

SAR Test Report

Report No.: AGC02575200302FH01

FCC ID : 025BIT-4

APPLICATION PURPOSE : Original Equipment

PRODUCT DESIGNATION : Bluetooth Helmet Headset

BRAND NAME : ChatterBox

MODEL NAME : BiT-4

APPLICANT : Unimo Technology Co.,Ltd.

DATE OF ISSUE : Jul. 27,2020

STANDARD(S) : IEEE Std. 1528:2013
FCC 47 CFR Part 2§2.1093:2013
IEEE Std C95.1™-2005
IEC 62209-1: 2016

REPORT VERSION : V1.0

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Report Revise Record

Report Version	Revise Time	Issued Date	Valid Version	Notes
V1.0	/	Jul. 27,2020	Valid	Initial Release

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Test Report

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Factory Name	Unimo Technology Co.,Ltd.
Factory Address	4th Floor, 162 Bangbae-Ro Seocho-Gu, Seoul,Korea, 137820 South Korea
Product Designation	Bluetooth Helmet Headset
Brand Name	ChatterBox
Model Name	BiT-4
EUT Voltage	DC3.7V by battery
Applicable Standard	IEC 62209-2:2010; RSS-102 Issue 5:2015 IEC 62209-1: 2016
Test Date	Jul. 23,2020
Report Template	AGCRT-US-Bluetooth/SAR (2018-01-01)

Note: The results of testing in this report apply to the product/system which was tested only.

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Jul. 23,2020

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Jul. 27,2020

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1. SUMMARY OF MAXIMUM SAR VALUE

The maximum results of Specific Absorption Rate (SAR) found during testing for EUT are as follows:

Frequency Band	Highest Reported 1g-SAR(W/Kg) (with 0mm separation)	Highest Reported 10-g extremity SAR (W/Kg) (with 0mm separation)	SAR Test Result
Bluetooth(BR/EDR)	0.229	0.121	PASS
Simultaneous Reported SAR	0.439	0.205	
SAR Test Limit (W/Kg)	1.6	4.0	

This device is compliance with Specific Absorption Rate (SAR) for general population/uncontrolled exposure limits (1.6W/Kg&4.0W/Kg) specified in IEEE Std. 1528:2013; FCC 47CFR § 2.1093; IEEE/ANSI C95.1:2005 and the following specific FCC Test Procedures:

- KDB 447498 D01 General RF Exposure Guidance v06
- KDB 865664 D01 SAR Measurement 100MHz to 6GHz v01r04

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2. GENERAL INFORMATION

2.1. EUT Description

General Information	
Product Designation	Bluetooth Helmet Headset
Test Model	BiT-4
Hardware Version	BiT-4_V10
Software Version	ChatterBoxBiT4 V00.35
Duty cycle	77%(test mode)
Device Category	Portable
RF Exposure Environment	Uncontrolled
Antenna Type	Internal
Bluetooth	
Operation Frequency	2402~2480MHz
Antenna Gain	0dBi
Bluetooth Version	V4.1
Type of modulation	BR/EDR: GFSK, $\pi/4$ -DQPSK, 8-DPSK;
Peak Output Power	BR/EDR: Ant.1: 6.028dBm; Ant.2:12.335dBm;
Power Supply	DC 3.7V,900mAh by battery

Note: 1. The sample used for testing is end product.

2. Duty-cycle = [on time/total time] x 100%

3. The test sample has no any deviation to the test method of standard mentioned in page 1.

Product	Type
	☒ Production unit ☐ Identical Prototype

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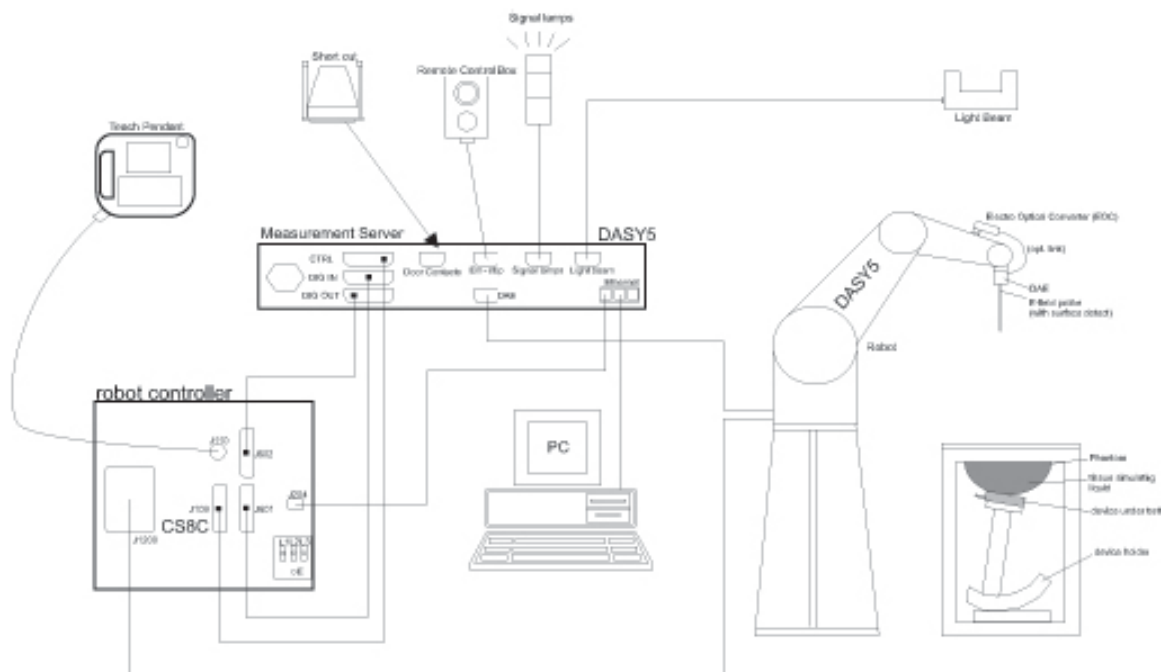
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3. SAR MEASUREMENT SYSTEM

3.1. The DASY5 system used for performing compliance tests consists of following items



- A standard high precision 6-axis robot with controller, teach pendant and software.
- Data acquisition electronics (DAE) which attached to the robot arm extension. The DAE consist of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder with a control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information, as well as an optical uplink for commands and the clock
- A dosimetric probe equipped with an optical surface detector system.
- The Electro-optical converter (EOC) performs the conversion from optical to electrical signals for the digital Communication to the DAE. To use optical surface detection, a special version of the EOC is required. The EOC signal is transmitted to the measurement server.
- A Light Beam used is for probe alignment. This improves the (absolute) accuracy of the probe positioning.
- A computer running WinXP and the DASY5 software.
- Remote control and teach pendant as well as additional circuitry for robot safety such as warning lamps, etc.
- Phantoms, device holders and other accessories according to the targeted measurement.

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3.2. DASY5 E-Field Probe

The SAR measurement is conducted with the dosimetric probe manufactured by SPEAG. The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. SPEAG conducts the probe calibration in compliance with international and national standards (e.g. IEEE-1528 etc.) Under ISO17025. The calibration data are in Appendix D.

Isotropic E-Field Probe Specification

Model	EX3DV4-SN:3953	
Manufacture	SPEAG	
frequency	0.7GHz-6GHz Linearity:±0.9%(k=2)	
Dynamic Range	0.01W/Kg-100W/Kg Linearity: ±0.9%(k=2)	
Dimensions	Overall length:337mm Tip diameter:2.5mm Typical distance from probe tip to dipole centers:1mm	
Application	High precision dosimetric measurements in any exposure scenario (e.g., very strong gradient fields). Only probe which enables compliance testing for frequencies up to 6 GHz with precision of better 30%.	

3.3. Data Acquisition Electronics description

The data acquisition electronics (DAE) consist of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder with a control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information, as well as an optical uplink for commands and the clock.

The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection.

DAE4

Input Impedance	200MΩ	
The Inputs	Symmetrical and floating	
Common mode rejection	above 80 dB	

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3.4. Robot

The DASY system uses the high precision robots (DASY5:TX60) type from Stäubli SA (France). For the 6-axis controller system, the robot controller version from is used.

