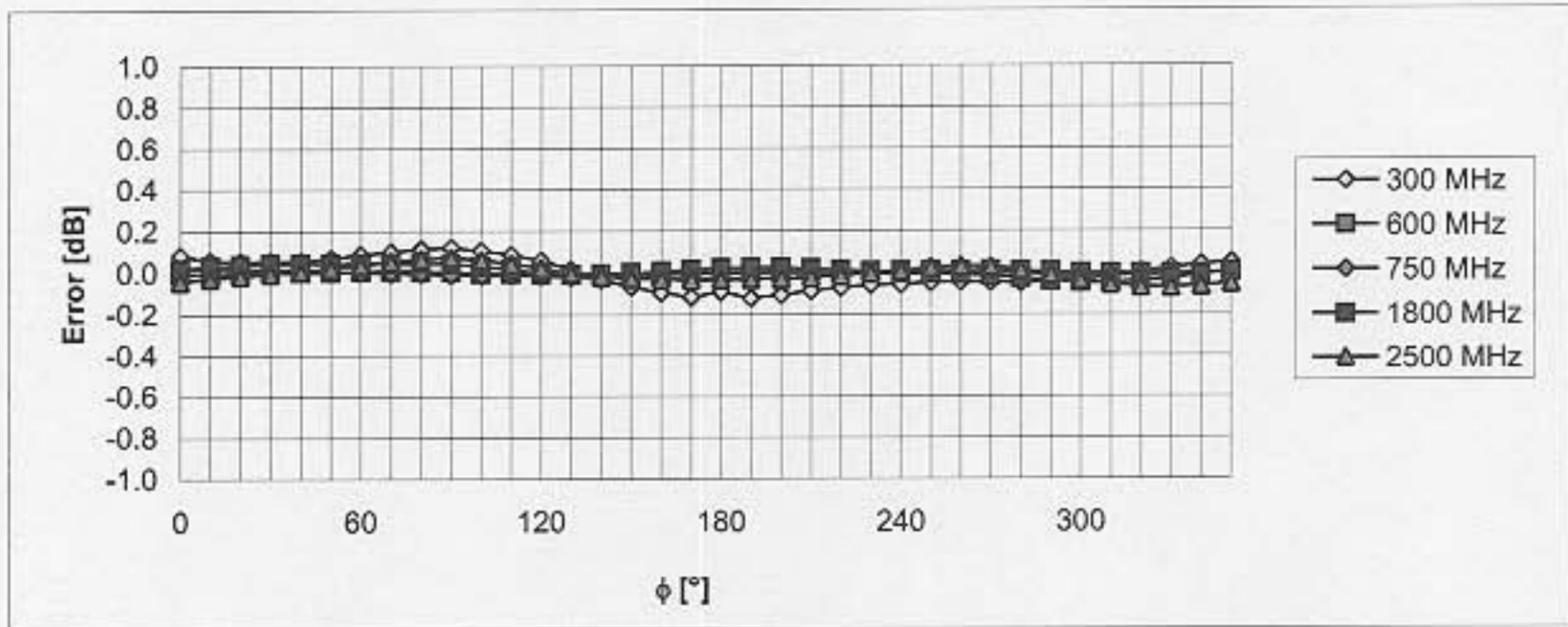


Receiving Pattern (ϕ), $\vartheta = 0^\circ$



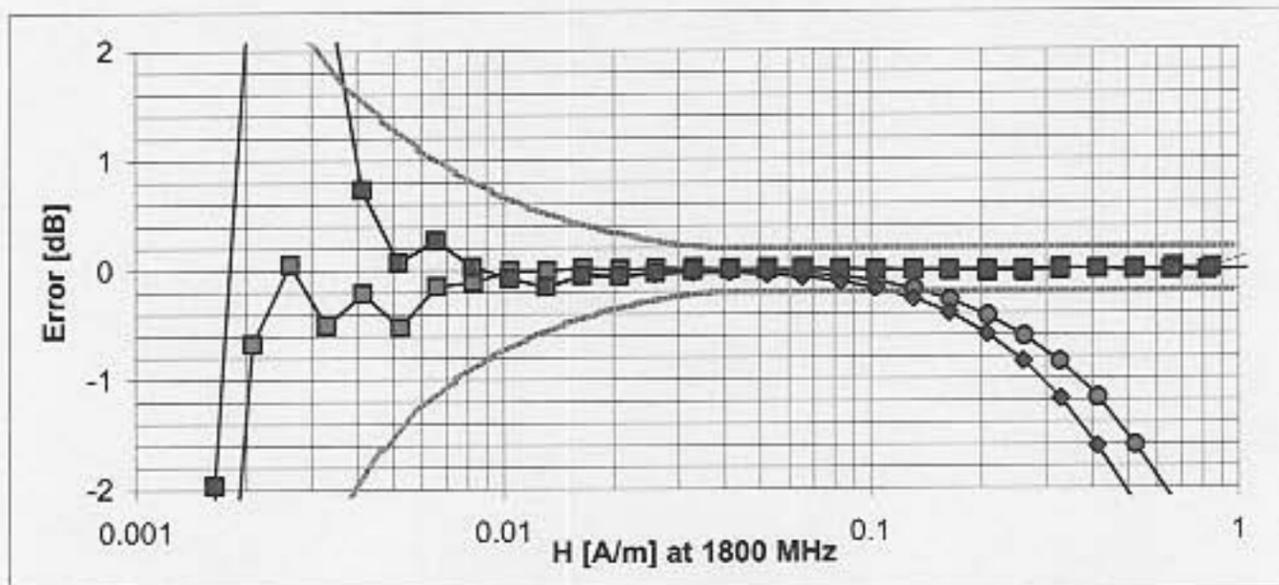
