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Accreditation No.: **SCS 108**

Client **Auden**

Certificate No: **AM1DV3-3067_Jan13**

CALIBRATION CERTIFICATE

Object **AM1DV3 - SN: 3067**

Calibration procedure(s) **QA CAL-24.v3
Calibration procedure for AM1D magnetic field probes and TMFS in the
audio range**

Calibration date: **January 10, 2013**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Keithley Multimeter Type 2001	SN: 0810278	02-Oct-12 (No:12728)	Oct-13
Reference Probe AM1DV2	SN: 1008	10-Jan-13 (No. AM1D-1008_Jan13)	Jan-14
DAE4	SN: 781	29-May-12 (No. DAE4-781_May12)	May-13

Secondary Standards	ID #	Check Date (in house)	Scheduled Check
AMCC	1050	12-Oct-11 (in house check Oct-11)	Oct-13
AMMI Audio Measuring Instrument	1062	26-Sep-12 (in house check Sep-12)	Sep-14

Calibrated by:	Name Dimce Iliev	Function Laboratory Technician	Signature <i>D. Iliev</i>
Approved by:	Name Fin Bomholt	Function Deputy Technical Manager	Signature <i>F. Bomholt</i>

Issued: January 10, 2013

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References

- [1] ANSI C63.19-2007
American National Standard for Methods of Measurement of Compatibility between Wireless Communications Devices and Hearing Aids.
- [2] DASY5 manual, Chapter: Hearing Aid Compatibility (HAC) T-Coil Extension

Description of the AM1D probe

The AM1D Audio Magnetic Field Probe is a fully shielded magnetic field probe for the frequency range from 100 Hz to 20 kHz. The pickup coil is compliant with the dimensional requirements of [1]. The probe includes a symmetric low noise amplifier for the signal available at the shielded 3 pin connector at the side. Power is supplied via the same connector (phantom power supply) and monitored via the LED near the connector. The 7 pin connector at the end of the probe does not carry any signals, but determines the angle of the sensor when mounted on the DAE. The probe supports mechanical detection of the surface.

The single sensor in the probe is arranged in a tilt angle allowing measurement of 3 orthogonal field components when rotating the probe by 120° around its axis. It is aligned with the perpendicular component of the field, if the probe axis is tilted nominally 35.3° above the measurement plane, using the connector rotation and sensor angle stated below.

The probe is fully RF shielded when operated with the matching signal cable (shielded) and allows measurement of audio magnetic fields in the close vicinity of RF emitting wireless devices according to [1] without additional shielding.

Handling of the item

The probe is manufactured from stainless steel. In order to maintain the performance and calibration of the probe, it must not be opened. The probe is designed for operation in air and shall not be exposed to humidity or liquids. For proper operation of the surface detection and emergency stop functions in a DASY system, the probe must be operated with the special probe cup provided (larger diameter).

Methods Applied and Interpretation of Parameters

- *Coordinate System:* The AM1D probe is mounted in the DASY system for operation with a HAC Test Arch phantom with AMCC Helmholtz calibration coil according to [2], with the tip pointing to “southwest” orientation.
- *Functional Test:* The functional test preceding calibration includes test of Noise level
RF immunity (1kHz AM modulated signal). The shield of the probe cable must be well connected.
Frequency response verification from 100 Hz to 10 kHz.
- *Connector Rotation:* The connector at the end of the probe does not carry any signals and is used for fixation to the DAE only. The probe is operated in the center of the AMCC Helmholtz coil using a 1 kHz magnetic field signal. Its angle is determined from the two minima at nominally +120° and -120° rotation, so the sensor in the tip of the probe is aligned to the vertical plane in z-direction, corresponding to the field maximum in the AMCC Helmholtz calibration coil.
- *Sensor Angle:* The sensor tilting in the vertical plane from the ideal vertical direction is determined from the two minima at nominally +120° and -120°. DASY system uses this angle to align the sensor for radial measurements to the x and y axis in the horizontal plane.
- *Sensitivity:* With the probe sensor aligned to the z-field in the AMCC, the output of the probe is compared to the magnetic field in the AMCC at 1 kHz. The field in the AMCC Helmholtz coil is given by the geometry and the current through the coil, which is monitored on the precision shunt resistor of the coil.

