PARTS LIST AND TUNE UP PROCEDURES

(CONFIDENTIALITY REQUESTED)

This exhibit contains a list of the semiconductor devices used in the transceiver and the test equipment and tuning procedures for maintaining the transceiver.

EXHIBIT 10A Function of RF Semiconductors and Other Active Devices

EXHIBIT 10B List of Recommended Test Equipment for Servicing

EXHIBIT 10C Tune Up Procedure

Exhibit 10A – Function of RF Semiconductors and Other Active Devices

Pursuant to 47 CFR 2.1033(c)(10)

D100	Reference #	Part #	Circuit Application	Operating Freq.	Industry Equivalent
D102	D100	4813833C02	DC Switch	DC	MMBD6100
D103	D101	4813833C02	DC Switch	DC	MMBD6100
D104	D102	4813833C02	DC Switch	DC	MMBD6100
D105	D103	4802482J02	Antenna Switch	438-470MHz	MA4P959
D106	D104	4802482J02	Antenna Switch	438-470MHz	MA4P959
D107	D105	4805218N57	Reverse Volt. Peak Detector	DC	RB715F
D108	D106	4805218N57	Reverse Volt. Peak Detector	DC	RB715F
D200 4802233J09 Voltage Multiplier 1.05MHz IMN10 D201 4802233J09 Voltage Multiplier 1.05MHz IMN10 D202 4802824C03 Crystal Warp DC 1SV232 D203 4805649Q13 TX VCO Frequency Control 393-425MHz 1SV228 D204 4805649Q13 TX VCO Frequency Control 438-470MHz 1SV228 D205 4862824C01 TX VCO Modulator Audio-470MHz 1SV229 D400 4813833C07 Steering Diode DC MMBD7000 D401 4813833C07 Steering Diode DC MMBD7000 Q100 4886163B01 TX RF Power Amplifier 438-470MHz MRF1535 Q101 4813824A10 DC Switch DC MMBT3904 Q103 4813824A10 DC Switch DC MMBT3904 Q105 4886212B01 TX Driver Stage 438-470MHz MRF1518 Q200 4802245J95 RX Injection Amplifier 393-425MHz BFS540 Q201 48099390C04 <td>D107</td> <td>4805218N57</td> <td>Forward Volt. Peak Detector</td> <td>DC</td> <td>RB715F</td>	D107	4805218N57	Forward Volt. Peak Detector	DC	RB715F
D201 4802233J09 Voltage Multiplier 1.05MHz IMM10 D202 4862824C03 Crystal Warp DC 1SV232 D203 4805649Q13 RX VCO Frequency Control 438-470MHz 1SV228 D204 4805649Q13 TX VCO Frequency Control 438-470MHz 1SV228 D205 4862824C01 TX VCO Modulator Audio-470MHz 1SV229 D400 4813833C07 Steering Diode DC MMBD7000 D401 4813833C02 Steering Diode DC MMBD7000 D401 481663B01 TX RF Power Amplifier 438-470MHz MRF1535 Q101 4813824A10 DC Switch DC MMBT3904 Q102 4813824A10 DC Switch DC MMBT3904 Q105 4886212B01 TX Driver Stage 438-470MHz MRF1518 Q106 4805128M27 Current Source DC BSR33 Q201 4809940E02 DC Switch DC UMC3 UM5 Q201 4809940E02 DC Switch	D108	4805218N57	Forward Volt. Peak Detector		RB715F
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U103 5113819A04 Power Control DC MC3303					
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EXHIBIT 10 SHEET 2 OF 15

Applicant: Motorola Inc.

U404 U405 U405 U500 4 U501 U503 U504 U508 U510 U511 U512 U513 U514 VR101 VR102 VR400 VR400 VR401 VR402 VR500 VR501 VR501 VR502 VR503 VR504 VR503 VR504 VR694 VR695 VR696 VR697 VR698	5102226J56 5189233U02 5113805B58 4813833C02 5102190C33 5105469E65 5185130C53 5113816A30 5104187K94 4813833C02 4813833C02 4813833C02 4813833C02 4813830A15 4813830A15 4813830A15 4813830A15 4813830A15 4813830A15 4813830A75 4813830A75 4813830A75 4813830A75 4813830A75 4813830A75 4813830A75 4813830A75 4813830A75 4813830A75 4813830A75 4813830A75 4813830A75 4813830A75 4813830A75 4813830A75	Microprocessor FLASH Shift Register Wired OR Voltage Regulator Voltage Regulator Audio and Signaling IC Voltage Regulator Voltage Regulator Voltage Regulator Voltage Regulator Wired OR Wired OR Reverse Protection DC Switch Power Control Loop Protection Current Source DC Switch Over voltage Protection DC Switch Reverse Protection Reverse Protection Reverse Protection Reverse Protection Reverse Protection Reverse Protection ESD Protection	3.78MHz 7.56MHz 3.78MHz DC	SRM2B256 MC68HC11FL0 AT49LV002N_70VI MC74VHC1GT66 MMBD6100 LM2941T LP2951C 30C53 MC33269D LP2986ILDX MMBD6100 MMBD6100 MMBD6100 SI3455ADV MMBZ5232B MMBZ5232B MMBZ5232B MMBZ5235B MMSZ4687T1 MMBZ5226B MR2835S MMBZ5231B MMSZ4686T1 MMSZ4684 MMSZ4684 MMSZ4684 MMSZ4684 MMBZ20VAL
VR699 4	1813830A75	ESD Protection	DC	MMBZ20VAL
	1880114R06	16.8MHz Crystal	16.8MHz	114R06