The XL robot series have many features that are important for our application:

- ☐ High precision (repeatability 0.02 mm)
- ☐ High reliability (industrial design)
- ☐ Jerk-free straight movements
- ☐ Low ELF interference (the closed metallic construction shields against motor control fields)
- ☐ 6-axis controller



3.5. Light Beam Unit

The light beam switch allows automatic “tooling” of the probe. During the process, the actual position of the probe tip with respect to the robot arm is measured, as well as the probe length and the horizontal probe offset. The software then corrects all movements, such that the robot coordinates are valid for the probe tip.

The repeatability of this process is better than 0.1 mm. If a position has been taught with an aligned prob.1 mm, even if the other probe has different dimensions. During probe rotations, the probe tip will keep its actual position. e, the same position will be reached with another aligned probe within 0



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3.6. Device Holder

The DASY device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation center for both scales is the ear reference point (EPR).

Thus the device needs no repositioning when changing the angles.

The DASY device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity $\epsilon=3$ and loss tangent $\delta = 0.02$. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.



3.7. Measurement Server

The measurement server is based on a PC/104 CPU board with CPU (DASY5: 400 MHz, Intel Celeron), chip-disk (DASY5: 128MB), RAM (DASY5: 128MB). The necessary circuits for communication with the DAE electronic box, as well as the 16 bit AD converter system for optical detection and digital I/O interface are contained on the DAYS I/O board, which is directly connected to the PC/104 bus of the CPU board.

The measurement server performs all the real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operations.



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3.8. PHANTOM SAM Twin Phantom

The SAM twin phantom is a fiberglass shell phantom with 2mm shell thickness (except the ear region where shell thickness increases to 6mm). It has three measurement areas:

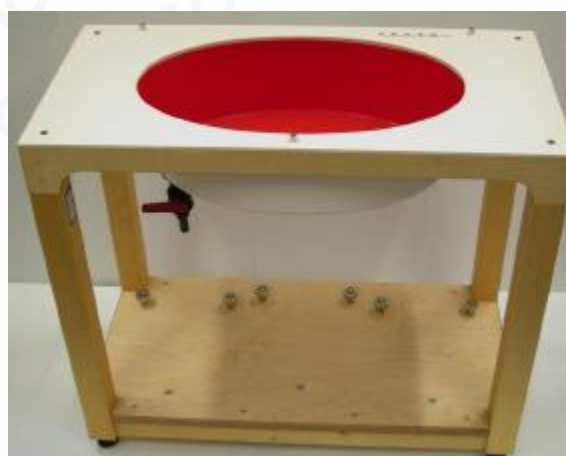
- ☐ Left head
- ☐ Right head
- ☐ Flat phantom



The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

ELI4 Phantom

- ☐ Flat phantom a fiberglass shell flat phantom with 2mm+/- 0.2 mm shell thickness. It has only one measurement area for Flat phantom



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4. SAR MEASUREMENT PROCEDURE

4.1. Specific Absorption Rate (SAR)

SAR is related to the rate at which energy is absorbed per unit mass in object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and occupational/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element(dv) of given mass density (ρ). The equation description is as below:

$$SAR = \frac{d}{dt} \left(\frac{dW}{dm} \right) = \frac{d}{dt} \left(\frac{dW}{\rho dV} \right)$$

SAR is expressed in units of Watts per kilogram (W/Kg)

SAR can be obtained using either of the following equations:

$$SAR = \frac{\sigma E^2}{\rho}$$

$$SAR = c_h \left. \frac{dT}{dt} \right|_{t=0}$$

Where

SAR	is the specific absorption rate in watts per kilogram;
E	is the r.m.s. value of the electric field strength in the tissue in volts per meter;
σ	is the conductivity of the tissue in siemens per metre;
ρ	is the density of the tissue in kilograms per cubic metre;
c _h	is the heat capacity of the tissue in joules per kilogram and Kelvin;

$\left. \frac{dT}{dt} \right|_{t=0}$ is the initial time derivative of temperature in the tissue in kelvins per second

4.2. SAR Measurement Procedure

Step 1: Power Reference Measurement

The Power Reference Measurement and Power Drift Measurement are for monitoring the power drift of the device under test in the batch process. The minimum distance of probe sensors to surface is 2.7mm This distance cannot be smaller than the distance of sensor calibration points to probe tip as defined in the probe properties,

Step 2: Area Scan

The Area Scan is used as a fast scan in two dimensions to find the area of high field values, before doing a fine measurement around the hot spot. The sophisticated interpolation routines implemented in DASY software can find the maximum locations even in relatively coarse grids. When an Area Scan has measured all reachable points, it computes the field maximal found in the scanned area, within a range of the global maximum. The range (in db) is specified in the standards for compliance testing. For example, a 2db range is required in IEEE Standard 1528, whereby 3db is a requirement when compliance is assessed in accordance with the ARIB standard (Japan) If one Zoom Scan follows the Area Scan, then only the absolute maximum will be taken as reference. For cases where multiple maximum are detected, the number of Zoom Scan has to be increased accordingly.

Area Scan Parameters extracted from KDB 865664 D01 SAR Measurement 100MHz to 6GHz

	$\leq 3 \text{ GHz}$	$> 3 \text{ GHz}$
Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface	$5 \pm 1 \text{ mm}$	$\frac{1}{2} \cdot \delta \cdot \ln(2) \pm 0.5 \text{ mm}$
Maximum probe angle from probe axis to phantom surface normal at the measurement location	$30^\circ \pm 1^\circ$	$20^\circ \pm 1^\circ$
Maximum area scan spatial resolution: $\Delta x_{\text{Area}}, \Delta y_{\text{Area}}$	$\leq 2 \text{ GHz}: \leq 15 \text{ mm}$ $2 - 3 \text{ GHz}: \leq 12 \text{ mm}$	$3 - 4 \text{ GHz}: \leq 12 \text{ mm}$ $4 - 6 \text{ GHz}: \leq 10 \text{ mm}$
	When the x or y dimension of the test device, in the measurement plane orientation, is smaller than the above, the measurement resolution must be $\leq$ the corresponding x or y dimension of the test device with at least one measurement point on the test device.	

Step 3: Zoom Scan

Zoom Scan are used to assess the peak spatial SAR value within a cubic average volume containing 1g and 10g of simulated tissue. The Zoom Scan measures points(refer to table below) within a cube whose base faces are centered on the maxima found in a preceding area scan job within the same procedure. When the measurement is done, the Zoom Scan evaluates the averaged SAR for 1g and 10g and displays these values next to the job's label.

Zoom Scan Parameters extracted from KDB865664 d01 SAR Measurement 100MHz to 6GHz

Maximum zoom scan spatial resolution: Δx_{Zoom} , Δy_{Zoom}		$\leq 2 \text{ GHz}: \leq 8 \text{ mm}$ $2 - 3 \text{ GHz}: \leq 5 \text{ mm}^*$	$3 - 4 \text{ GHz}: \leq 5 \text{ mm}^*$ $4 - 6 \text{ GHz}: \leq 4 \text{ mm}^*$
Maximum zoom scan spatial resolution, normal to phantom surface	uniform grid: $\Delta z_{Zoom}(n)$	$\leq 5 \text{ mm}$	$3 - 4 \text{ GHz}: \leq 4 \text{ mm}$ $4 - 5 \text{ GHz}: \leq 3 \text{ mm}$ $5 - 6 \text{ GHz}: \leq 2 \text{ mm}$
	graded grid	$\Delta z_{Zoom}(1)$: between 1 st two points closest to phantom surface	$3 - 4 \text{ GHz}: \leq 3 \text{ mm}$ $4 - 5 \text{ GHz}: \leq 2.5 \text{ mm}$ $5 - 6 \text{ GHz}: \leq 2 \text{ mm}$
		$\Delta z_{Zoom}(n>1)$: between subsequent points	$\leq 1.5 \cdot \Delta z_{Zoom}(n-1)$
Minimum zoom scan volume	x, y, z	$\geq 30 \text{ mm}$	$3 - 4 \text{ GHz}: \geq 28 \text{ mm}$ $4 - 5 \text{ GHz}: \geq 25 \text{ mm}$ $5 - 6 \text{ GHz}: \geq 22 \text{ mm}$
Note: δ is the penetration depth of a plane-wave at normal incidence to the tissue medium; see draft standard IEEE P1528-2011 for details. * When zoom scan is required and the <u>reported</u> SAR from the <u>area scan based 1-g SAR estimation</u> procedures of KDB 447498 is $\leq 1.4 \text{ W/kg}$, $\leq 8 \text{ mm}$, $\leq 7 \text{ mm}$ and $\leq 5 \text{ mm}$ zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.			