AM1D probe identification and configuration data

Item	AM1DV3 Audio Magnetic 1D Field Probe
Type No	SP AM1 001 BA
Serial No	3067

Overall length	296 mm
Tip diameter	6.0 mm (at the tip)
Sensor offset	3.0 mm (centre of sensor from tip)
Internal Amplifier	20 dB

Manufacturer / Origin	Schmid & Partner Engineering AG, Zürich, Switzerland
Manufacturing date	February 17, 2009
Last calibration date	December 08, 2011

Calibration data

Connector rotation angle	(in DASY system)	263.9 °	+/- 3.6 ° (k=2)
Sensor angle	(in DASY system)	0.92 °	+/- 0.5 ° (k=2)
Sensitivity at 1 kHz	(in DASY system)	0.00738 V / (A/m)	+/- 2.2 % (k=2)

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor $k=2$, which for a normal distribution corresponds to a coverage probability of approximately 95%.

IMPORTANT NOTICE

USAGE OF THE DAE 4

The DAE unit is a delicate, high precision instrument and requires careful treatment by the user. There are no serviceable parts inside the DAE. Special attention shall be given to the following points:

Battery Exchange: The battery cover of the DAE4 unit is closed using a screw, over tightening the screw may cause the threads inside the DAE to wear out.

Shipping of the DAE: Before shipping the DAE to SPEAG for calibration, remove the batteries and pack the DAE in an antistatic bag. This antistatic bag shall then be packed into a larger box or container which protects the DAE from impacts during transportation. The package shall be marked to indicate that a fragile instrument is inside.

E-Stop Failures: Touch detection may be malfunctioning due to broken magnets in the E-stop. Rough handling of the E-stop may lead to damage of these magnets. Touch and collision errors are often caused by dust and dirt accumulated in the E-stop. To prevent E-stop failure, the customer shall always mount the probe to the DAE carefully and keep the DAE unit in a non-dusty environment if not used for measurements.

Repair: Minor repairs are performed at no extra cost during the annual calibration. However, SPEAG reserves the right to charge for any repair especially if rough unprofessional handling caused the defect.

DASY Configuration Files: Since the exact values of the DAE input resistances, as measured during the calibration procedure of a DAE unit, are not used by the DASY software, a nominal value of 200 MOhm is given in the corresponding configuration file.

Important Note:

Warranty and calibration is void if the DAE unit is disassembled partly or fully by the Customer.

Important Note:

Never attempt to grease or oil the E-stop assembly. Cleaning and readjusting of the E-stop assembly is allowed by certified SPEAG personnel only and is part of the annual calibration procedure.

Important Note:

To prevent damage of the DAE probe connector pins, use great care when installing the probe to the DAE. Carefully connect the probe with the connector notch oriented in the mating position. Avoid any rotational movement of the probe body versus the DAE while turning the locking nut of the connector. The same care shall be used when disconnecting the probe from the DAE.



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Accreditation No.: **SCS 108**

Client **Auden**

Certificate No: **DAE4-1305_Jan13**

CALIBRATION CERTIFICATE

Object **DAE4 - SD 000 D04 BJ - SN: 1305**

Calibration procedure(s) **QA CAL-06.v25
Calibration procedure for the data acquisition electronics (DAE)**

Calibration date: **January 08, 2013**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Keithley Multimeter Type 2001	SN: 0810278	02-Oct-12 (No:12728)	Oct-13
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Auto DAE Calibration Unit	SE UWS 053 AA 1001	07-Jan-13 (in house check)	In house check: Jan-14
Calibrator Box V2.1	SE UMS 006 AA 1002	07-Jan-13 (in house check)	In house check: Jan-14

	Name	Function	Signature
Calibrated by:	Eric Hainfeld	Technician	

Approved by:	Fin Bomholt	Deputy Technical Manager	
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Issued: January 8, 2013

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Accreditation No.: **SCS 108**

Glossary

DAE	data acquisition electronics
Connector angle	information used in DASY system to align probe sensor X to the robot coordinate system.