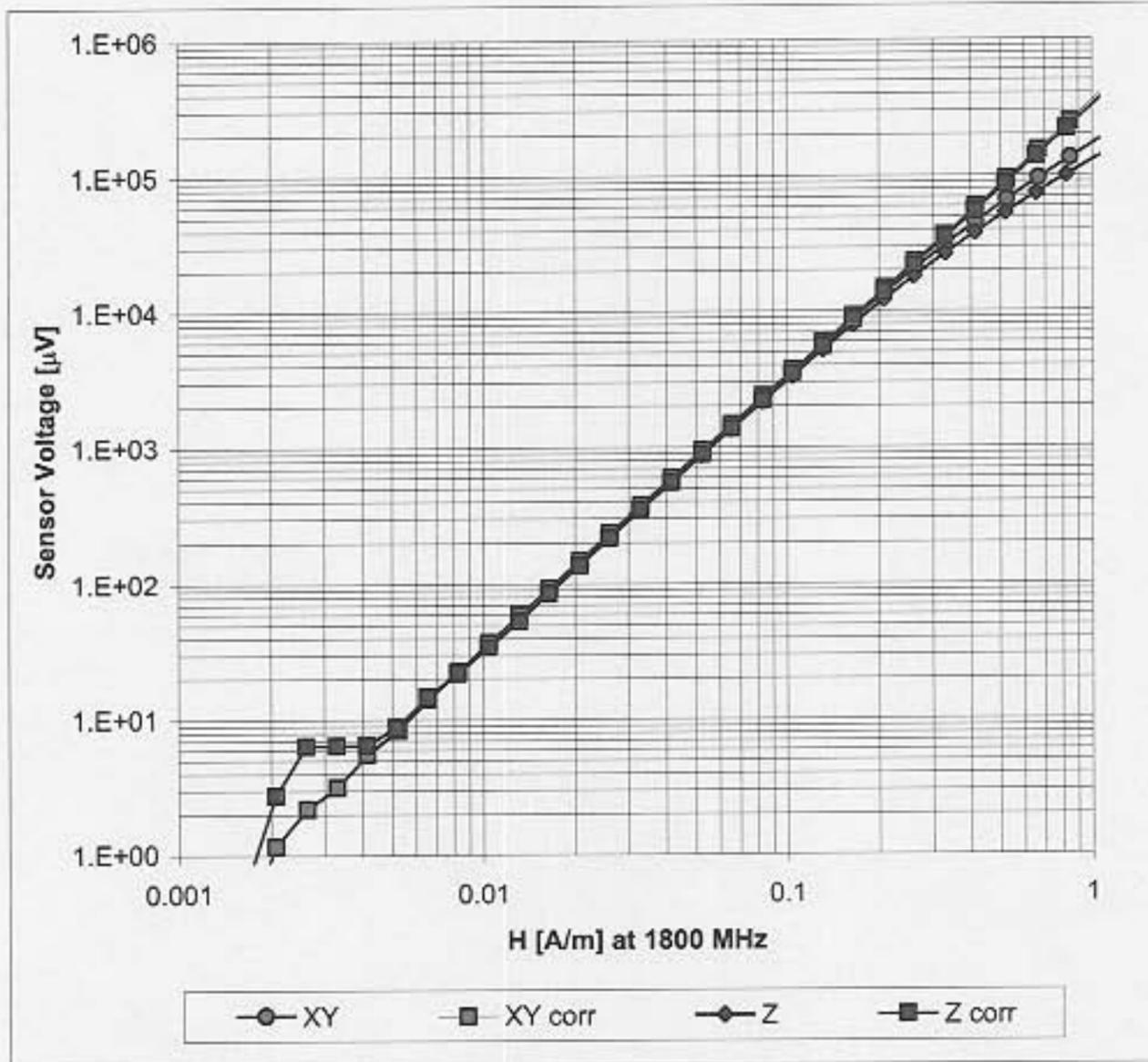
Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)