Step 4: Power Drift Measurement

The Power Drift Measurement measures the field at the same location as the most recent power reference measurement within the same procedure, and with the same settings. The Power Drift Measurement gives the field difference in dB from the reading conducted within the same settings. This allows a user to monitor the power drift of the device under test within a batch process. The measurement procedure is the same as Step 1.

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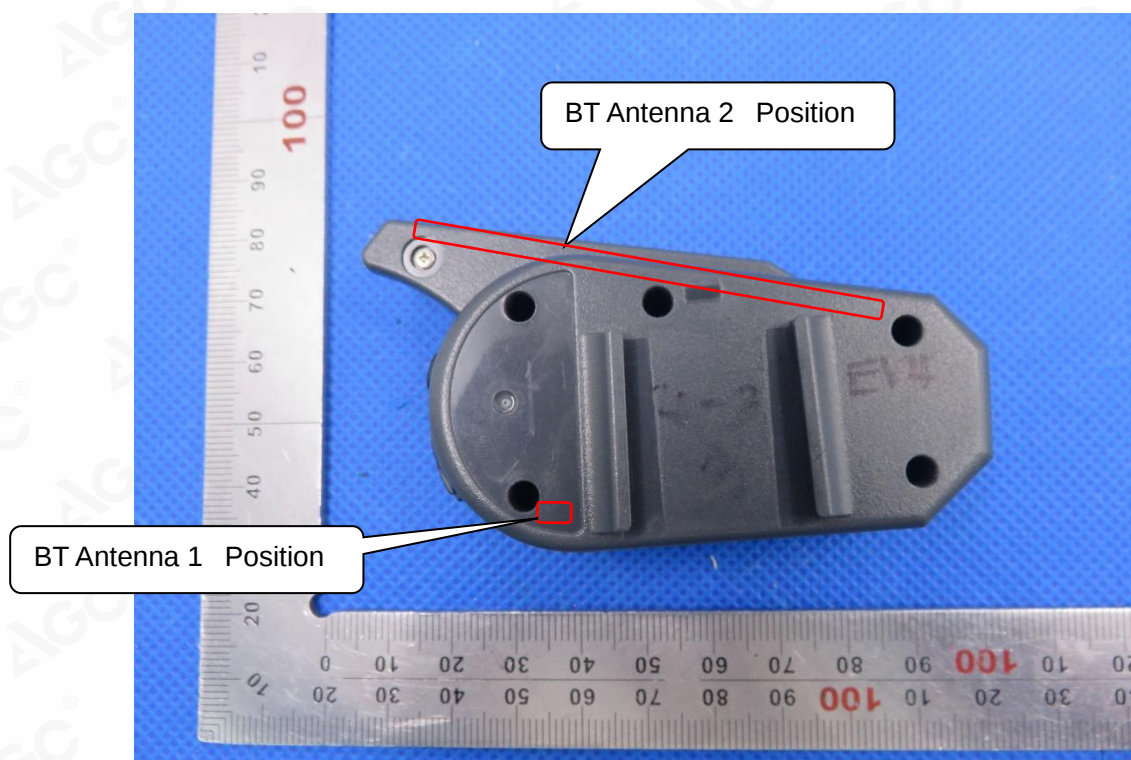
4.3. RF Exposure Conditions

Test Configuration and setting:

The device is a bluetooth headset, and supports Bluetooth wireless technology.

For SAR testing, the device was controlled by software to test at reference fixed frequency points.

Antenna Location: (the back view)



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5. TISSUE SIMULATING LIQUID

For SAR measurement of the field distribution inside the phantom, the phantom must be filled with homogeneous tissue simulating liquid to a depth of at least 15cm. For head SAR testing the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15cm. For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15cm. The nominal dielectric values of the tissue simulating liquids in the phantom and the tolerance of 10% are listed in 6.2.

5.1. The composition of the tissue simulating liquid

Ingredient (% Weight) Frequency (MHz)	Water	Nacl	Polysorbate 20	DGBE	1,2 Propanediol	Triton X-100
2450 Head	71.88	0.16	0.0	7.99	0.0	19.97

5.2. Tissue Dielectric Parameters for Head and Body Phantoms

The head tissue dielectric parameters recommended by the IEC 62209-1 have been incorporated in the following table. The body tissue dielectric parameters recommended by the IEC 62209-2 have been incorporated in the following table.

Target Frequency (MHz)	head		body	
	ϵ_r	σ (S/m)	ϵ_r	σ (S/m)
300	45.3	0.87	45.3	0.87
450	43.5	0.87	43.5	0.87
835	41.5	0.90	41.5	0.90
900	41.5	0.97	41.5	0.97
915	41.5	1.01	41.5	1.01
1450	40.5	1.20	40.5	1.20
1610	40.3	1.29	40.3	1.29
1800 – 2000	40.0	1.40	40.0	1.40
2450	39.2	1.80	39.2	1.80
3000	38.5	2.40	38.5	2.40

(ϵ_r = relative permittivity, σ = conductivity and $\rho = 1000 \text{ kg/m}^3$)

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5.3. Tissue Calibration Result

The dielectric parameters of the liquids were verified prior to the SAR evaluation using DASY 5 Dielectric Probe Kit and R&S Network Analyzer ZVL6.

Tissue Stimulant Measurement for 2450MHz					
Head	Fr. (MHz)	Dielectric Parameters ($\pm 10\%$)		Tissue Temp [°C]	Test time
		$\epsilon_r 39.2(35.28-43.12)$	$\delta [s/m] 1.80(1.62-1.98)$		
	2441	39.69	1.80	21.6	Jul. 23, 2020
	2450	38.53	1.82		

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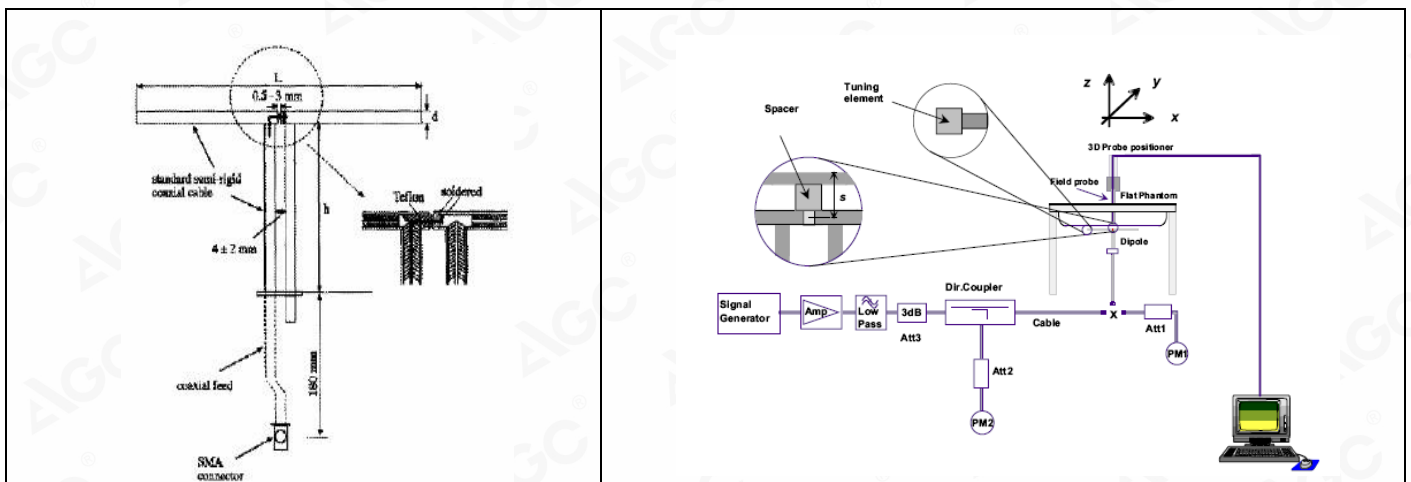
6. SAR SYSTEM CHECK PROCEDURE

6.1. SAR System Check Procedures

SAR system check is required to confirm measurement accuracy, according to the tissue dielectric media, probe calibration points and other system operating parameters required for measuring the SAR of a test device. The system verification must be performed for each frequency band and within the valid range of each probe calibration point required for testing the device. The same SAR probe(s) and tissue-equivalent media combinations used with each specific SAR system for system verification must be used for device testing. When multiple probe calibration points are required to cover substantially large transmission bands, independent system verifications are required for each probe calibration point. A system verification must be performed before each series of SAR measurements using the same probe calibration point and tissue-equivalent medium. Additional system verification should be considered according to the conditions of the tissue-equivalent medium and measured tissue dielectric parameters, typically every three to four days when the liquid parameters are remeasured or sooner when marginal liquid parameters are used at the beginning of a series of measurements.