Methods Applied and Interpretation of Parameters

- *DC Voltage Measurement:* Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- *Connector angle:* The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters as documented in the Appendix contain technical information as a result from the performance test and require no uncertainty.
 - *DC Voltage Measurement Linearity:* Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
 - *Common mode sensitivity:* Influence of a positive or negative common mode voltage on the differential measurement.
 - *Channel separation:* Influence of a voltage on the neighbor channels not subject to an input voltage.
 - *AD Converter Values with inputs shorted:* Values on the internal AD converter corresponding to zero input voltage
 - *Input Offset Measurement:* Output voltage and statistical results over a large number of zero voltage measurements.
 - *Input Offset Current:* Typical value for information; Maximum channel input offset current, not considering the input resistance.
 - *Input resistance:* Typical value for information: DAE input resistance at the connector, during internal auto-zeroing and during measurement.
 - *Low Battery Alarm Voltage:* Typical value for information. Below this voltage, a battery alarm signal is generated.
 - *Power consumption:* Typical value for information. Supply currents in various operating modes.

DC Voltage Measurement

A/D - Converter Resolution nominal

High Range: 1LSB = 6.1 μ V, full range = -100...+300 mV

Low Range: 1LSB = 61nV, full range = -1.....+3mV

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Calibration Factors	X	Y	Z
High Range	403.769 \pm 0.02% (k=2)	403.933 \pm 0.02% (k=2)	404.254 \pm 0.02% (k=2)
Low Range	3.97987 \pm 1.55% (k=2)	3.99072 \pm 1.55% (k=2)	3.99618 \pm 1.55% (k=2)

Connector Angle

Connector Angle to be used in DASY system	118 $^{\circ}$ \pm 1 $^{\circ}$
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Appendix

1. DC Voltage Linearity

High Range	Reading (μV)	Difference (μV)	Error (%)
Channel X + Input	199995.60	-0.47	-0.00
Channel X + Input	20002.18	1.87	0.01
Channel X - Input	-19998.16	2.44	-0.01
Channel Y + Input	199996.69	0.70	0.00
Channel Y + Input	19998.39	-1.85	-0.01
Channel Y - Input	-20000.69	-0.06	0.00
Channel Z + Input	199996.70	0.67	0.00
Channel Z + Input	20000.52	0.31	0.00
Channel Z - Input	-20001.48	-0.75	0.00

Low Range	Reading (μV)	Difference (μV)	Error (%)
Channel X + Input	2000.67	-0.02	-0.00
Channel X + Input	201.91	0.58	0.29
Channel X - Input	-197.69	1.04	-0.52
Channel Y + Input	2000.52	-0.14	-0.01
Channel Y + Input	200.13	-1.11	-0.55
Channel Y - Input	-199.68	-0.94	0.47
Channel Z + Input	2000.29	-0.32	-0.02
Channel Z + Input	200.75	-0.35	-0.18
Channel Z - Input	-199.77	-0.95	0.48

2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Average Reading (μV)	Low Range Average Reading (μV)
Channel X	200	10.78	8.81
	- 200	-6.71	-8.43
Channel Y	200	-23.23	-23.66
	- 200	22.10	21.91
Channel Z	200	-10.43	-10.25
	- 200	8.56	8.72

3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Input Voltage (mV)	Channel X (μV)	Channel Y (μV)	Channel Z (μV)
Channel X	200	-	0.64	-4.03
Channel Y	200	8.66	-	2.90
Channel Z	200	11.08	5.80	-

4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	High Range (LSB)	Low Range (LSB)
Channel X	15880	16341
Channel Y	16302	17023
Channel Z	15978	15918

5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Input 10M Ω

	Average (μ V)	min. Offset (μ V)	max. Offset (μ V)	Std. Deviation (μ V)
Channel X	0.31	-0.57	1.19	0.37
Channel Y	-0.75	-1.90	0.57	0.45
Channel Z	-0.24	-1.57	1.07	0.56

6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

7. Input Resistance (Typical values for information)

	Zeroing (kOhm)	Measuring (MOhm)
Channel X	200	200
Channel Y	200	200
Channel Z	200	200