Receiving Pattern (ϕ), $\vartheta = 90^\circ$



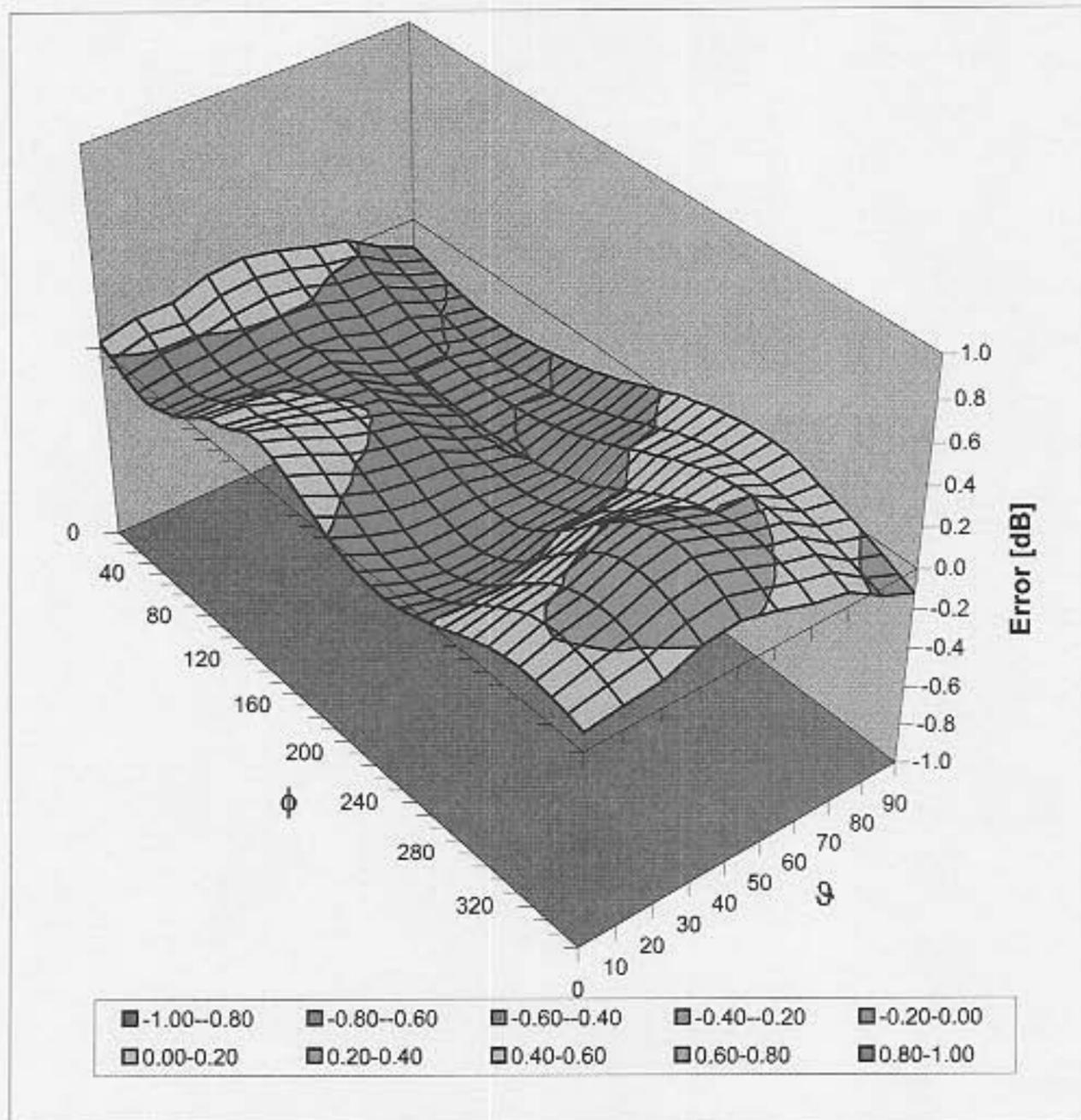
Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)