Each DASY system is equipped with one or more system check kits. These units, together with the predefined measurement procedures within the DASY software, enable the user to conduct the system check and system validation. System kit includes a dipole, and dipole device holder.

The system check verifies that the system operates within its specifications. It's performed daily or before every SAR measurement. The system check uses normal SAR measurement in the flat section of the phantom with a matched dipole at a specified distance. The system check setup is shown as below.



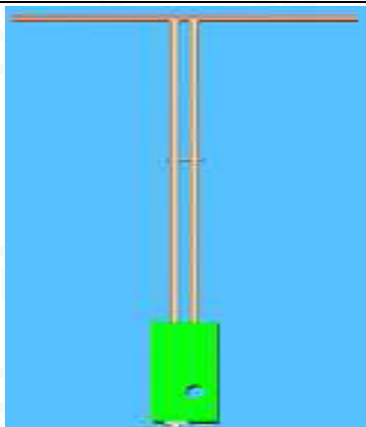
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6.2. SAR System Check

6.2.1. Dipoles

	The dipoles used are based on the IEEE-1528 standard, and is complied with mechanical and electrical specifications in line with the requirements of IEEE. the table below provides details for the mechanical and electrical specifications for the dipoles.
---	--

Frequency	L (mm)	h (mm)	d (mm)
2450MHz	51.5	30.4	3.6

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6.2.2. System Check Result

System Performance Check at 2450MHz for Head								
Validation Kit: D2450V2-SN:968								
Frequency [MHz]	Target Value(W/Kg)		Reference Result ($\pm 10\%$)		Tested Value(W/Kg)		Tissue Temp. [°C]	Test time
	1g	10g	1g	10g	1g	10g		
2450	53.6	25.0	48.24-58.96	22.50-27.50	55.15	24.25	21.6	Jul. 23,2020

Note:

(1) We use a CW signal of 18dBm for system check, and then all SAR values are normalized to 1W forward power. The result must be within $\pm 10\%$ of target value.

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7. EUT TEST POSITION

This EUT was tested in **Body back, Body front and 4Edges.**

7.1. Body Worn Position

- (1) To position the EUT parallel to the phantom surface.
- (2) To adjust the EUT parallel to the flat phantom.
- (3) To adjust the distance between the EUT surface and the flat phantom to **0mm.**

The SAR test procedure has been defined by FCC via KDB.

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8. SAR EXPOSURE LIMITS

Limits for General Population/Uncontrolled Exposure (W/kg)

Type Exposure	Uncontrolled Environment Limit (W/kg)
Spatial Peak SAR (1g cube tissue for brain or body)	1.60
Spatial Average SAR (Whole body)	0.08
Spatial Peak SAR (Limbs)	4.0

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9. TEST FACILITY

Test Site	Attestation of Global Compliance (Shenzhen) Co., Ltd
Location	1-2/F, Building 19, Junfeng Industrial Park, Chongqing Road, Heping Community, Fuhai Street, Bao'an District, Shenzhen, Guangdong, China
Designation Number	CN1259
FCC Test Firm Registration Number	975832
A2LA Cert. No.	5054.02
Description	Attestation of Global Compliance(Shenzhen) Co., Ltd is accredited by A2LA

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10. TEST EQUIPMENT LIST

Equipment description	Manufacturer/ Model	Identification No.	Current calibration date	Next calibration date
Stäubli Robot	Stäubli-TX60	F13/5Q2UD1/A/01	N/A	N/A
Robot Controller	Stäubli-CS8	139522	N/A	N/A
E-Field Probe	Speag- EX3DV4	SN:3953	Sep. 27,2019	Sep. 26,2020
SAM Twin Phantom	Speag-SAM	1790	N/A	N/A
Device Holder	Speag-SD 000 H01 KA	SD 000 H01 KA	N/A	N/A
DAE4	Speag-SD 000 D04 BM	1398	Apr. 23,2020	Apr. 22,2021
SAR Software	Speag-DASY5	DASY52.8	N/A	N/A
Liquid	SATIMO	-	N/A	N/A
Dipole	D2450V2	SN968	July 31,2018	July 30,2021
Signal Generator	Agilent-E4438C	US41461365	Oct. 08,2019	Oct. 07,2020
Vector Analyzer	Agilent / E4440A	US41421290	Sep. 09,2019	Sep. 08,2020
Network Analyzer	Rhode & Schwarz ZVL6	SN101443	Oct. 08,2019	Oct. 07,2020
Attenuator	Warison /WATT-6SR1211	S/N:WRJ34AYM2F 1	June 10, 2020	June 09, 2021
Attenuator	Mini-circuits / VAT-10+	31405	June 10, 2020	June 09, 2021
Amplifier	AS0104-55_55	1004793	June 11,2020	June 10,2021
Directional Couple	Werlatone/ C5571-10	SN99463	June 11,2020	June 10,2021
Directional Couple	Werlatone/ C6026-10	SN99482	June 11,2020	June 10,2021
Power Sensor	NRP-Z21	1137.6000.02	Sep. 09,2019	Sep. 08,2020
Power Sensor	NRP-Z23	US38261498	Feb. 18,2020	Feb. 17,2021
Power Viewer	R&S	V2.3.1.0	N/A	N/A

Note: Per KDB 865664 Dipole SAR Validation, AGC Lab has adopted 3 years calibration intervals. On annual basis, every measurement dipole has been evaluated and is in compliance with the following criteria:

1. There is no physical damage on the dipole;
2. System validation with specific dipole is within 10% of calibrated value;
3. Return-loss is within 20% of calibrated measurement;
4. Impedance is within 5Ω of calibrated measurement.

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11. MEASUREMENT UNCERTAINTY

DASY Uncertainty- EX3DV4 Measurement uncertainty for Dipole averaged over 1 gram / 10 gram.									
a	b	c	d	e f(d,k)	f	g	h c×f/e	i c×g/e	k
Uncertainty Component	Sec.	Tol (± %)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (±%)	10g Ui (±%)	vi
Measurement System									
Probe calibration	E.2.1	6.65	N	1	1	1	6.65	6.65	∞
Axial Isotropy	E.2.2	0.6	R	$\sqrt{3}$	$\sqrt{0.5}$	$\sqrt{0.5}$	0.24	0.24	∞
Hemispherical Isotropy	E.2.2	1.6	R	$\sqrt{3}$	$\sqrt{0.5}$	$\sqrt{0.5}$	0.65	0.65	∞
Boundary effect	E.2.3	1.0	R	$\sqrt{3}$	1	1	0.58	0.58	∞
Linearity	E.2.4	0.45	R	$\sqrt{3}$	1	1	0.26	0.26	∞
System detection limits	E.2.4	1.0	R	$\sqrt{3}$	1	1	0.58	0.58	∞
Modulation response 调制响应	E.2.5	3.3	R	$\sqrt{3}$	1	1	1.91	1.91	∞
Readout Electronics	E.2.6	0.15	N	1	1	1	0.15	0.15	∞
Response Time	E.2.7	0	R	$\sqrt{3}$	1	1	0	0	∞
Integration Time	E.2.8	1.7	R	$\sqrt{3}$	1	1	0.98	0.98	∞
RF ambient conditions-Noise	E.6.1	3.0	R	$\sqrt{3}$	1	1	1.73	1.73	∞
RF ambient conditions-reflections	E.6.1	3.0	R	$\sqrt{3}$	1	1	1.73	1.73	∞
Probe positioner mechanical tolerance	E.6.2	0.4	R	$\sqrt{3}$	1	1	0.37	0.37	∞
Probe positioning with respect to phantom shell	E.6.3	6.7	R	$\sqrt{3}$	1	1	3.87	3.87	∞
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	4	R	$\sqrt{3}$	1	1	2.31	2.31	∞
Test sample Related									
Test sample positioning	E.4.2	2.9	N	1	1	1	2.90	2.90	∞
Device holder uncertainty	E.4.1	3.6	N	1	1	1	3.60	3.60	∞
Output power variation—SAR drift measurement	E.2.9	5	R	$\sqrt{3}$	1	1	2.89	2.89	∞
SAR scaling	E.6.5	5	R	$\sqrt{3}$	1	1	2.89	2.89	∞
Phantom and tissue parameters									
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	6.6	R	$\sqrt{3}$	1	1	3.81	3.81	∞
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1	1	0.84	1.90	1.60	∞
Liquid conductivity measurement	E.3.3	4	N	1	0.78	0.71	3.12	2.84	M
Liquid permittivity measurement	E.3.3	5	N	1	0.23	0.26	1.15	1.30	M
Liquid conductivity—temperature uncertainty	E.3.4	2.5	R	$\sqrt{3}$	0.78	0.71	1.13	1.02	∞
Liquid permittivity—temperature uncertainty	E.3.4	2.5	R	$\sqrt{3}$	0.23	0.26	0.33	0.38	∞
Combined Standard Uncertainty			RSS				11.80	11.635	
Expanded Uncertainty (95% Confidence interval)			K=2				23.60	23.27	