8. Low Battery Alarm Voltage (Typical values for information)

Typical values	Alarm Level (VDC)
Supply (+ Vcc)	+7.9
Supply (- Vcc)	-7.6

9. Power Consumption (Typical values for information)

Typical values	Switched off (mA)	Stand by (mA)	Transmitting (mA)
Supply (+ Vcc)	+0.01	+6	+14
Supply (- Vcc)	-0.01	-8	-9



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Accreditation No.: **SCS 108**

Client **Huawei-SZ (Auden)**

Certificate No: **TMFS_1030_Nov12**

CALIBRATION CERTIFICATE

Object / Identification **TMFS – SN: 1030**

Calibration procedure(s) **QA CAL-24.v3
Calibration procedure for AM1D magnetic field probes and TMFS in the
audio range**

Calibration date **November 21, 2012**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The calibrations have been conducted in the R&D laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Calibrated by, Certificate No.)	Scheduled Calibration
Keithley Multimeter Type 2001	SN: 0810278	02-Oct-12 (No:12728)	Oct-13
Secondary Standards	ID #	Cal / Check Date	Scheduled Calibration Check
AMCC	1050	12-Oct-11 (in house check Oct-11)	Oct-13
Reference Probe AM1DV2	SN: 1008	18-Jan-12 (No. AM1D-1008_Jan12)	Jan-13
AMMI Audio Measuring Instrument	1062	26-Sep-12 (in house check Sep-12)	Sep-14
Agilent WF Generator 33120A	MY40005266	12-Oct-11 (in house check Oct-11)	Oct-13
Keithley Multimeter Type 2001	SN: 0661047	22-Oct-12 (in house check Oct-12)	Oct-13

Calibrated by:	Name Claudio Leubler	Function Laboratory Technician	Signature
Approved by:	Name Fin Bomholt	Function R&D Director	Signature

Issued: November 21, 2012

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

References

- [1] ANSI-C63.19-2007
American National Standard for Methods of Measurement of Compatibility between Wireless Communications Devices and Hearing Aids.
- [2] DASY manual, Chapter "Hearing Aid Compatibility (HAC) T-Coil Extension"

Methods Applied and Interpretation of Parameters

- **Coordinate System:** The TMFS is mounted underneath the HAC Test Arch touching equivalently to a wireless device according to [2] 29.2.2.: In "North" orientation, the TMFS signal connector is directed to the north, with x and y axes of TMFS and Test arch coinciding (see fig. 1). The rotational symmetry axis of the TMFS is aligned to the center of the HAC test Arch. For East, South and West configuration, the TMFS has been rotated clockwise in steps of 90°, so the connector looks into the specified direction. The evaluation of the radial direction is referenced to the device orientation (x equivalent to South direction).