Dynamic Range f(H-field) (Waveguide R22, f = 1800 MHz)



Uncertainty of Linearity Assessment: $\pm 0.6\%$ (k=2)

Deviation from Isotropy in Air Error (ϕ, ϑ), $f = 900$ MHz



Uncertainty of Spherical Isotropy Assessment: $\pm 2.6\%$ ($k=2$)



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Accreditation No.: **SCS 108**

Client **ATL (Auden)**

Certificate No: **DAE4-779_Nov08**

CALIBRATION CERTIFICATE

Object **DAE4 - SD 000 D04 BJ - SN: 779**

Calibration procedure(s) **QA CAL-06.v12
Calibration procedure for the data acquisition electronics (DAE)**

Calibration date: **November 11, 2008**

Condition of the calibrated item **In Tolerance**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility; environment temperature $(22 \pm 3)^\circ\text{C}$ and humidity $< 70\%$.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Fluke Process Calibrator Type 702	SN: 6295803	30-Sep-08 (No: 7673)	Sep-09
Keithley Multimeter Type 2001	SN: 0810278	30-Sep-08 (No: 7670)	Sep-09
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Calibrator Box V1.1	SE UMS 006 AB 1004	06-Jun-08 (in house check)	In house check: Jun-09

Calibrated by: **Name** Daniel Hess **Function** Technician **Signature** *D. Hess*

Approved by: **Name** Fin Bornholt **Function** R&D Director **Signature** *F. Bornholt*

Issued: November 11, 2008

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Glossary

DAE data acquisition electronics
Connector angle information used in DASY system to align probe sensor X to the robot coordinate system.