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DASY Uncertainty- EX3DV4 System Check uncertainty for Dipole averaged over 1 gram / 10 gram.									
a	b	c	d	e f(d,k)	f	g	h c×f/e	i c×g/e	k
Uncertainty Component	Sec.	Tol (± %)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (±%)	10g Ui (±%)	vi
Measurement System									
Probe calibration drift	E.2.1	0.5	N	1	1	1	0.5	0.5	∞
Axial Isotropy	E.2.2	0.6	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Hemispherical Isotropy	E.2.2	1.6	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Boundary effect	E.2.3	1.0	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Linearity	E.2.4	0.45	R	$\sqrt{3}$	0	0	0.00	0.00	∞
System detection limits	E.2.4	1.0	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Modulation response	E.2.5	3.3	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Readout Electronics	E.2.6	0.15	N	1	0	0	0.00	0.00	∞
Response Time	E.2.7	0	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Integration Time	E.2.8	1.7	R	$\sqrt{3}$	0	0	0.00	0.00	∞
RF ambient conditions-Noise	E.6.1	3.0	R	$\sqrt{3}$	0	0	0.00	0.00	∞
RF ambient conditions-reflections	E.6.1	3.0	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Probe positioner mechanical tolerance	E.6.2	0.4	R	$\sqrt{3}$	1	1	0.37	0.37	∞
Probe positioning with respect to phantom shell	E.6.3	6.7	R	$\sqrt{3}$	1	1	3.87	3.87	∞
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	4	R	$\sqrt{3}$	0	0	0.00	0.00	∞
System check source (dipole)									
Deviation of experimental dipoles	E.6.4	2.0	N	1	1	1	2.00	2.00	∞
Input power and SAR drift measurement	8,6.6.4	5.0	R	$\sqrt{3}$	1	1	2.89	2.89	∞
Dipole axis to liquid distance	8,E.6.6	2.0	R	$\sqrt{3}$	1	1	1.15	1.15	∞
Phantom and tissue parameters									
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	6.6	R	$\sqrt{3}$	1	1	3.81	3.81	∞
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1	1	0.84	1.90	1.60	∞
Liquid conductivity measurement	E.3.3	4	N	1	0.78	0.71	3.12	2.84	M
Liquid permittivity measurement	E.3.3	5	N	1	0.23	0.26	1.15	1.30	M
Liquid conductivity—temperature uncertainty	E.3.4	2.5	R	$\sqrt{3}$	0.78	0.71	1.13	1.02	∞
Liquid permittivity—temperature uncertainty	E.3.4	2.5	R	$\sqrt{3}$	0.23	0.26	0.33	0.38	∞
Combined Standard Uncertainty			RSS				7.344	7.076	
Expanded Uncertainty (95% Confidence interval)			K=2				14.689	14.153	

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DASY Uncertainty- EX3DV4 System Validation uncertainty for Dipole averaged over 1 gram / 10 gram.									
a	b	c	d	e f(d,k)	f	g	h cxf/e	i cxg/e	k
Uncertainty Component	Sec.	Tol (±%)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (±%)	10g Ui (±%)	vi
Measurement System									
Probe calibration	E.2.1	6.65	N	1	1	1	6.65	6.65	∞
Axial Isotropy	E.2.2	0.6	R	$\sqrt{3}$	1	1	0.35	0.35	∞
Hemispherical Isotropy	E.2.2	1.6	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Boundary effect	E.2.3	1.0	R	$\sqrt{3}$	1	1	0.58	0.58	∞
Linearity	E.2.4	0.45	R	$\sqrt{3}$	1	1	0.26	0.26	∞
System detection limits	E.2.4	1.0	R	$\sqrt{3}$	1	1	0.58	0.58	∞
Modulation response	E.2.5	3.3	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Readout Electronics	E.2.6	0.15	N	1	1	1	0.15	0.15	∞
Response Time	E.2.7	0	R	$\sqrt{3}$	0	0	0.00	0.00	∞
Integration Time	E.2.8	1.7	R	$\sqrt{3}$	0	0	0.00	0.00	∞
RF ambient conditions-Noise	E.6.1	3.0	R	$\sqrt{3}$	1	1	1.73	1.73	∞
RF ambient conditions-reflections	E.6.1	3.0	R	$\sqrt{3}$	1	1	1.73	1.73	∞
Probe positioner mechanical tolerance	E.6.2	0.4	R	$\sqrt{3}$	1	1	0.37	0.37	∞
Probe positioning with respect to phantom shell	E.6.3	6.7	R	$\sqrt{3}$	1	1	3.87	3.87	∞
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	4	R	$\sqrt{3}$	1	1	2.31	2.31	∞
System check source (dipole)									
Deviation of experimental dipole from numerical dipole	E.6.4	5.0	N	1	1	1	5.00	5.00	∞
Input power and SAR drift measurement	8,6.6.4	5.0	R	$\sqrt{3}$	1	1	2.89	2.89	∞
Dipole axis to liquid distance	8,E.6.6	2.0	R	$\sqrt{3}$	1	1	1.15	1.15	∞
Phantom and tissue parameters									
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	6.6	R	$\sqrt{3}$	1	1	3.81	3.81	∞
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1	1	0.84	1.90	1.60	∞
Liquid conductivity measurement	E.3.3	4	N	1	0.78	0.71	3.12	2.84	M
Liquid permittivity measurement	E.3.3	5	N	1	0.23	0.26	1.15	1.30	M
Liquid conductivity—temperature uncertainty	E.3.4	2.5	R	$\sqrt{3}$	0.78	0.71	1.13	1.02	∞
Liquid permittivity—temperature uncertainty	E.3.4	2.5	R	$\sqrt{3}$	0.23	0.26	0.33	0.38	∞
Combined Standard Uncertainty			RSS				11.451	11.281	
Expanded Uncertainty (95% Confidence interval)			K=2				22.901	22.561	

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12. CONDUCTED POWER MEASUREMENT

Bluetooth_V3.0 (BR/EDR)

Modulation	Channel	Frequency(MHz)	Peak Power (dBm)-Ant.1	Peak Power (dBm)-Ant.2
GFSK	0	2402	0.435	10.633
	39	2441	2.861	11.151
	78	2480	4.843	12.335
$\pi/4$ -DQPSK	0	2402	1.521	10.452
	39	2441	3.902	11.006
	78	2480	5.732	12.152
8-DPSK	0	2402	1.926	10.373
	39	2441	4.237	10.922
	78	2480	6.028	11.973

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13. TEST RESULTS

13.1. SAR Test Results Summary

13.1.1. Test position and configuration

1. The EUT is a bluetooth earphone.
2. Based on FCC guidance, use a non-standard setting for SAR testing. The operating instructions contain additional information:
According to KDB 447498 D01 General RF Exposure Guide v06, due to maximum peak power for Ant.2 of bluetooth is more than just a test exclusion threshold, which must be tested.
3. And an inquiry about SAR test method is request:
 - (1) For 1g SAR and 10-g extremity SAR, Lab. use the head liquid with a separation of 0mm at flat phantom to test back, front and 4 edges.
 4. For SAR testing, the device was controlled by software to test at reference fixed frequency points.
 5. According to KDB 447498 D01, annex A, SAR is not required for Ant.1 of bluetooth because its maximum output power is less than 10 mW.