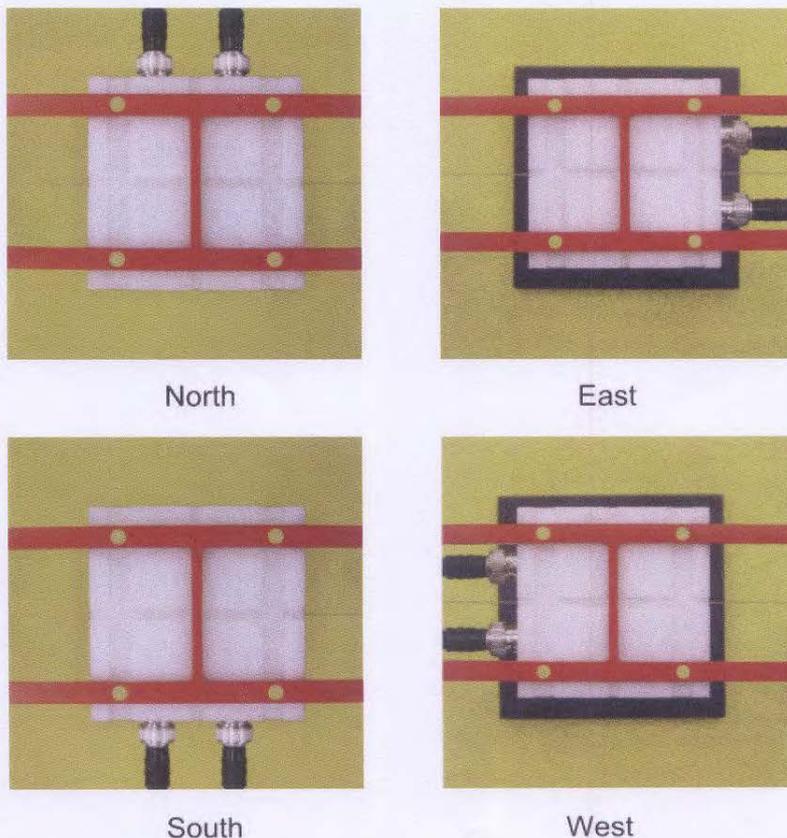


Fig. 1 TMFS scanning measurement configurations

- **Measurement Plane:** In coincidence with standard [1], the measurement plane (probe sensor center) is selected to be at a distance of 10 mm above the the surface of the TMFS touching the frame. The 50 x 50 mm scan area is aligned to the center of the unit. The scanning plane is verified to be parallel to the phantom frame before the measurements using the predefined "Geometry and signal check" procedure according to the predefined procedures described in [2].
- **Measurement Conditions:** Calibration of AM1D probe and AMMI are according to [2]. The 1 kHz sine signal for the level measurement is supplied from an external, independent generator via a BNC cable to TMFS IN and monitored at TMFS OUT with an independent RMS voltmeter or Audio Analyzer. The level is set to 0.5 Vrms and monitored during the scans.
- For the *frequency response*, a higher suppression of the background ambient magnetic field over the full frequency range was achieved by placing the TMFS in a magnetically shielded box. The AM1D probe was fixed without robot positioner near the axial maximum for this measurement. The background noise suppression was typ. 30 dB at 100 Hz (minimum) and 42 dB at 1 kHz. The predefined multisine signal (48k_multisine_50-10000_10s.wav) was used and evaluated in the third-octave bands from 100 Hz to 10000 Hz.

1 Measurement Conditions

DASY system configuration, as far as not given on page 1.

DASY Version	DASY5	V52.8.3 (988)
DASY PP Version	SEMCAD	V14.6.7 (6848)
Phantom	HAC Test Arch	SD HAC P01 BA, #1002
Distance TMFS Top - Probe Centre	10 mm	
Scan resolution	dx, dy = 5 mm	area = 50 x 50 mm
Frequency	for field scans	1 kHz
Signal level to TMFS	for field scans	500 mV RMS
Signal	for frequency response	multisine signal 50-10000 Hz, each third-octave band

Table 1: System configuration

2 Axial Maximum Field

Configuration	East	South	West	North	Subset Average	Average
Axial Max	-20.20	-20.20	-20.19	-20.20		-20.20
TMFS Y Axis 1st Max	-25.77	-25.86	-25.82	-25.81		
TMFS Y Axis 2nd Max	-26.01	-26.05	-25.90	-26.00		
Longitudinal Max Avg	-25.89	-25.96	-25.86	-25.91	-25.90	
TMFS X Axis 1st Max	-25.94	-25.88	-25.91	-25.96		
TMFS X Axis 2nd Max	-25.63	-25.65	-25.65	-25.59		
Transversal Max Avg	-25.79	-25.77	-25.78	-25.78	-25.78	
Radial Max						-25.84

Table 2: Axial and radial field maxima measured with probe center at 10mm distance in dB A/m

The maximum was calculated as the average from the values measured in the 4 orientations listed in table 2.

Axial Maximum -20.20 dB A/m (+/- 0.33dB, k=2)

3 Radial Maximum Field

In addition, the average from the 16 maxima of the radial field listed in table 2 (measured at 10mm) was calculated:

Radial Maximum -25.84 dB A/m

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

4 Appendix

4.1 Frequency response

Max. deviation measured, relative to 1 kHz: **min. -0.03, max. 0.00 dB**

Frequency [Hz]	Response [dB]
100	0.00
125	-0.01
160	0.00
200	0.00
250	-0.01
315	0.00
400	0.00
500	0.00
630	0.00
800	0.00
1000	0.00
1250	-0.01
1600	-0.01
2000	-0.01
2500	-0.01
3150	-0.01
4000	-0.02
5000	-0.02
6300	-0.02
8000	-0.03
10000	-0.03