Methods Applied and Interpretation of Parameters

- *DC Voltage Measurement:* Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- *Connector angle:* The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters as documented in the Appendix contain technical information as a result from the performance test and require no uncertainty.
 - *DC Voltage Measurement Linearity:* Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
 - *Common mode sensitivity:* Influence of a positive or negative common mode voltage on the differential measurement.
 - *Channel separation:* Influence of a voltage on the neighbor channels not subject to an input voltage.
 - *AD Converter Values with inputs shorted:* Values on the internal AD converter corresponding to zero input voltage
 - *Input Offset Measurement:* Output voltage and statistical results over a large number of zero voltage measurements.
 - *Input Offset Current:* Typical value for information; Maximum channel input offset current, not considering the input resistance.
 - *Input resistance:* DAE input resistance at the connector, during internal auto-zeroing and during measurement.
 - *Low Battery Alarm Voltage:* Typical value for information. Below this voltage, a battery alarm signal is generated.
 - *Power consumption:* Typical value for information. Supply currents in various operating modes.

DC Voltage Measurement

A/D - Converter Resolution nominal

High Range: 1LSB = 6.1 μ V, full range = -100...+300 mV
Low Range: 1LSB = 61nV, full range = -1.....+3mV

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Calibration Factors	X	Y	Z
High Range	404.449 \pm 0.1% (k=2)	403.679 \pm 0.1% (k=2)	403.906 \pm 0.1% (k=2)
Low Range	3.97989 \pm 0.7% (k=2)	3.96584 \pm 0.7% (k=2)	3.96834 \pm 0.7% (k=2)

Connector Angle

Connector Angle to be used in DASY system	88 $^{\circ}$ \pm 1 $^{\circ}$
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Appendix

1. DC Voltage Linearity

High Range	Input (μV)	Reading (μV)	Error (%)
Channel X + Input	200000	200000.2	0.00
Channel X + Input	20000	20004.76	0.02
Channel X - Input	20000	-20000.46	0.00
Channel Y + Input	200000	199999.9	0.00
Channel Y + Input	20000	20004.23	0.02
Channel Y - Input	20000	-20000.37	0.00
Channel Z + Input	200000	200000.1	0.00
Channel Z + Input	20000	20003.22	0.02
Channel Z - Input	20000	-20000.98	0.00

Low Range	Input (μV)	Reading (μV)	Error (%)
Channel X + Input	2000	1999.9	0.00
Channel X + Input	200	199.15	-0.43
Channel X - Input	200	-200.23	0.11
Channel Y + Input	2000	2000	0.00
Channel Y + Input	200	198.78	-0.61
Channel Y - Input	200	-199.84	-0.08
Channel Z + Input	2000	2000.1	0.00
Channel Z + Input	200	199.55	-0.22
Channel Z - Input	200	-201.30	0.65

2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Average Reading (μV)	Low Range Average Reading (μV)
Channel X	200	-4.34	-5.11
	- 200	5.57	5.20
Channel Y	200	13.81	13.35
	- 200	-14.32	-13.88
Channel Z	200	2.61	2.32
	- 200	-4.14	-4.46

3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Input Voltage (mV)	Channel X (μV)	Channel Y (μV)	Channel Z (μV)
Channel X	200	-	2.09	0.14
Channel Y	200	-0.49	-	2.40
Channel Z	200	-1.47	0.22	-

4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	High Range (LSB)	Low Range (LSB)
Channel X	15617	15330
Channel Y	15810	15565
Channel Z	16216	15563

5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Input 10M Ω

	Average (μ V)	min. Offset (μ V)	max. Offset (μ V)	Std. Deviation (μ V)
Channel X	-0.13	-2.92	1.64	0.57
Channel Y	-0.83	-2.41	0.83	0.63
Channel Z	-1.03	-2.84	-0.06	0.42

6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

7. Input Resistance

	Zeroing (MOhm)	Measuring (MOhm)
Channel X	0.1999	202.2
Channel Y	0.1999	201.5
Channel Z	0.2000	201.5

8. Low Battery Alarm Voltage (verified during pre test)

Typical values	Alarm Level (VDC)
Supply (+ Vcc)	+7.9
Supply (- Vcc)	-7.6

9. Power Consumption (verified during pre test)

Typical values	Switched off (mA)	Stand by (mA)	Transmitting (mA)
Supply (+ Vcc)	+0.0	+6	+14
Supply (- Vcc)	-0.01	-8	-9