13.1.2. Operation Mode

1. Per KDB 447498 D01 v06 ,for each exposure position, if the highest 1-g SAR is ≤ 0.8 W/kg, testing for low and high channel is optional.
2. Per KDB 865664 D01 v01r04,for each frequency band, if the measured SAR is ≥ 0.8 W/Kg, testing for repeated SAR measurement is required , that the highest measured SAR is only to be tested. When the SAR results are near the limit, the following procedures are required for each device to verify these types of SAR measurement related variation concerns by repeating the highest measured SAR configuration in each frequency band.
 - (1) When the original highest measured SAR is ≥ 0.8 W/Kg, repeat that measurement once.
 - (2) Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is >1.20 or when the original or repeated measurement is ≥ 1.45 W/Kg.
 - (3) Perform a third repeated measurement only if the original, first and second repeated measurement is ≥ 1.5 W/Kg and ratio of largest to smallest SAR for the original, first and second measurement is ≥ 1.20 .
3. Maximum Scaling SAR in order to calculate the Maximum SAR values to test under the standard Peak Power, Calculation method is as follows:
Maximum Scaling SAR =tested SAR (Max.) $\times$ [maximum turn-up power (mw)/ maximum measurement output power(mw)]

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13.1.3. Test Result

SAR MEASUREMENT									
Depth of Liquid (cm):>15					Relative Humidity (%): 57.4				
Product: Bluetooth Helmet Headset									
Test Mode: Bluetooth for head liquid-Ant. 2									
Position	Mode	Ch.	Fr. (MHz)	Power Drift (<±0.2dB)	SAR (1g) (W/kg)	Max. Tune-up Power (dBm)	Meas. output Power (dBm)	Scaled SAR (W/Kg)	Limit W/kg
Body back	1DH5	39	2441	0.16	0.103	12.400	11.151	0.137	1.6
Body front	1DH5	39	2441	-0.14	0.024	12.400	11.151	0.032	1.6
Edge1	1DH5	39	2441	/	<0.001	12.400	11.151	<0.001 #	1.6
Edge2	1DH5	39	2441	0.06	0.022	12.400	11.151	0.029	1.6
Edge3	1DH5	39	2441	-0.09	0.020	12.400	11.151	0.027	1.6
Edge4	1DH5	39	2441	-0.13	0.172	12.400	11.151	0.229	1.6

Note:

- When the 1-g SAR is ≤ 0.8W/kg, testing for low and high channel is optional.
- The test separation of all above table is 0mm.
- Due the antenna location and antenna performance results much lower SAR result ,and lower than the lowest system limit, then we show "<0.001W/Kg" in the report ;

SAR MEASUREMENT									
Depth of Liquid (cm):>15					Relative Humidity (%): 57.4				
Product: Bluetooth Helmet Headset									
Test Mode: Bluetooth for head liquid-Ant. 2									
Position	Mode	Ch.	Fr. (MHz)	Power Drift (<±0.2dB)	10-g extremity SAR (W/kg)	Max. Tune-up Power (dBm)	Meas. output Power (dBm)	Scaled SAR (W/Kg)	Limit W/kg
Body back	1DH5	39	2441	0.16	0.068	12.400	11.151	0.091	4.0
Body front	1DH5	39	2441	-0.14	0.019	12.400	11.151	0.025	4.0
Edge1	1DH5	39	2441	/	<0.001	12.400	11.151	<0.001 #	4.0
Edge2	1DH5	39	2441	0.06	0.019	12.400	11.151	0.025	4.0
Edge3	1DH5	39	2441	-0.09	0.019	12.400	11.151	0.025	4.0
Edge4	1DH5	39	2441	-0.13	0.091	12.400	11.151	0.121	4.0

Note:

- The test separation of all above table is 0mm.
- Due the antenna location and antenna performance results much lower SAR result ,and lower than the lowest system limit, then we show "<0.001W/Kg" in the report ;

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Simultaneous Multi-band Transmission Evaluation:

Application Simultaneous Transmission information:

NO	Simultaneous state	Portable Handset
1	Bluetooth-Ant.1+ Bluetooth-Ant.2	Yes

- KDB 447498 D01, BT SAR is excluded as below table.
- According to KDB 447498 D01 4.3.1, Standalone SAR test exclusion is as follow:
For 100 MHz to 6 GHz and test separation distances ≤ 50 mm, the 1-g and 10-g SAR test exclusion thresholds are determined by the following:

$$[(\text{max. power of channel, including tune-up tolerance, mW}) / (\text{min. test separation distance, mm})] \cdot [\sqrt{f(\text{GHz})}] \leq 3.0$$
for 1-g SAR, and ≤ 7.5 for 10-g extremity SAR³⁰, where
 $f(\text{GHz})$ is the RF channel transmit frequency in GHz
 ·Power and distance are rounded to the nearest mW and mm before calculation³¹
 ·The result is rounded to one decimal place for comparison
 ·The values 3.0 and 7.5 are referred to as numeric thresholds in step b) below
 The test exclusions are applicable only when the minimum test separation distance is ≤ 50 mm, and for transmission frequencies between 100 MHz and 6 GHz. When the minimum test separation distance is < 5 mm, a distance of 5 mm according to 4.1 f) is applied to determine SAR test exclusion.
- If the test separation distance is < 5 mm, 5mm is used for excluded SAR calculation.
- According to KDB 447498 D01 4.3.2, simultaneous transmission SAR test exclusion is as follow:
 - Simultaneous transmission SAR test exclusion is determined for each operating configuration and exposure condition according to the reported standalone SAR of each applicable simultaneous transmitting antenna.
 - Any transmitters and antennas should be considered when calculating simultaneous mode.
 - For mobile phone and PC, it's the sum of all transmitters and antennas at the same mode with same position in each applicable exposure condition
 - When the standalone SAR test exclusion of section 4.3.2 is applied to an antenna that transmits simultaneously with other antennas, the standalone SAR must be estimated according to the following to det

$$[(\text{max. power of channel, including tune-up tolerance, mW}) / (\text{min. test separation distance, mm})] \cdot [\sqrt{f(\text{GHz})} / x] \text{ W/kg}$$
for test separation distances ≤ 50 mm;
 where $x = 7.5$ for 1-g SAR, and $x = 18.75$ for 10-g extremity SAR.

Estimated SAR	Max Power including Tune-up Tolerance		Separation Distance (mm)	Estimated SAR (W/kg)
	dBm	mW		
BT-Ant.1 for 1-g SAR	7	5.012	0	0.210
BT-Ant.1 for 10-g extremity SAR	7	5.012	0	0.084

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RF Exposure Conditions	Test Position	Simultaneous Transmission Scenario		Σ 1-g SAR (W/Kg)	SPLSR (Yes/No)
		Bluetooth-Ant.1	Bluetooth-Ant.2		
Hotspot	Rear	0.210	0.137	0.347	No
	Front	0.210	0.032	0.242	No
	Edge 1	0.210	--	0.210	No
	Edge 2	0.210	0.029	0.239	No
	Edge 3	0.210	0.027	0.237	No
	Edge 4	0.210	0.229	0.439	No

Note:

- According to KDB 447498 D01 General RF Exposure Guidance, when the simultaneous transmission SAR is less than 1.6 W/Kg, SPLSR assessment is not required.
- SPLSR mean is "The SAR to Peak Location Separation Ratio "