Table 3: Frequency response

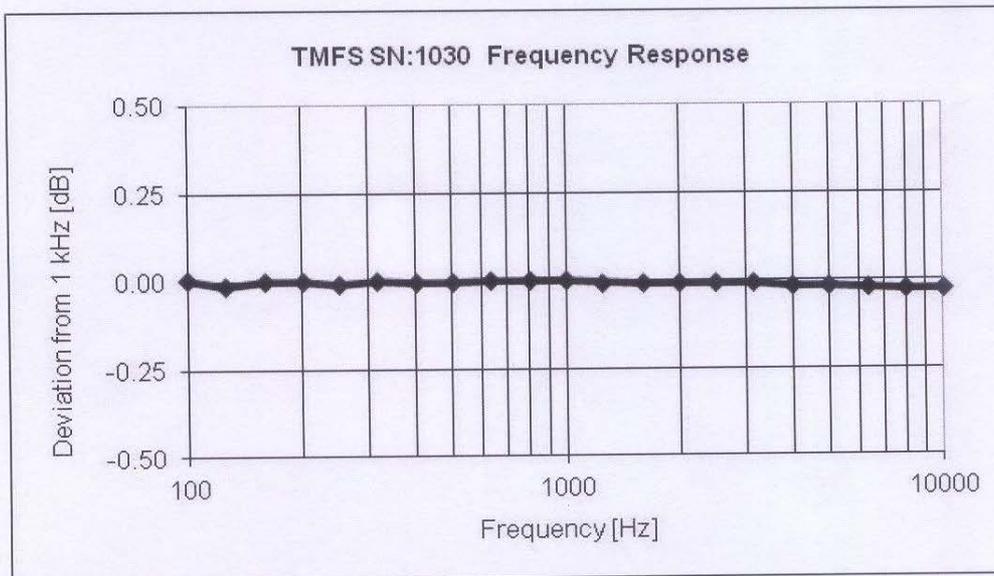


Fig. 2 Frequency response 100 to 10'000 Hz

4.2 Field plots

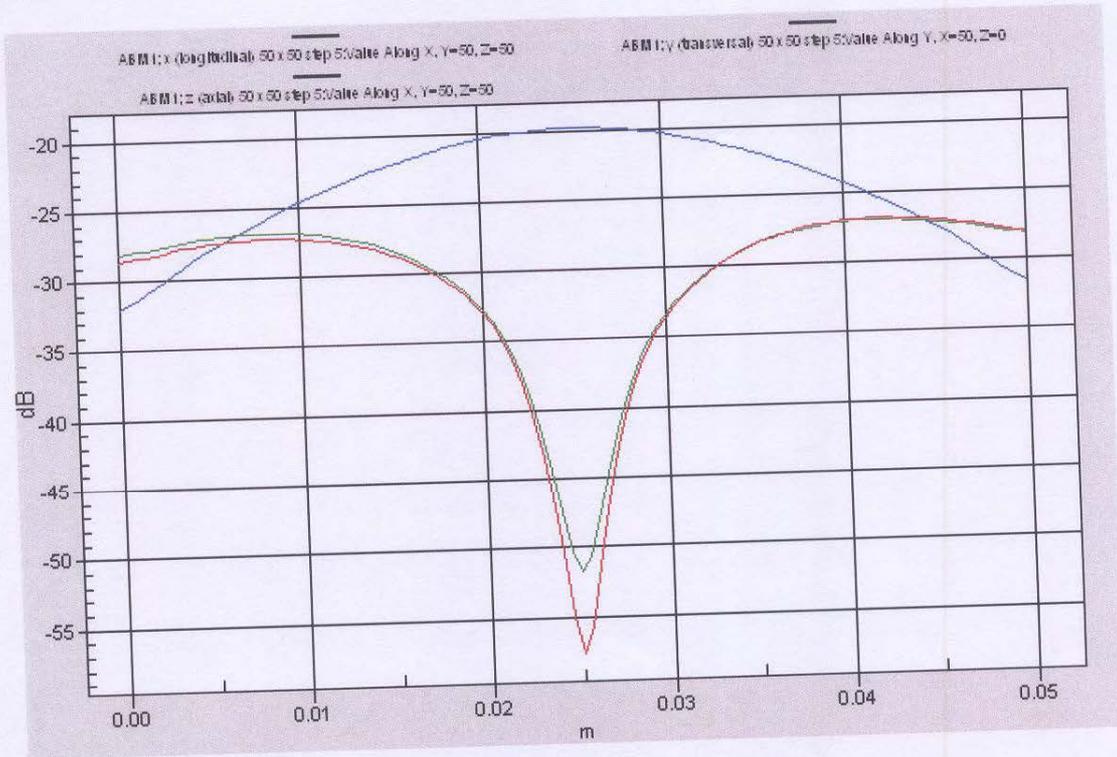


Fig. 3: Typical 2D field plots for x (red), y (green) and z (blue) components

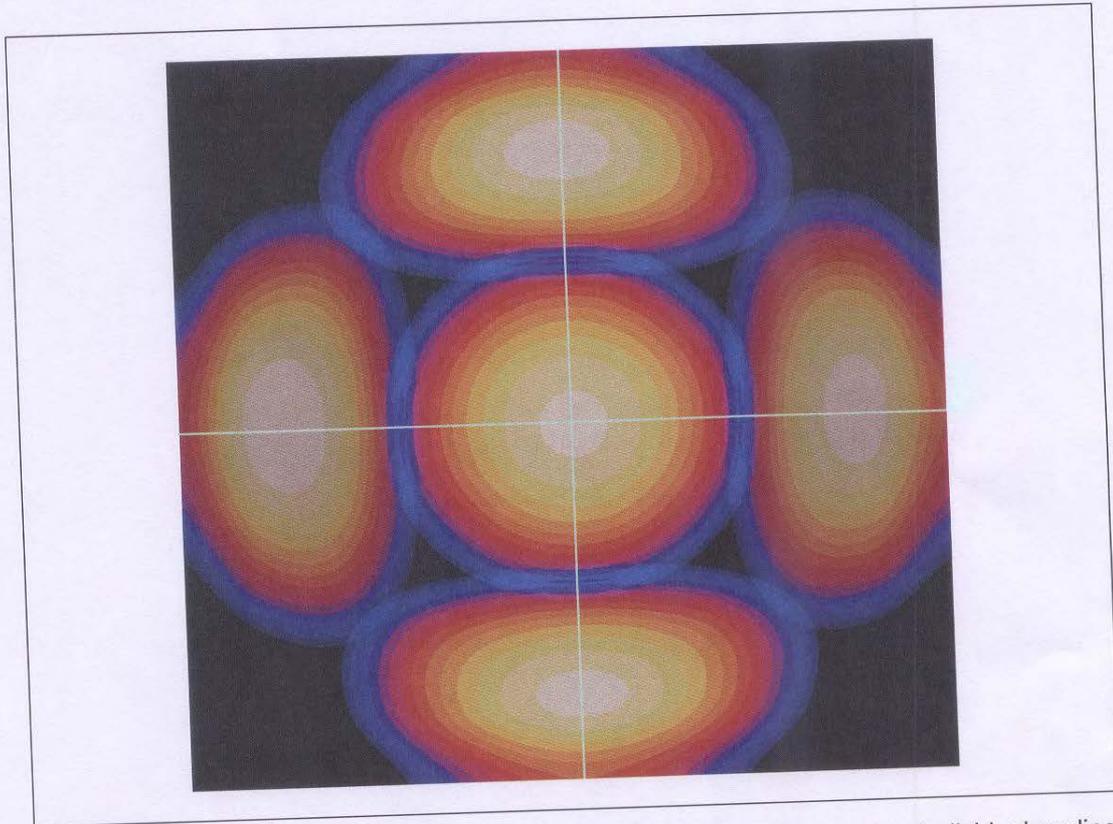


Fig. 4: Superposed field plots of z (axial), x and y radial magnetic field, 50 x 50 mm, individual scaling: white = max. field level, black = -4dB below max. The lines show the position of the 2D field plot of figure 3.