RF Exposure Conditions	Test Position	Simultaneous Transmission Scenario		Σ 10-g extremity SAR (W/Kg)	SPLSR (Yes/No)
		Bluetooth-Ant.1	Bluetooth-Ant.2		
Hotspot	Rear	0.084	0.091	0.175	No
	Front	0.084	0.025	0.109	No
	Edge 1	0.084	--	0.084	No
	Edge 2	0.084	0.025	0.109	No
	Edge 3	0.084	0.025	0.109	No
	Edge 4	0.084	0.121	0.205	No

Note:

- According to KDB 447498 D01 General RF Exposure Guidance, when the simultaneous transmission SAR is less than 4.0 W/Kg, SPLSR assessment is not required.
- SPLSR mean is "The SAR to Peak Location Separation Ratio "

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APPENDIX A. SAR SYSTEM CHECK DATA

Test Laboratory: AGC Lab

Date: Jul. 23,2020

System Check Head 2450 MHz

DUT: Dipole 2450 MHz Type: D2450V2

Communication System CW; Communication System Band: D2450 (2450.0 MHz); Duty Cycle: 1:1;
Frequency: 2450 MHz; Medium parameters used: $f = 2450$ MHz; $\sigma = 1.82$ mho/m; $\epsilon_r = 38.53$; $\rho = 1000$ kg/m³ ;
Phantom section: Flat Section; Input Power=18dBm
Ambient temperature (°C): 21.8, Liquid temperature (°C): 21.6

DASY Configuration:

- Probe: EX3DV4 – SN:3953; ConvF(7.75, 7.75, 7.75); Calibrated: Sep. 27,2019;
- Sensor-Surface: 1.4mm (Mechanical Surface Detection), $z = 1.0, 31.0$
- Electronics: DAE4 SN1398; Calibrated: Apr. 23,2020
- Phantom: SAM (20deg probe tilt) with CRP v5.0; Type: QD000P40CD;
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

Configuration/System Check Head 2450Hz/Area Scan (7x10x1): Measurement grid: dx=15mm, dy=15mm
Maximum value of SAR (measured) = 3.57 W/kg

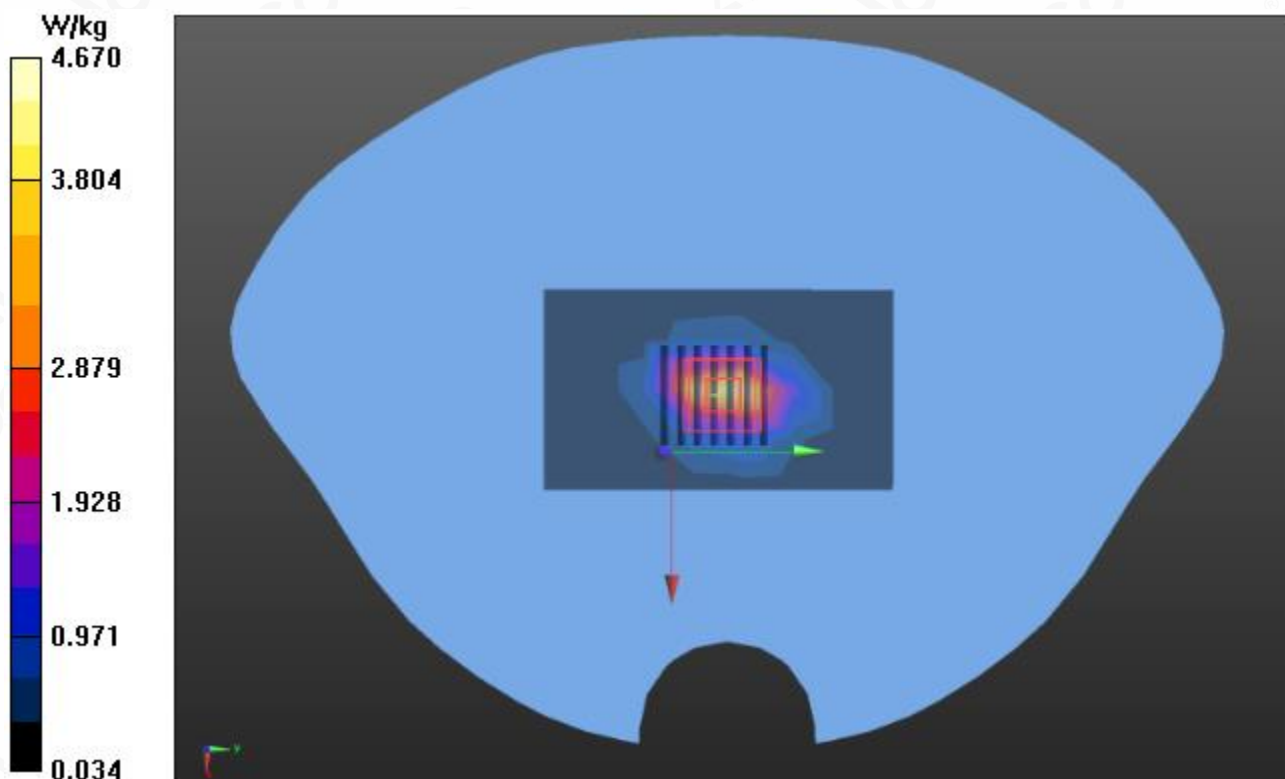
Configuration/System Check Head 2450Hz/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 48.057 V/m; Power Drift = -0.12 dB

Peak SAR (extrapolated) = 7.46 W/kg

SAR(1 g) = 3.48 W/kg; SAR(10 g) = 1.53 W/kg

Maximum value of SAR (measured) = 4.67 W/kg



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APPENDIX B. SAR MEASUREMENT DATA

Test Laboratory: AGC Lab

Date: Jul. 23,2020

Bluetooth Mid- Edge4 (1DH5)

DUT: Bluetooth Helmet Headset; Type: BiT-4

Communication System: Bluetooth; Communication System Band: Bluetooth; Duty Cycle: 77%;
Frequency: 2441 MHz; Medium parameters used: $f = 2450$ MHz; $\sigma = 1.80$ mho/m; $\epsilon_r = 39.69$; $\rho = 1000$ kg/m³ ;
Phantom section: Flat Section
Ambient temperature (°C): 21.8, Liquid temperature (°C):21.6

DASY Configuration:

- Probe: EX3DV4 – SN:3953; ConvF(7.75, 7.75, 7.75); Calibrated: Sep. 27,2019;
- Sensor-Surface: 3mm (Mechanical Surface Detection), $z = 1.0, 31.0$
- Electronics: DAE4 SN1398; Calibrated: Apr. 23,2020
- Phantom: SAM (20deg probe tilt) with CRP v5.0; Type: QD000P40CD;
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

BODY/4/Area Scan (8x14x1): Measurement grid: $dx=10$ mm, $dy=10$ mm
Maximum value of SAR (measured) = 0.225 W/kg

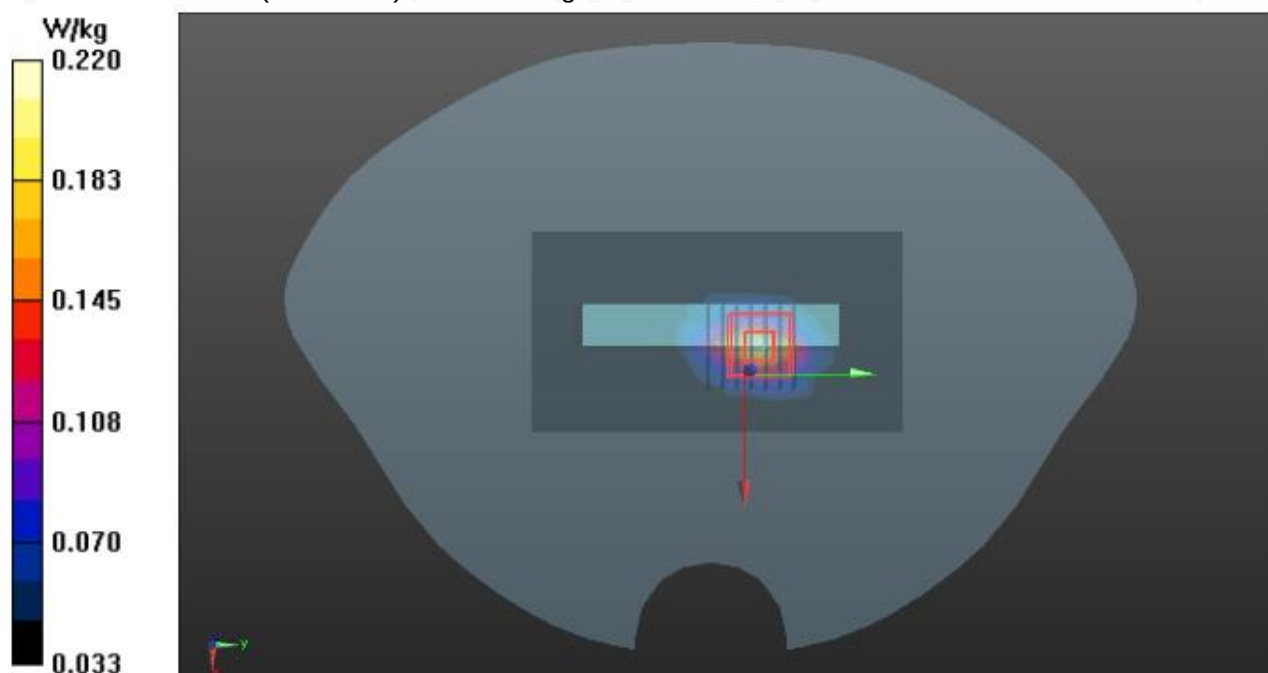
BODY/4/Zoom Scan (7x7x7)/Cube 0: Measurement grid: $dx=5$ mm, $dy=5$ mm, $dz=5$ mm

Reference Value = 8.483 V/m; Power Drift = -0.13 dB

Peak SAR (extrapolated) = 0.392 W/kg

SAR(1 g) = 0.172 W/kg; SAR(10 g) = 0.091 W/kg

Maximum value of SAR (measured) = 0.220 W/kg



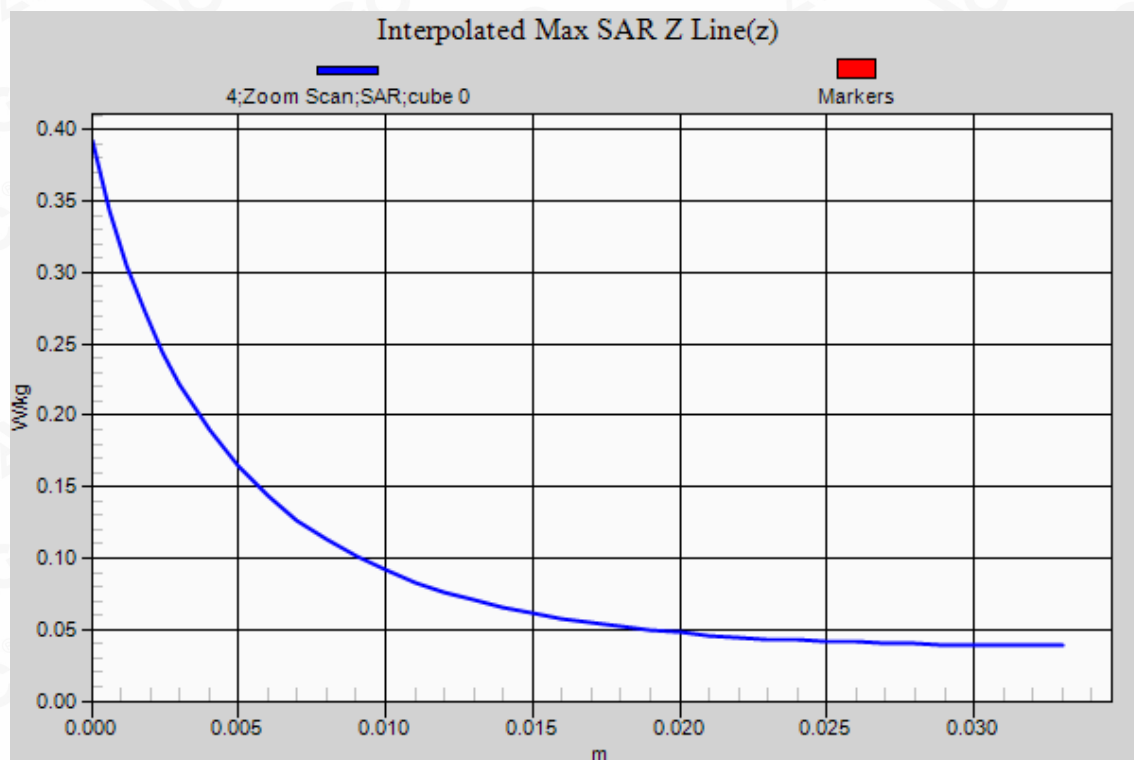
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APPENDIX C. TEST SETUP PHOTOGRAPHS

Body Back 0mm



Body Front 0mm



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Edge2-0mm



Edge3-0mm



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Edge4-0mm



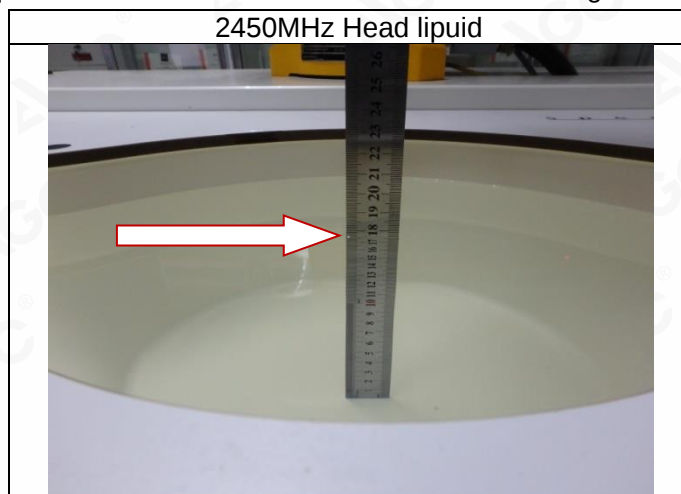
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DEPTH OF THE LIQUID IN THE PHANTOM—ZOOM IN

Note : The position used in the measurement were according to IEEE 1528-2013



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APPENDIX D. CALIBRATION DATA

Refer to Attached files.

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2. Any report issued by Company as a result of this application for testing services (the “Report”) shall be issued in confidence to the Clients and the Report will be strictly treated as such by the Company. It may not be reproduced either in its entirety or in part and it may not be used for advertising or other unauthorized purposes without the written consent of the Company. The Clients to whom the Report is issued may, however, show or send it, or a certified copy thereof prepared by the Company to its customer, supplier or other persons directly concerned. The Company will not, without the consent of the Clients, enter into any discussion or correspondence with any third party concerning the contents of the Report, unless required by the relevant governmental authorities, laws or court orders.
3. The Company shall not be called or be liable to be called to give evidence or testimony on the Report in a court of law without its prior written consent, unless required by the relevant governmental authorities, laws or court orders.
4. The non-CMA report issued by AGC is only permitted to be used by the client as internal reference use and shall not be used for public demonstration purpose.
5. In the event of the improper use of the report as determined by the Company, the Company reserves the right to withdraw it, and to adopt any other additional remedies which may be appropriate.
6. Samples submitted for testing are accepted on the understanding that the Report issued cannot form the basis of, or be the instrument for, any legal action against the Company.
7. The Company will not be liable for or accept responsibility for any loss or damage however arising from the use of information contained in any of its Reports or in any communication whatsoever about its said tests or investigations.
8. Clients wishing to use the Report in court proceedings or arbitration shall inform the Company to that effect prior to submitting the sample for testing.
9. The Company is not responsible for recalling the electronic version of the original report when any revision is made to them. The Client assumes the responsibility to providing the revised version to any interested party who uses them.
10. Subject to the variable length of retention time for test data and report stored hereinto as otherwise specifically required by individual accreditation authorities, the Company will only keep the supporting test data and information of the test report for a period of six years. The data and information will be disposed of after the aforementioned retention period has elapsed. Under no circumstances shall we provide any data and information which has been disposed of after retention period. Under no circumstances shall we be liable for damage of any kind, including (but not limited to) compensatory damages, lost profits, lost data, or any form of special, incidental, indirect, consequential or punitive damages of any kind, whether based on breach of contract of warranty, tort (including negligence), product liability or otherwise, even if we are informed in advance of the possibility of such damages.

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