Exhibit 10B – List of Recommended Test Equipment for Servicing

Instrument	Recommended Type	Application
RF Signal Generator	HP 8656B or equivalent	Receiver Measurements
Modulation Analyzer	HP 8901B or equivalent	Frequency and Deviation Measurements
Audio Analyzer	HP 8903A or equivalent	Receiver Measurements
Power Meter	HP 438A or equivalent	Transmitter Power Measurements
Power Sensor	HP 8428A or equivalent	Transmitter Output Power
DC Power Supply	0-20 volts at 15 amps	
Attenuator Pad	75 Watts, 30 dB	Transmitter Measurements
DC Ammeter	30mA to 20 A	Current Drain Measurements
Computer	IBM PC, PC/XT, or PC/AT	Radio Alignment
Radio Interface Box	RLN4008E	Computer Interface to Radio
Cable	3080369B72	From RIB to Computer
Cable	AAPMKN4004	From RIB to Radio
Software	RVN4191	Radio Alignment

Exhibit 10C – Tune Up Information

Pursuant to 47 CFR 2.1033(c)(9)

All transmitter adjustments are performed by electronic means. The transmitter contains no electromechanical components for the purpose of transmitter tuning or adjustment.

The tuning elements that are used for transmitter adjustment are:

Location	Type of Element	Function
U403	Microprocessor	Supplies data to Audio Filter IC, Fractional-N Synthesizer, Temperature Compensated Crystal Oscillator, and Power Control For Transmitter Modulation, Frequency and Power Adjustment
U200	Programmable Attenuator	Reference Modulation Balance
U504	Programmable Attenuator	Deviation Adjustment
U200	Digital to Analog Converter	Transmitter Frequency Adjustment
U200	Temperature Compensated Crystal Oscillator	Transmitter Frequency Adjustment
U504	Digital to Analog Converter	Transmitter Power Adjustment

The value of a particular tuning element is determined by data sent to that tuning element by microprocessor U403. This data is generated by the microprocessor based on tuning information that is stored in the microprocessor's EEPROM (Electrically Erasable Programmable Read Only Memory).

Tuning information is stored in the EEPROM during factory adjustment or by qualified field service facilities, using the attached procedure and recommended test equipment.

Tuning Procedure

Tuning Parameters

Supply Voltage

13.8+/-0.1Vdc @ DC Connector under operating condition 5.5A Current limit

Temperature

25+/-2°C

Table 1 Test Frequencies

	1				
	UHF R2				
Test	Portable & I	Mobile			
Frequency	TX (MHz)	RX (MHz)			
F1	438.000	438.025			
F2	433.325	433.350			
F3	448.675	448.700			
F4	454.000	454.025			
F5	459.325	459.350			
F6	464.675	464.700			
F7	470.000	469.975			

1. PA Bias Tuning

This procedure must be done before the transmitter is keyed the first time. To avoid FET device damage care must be taken not to exceed the drain current and dissipation limits of the devices by setting a too high bias voltage during tuning. The use of a power supply with an appropriate current limitation setting is recommended. The tune procedure should be done as fast as possible to keep the device temperature low and to achieve the required guiescent current accuracy.

General Tuning Procedure

Set the power supply to the voltage and current specified above and power up the radio. Define:

For VHF Radios: PA_BIAS = 0xD9, PA_BIAS_MAX = 0xE9, PA_BIAS_MIN = 0xC9, High_limit = 130, Low limit = 100

For UHF Radios: PA_BIAS = 0xA4, PA_BIAS_MAX = 0xB4, PA_BIAS_MIN = 0x94, High_limit = 330, Low limit = 300

Key the radio with the following values:

ASFIC BYTE 04 (DAC U) = 0x00ASFIC BYTE 06 (DAC G) = 0xFF

Set the TX freq to 200 MHz for VHF Radios and to 500 MHz for UHF Radios in order to eliminate the VCO influence.

Measure the power supply current and put it in I_REF.

Set the ASFIC BYTE 04 (DAC U) to PA BIAS.

Measure the power supply current and put it in I BIAS.

Calculate: Delta = I BIAS - I REF.

IF Low_limit [mA] < Delta < High_limit [mA] *** PA bias current ok ***

Program CP with ASFIC BYTE 04 (DAC U) = **PA_BIAS** and go to END **ELSE**

IF Delta > High_limit [mA] *** PA bias current too high ***
IF PA BIAS < PA BIAS MIN

Terminate the procedure and report FAIL - Hardware failure

Oscillator Sensitivity

-Calc OscSens:

waris_match_curve.

- Find inflection.

COLD:

Waris Match Curve

- Find best match.

best_comp_curve[i] = tc_curves[best_match_cold][i]

Inflection

-ppm =1

```
ELSE
                              PA BIAS = PA BIAS - 1
                              Go to stage (7)
                                        *** PA bias current too low ***
                       ELSE
                              IF PA BIAS > PA BIAS MAX
                                      Terminate the procedure and report FAIL – Hardware failure
                              ELSE
                                      PA BIAS = PA BIAS + 1
                                      Go to stage (7)
       END: PA BIAS tune completed
Barcode Reading And DAC Sensitivity Measurement (For Xtal Only)
-Scan the crystal code:
              A = Digit 1, B = Digit 2, C = Digit 3, D = Digit 4, E = Digit 5, F = Digit 6, G = Digit 7, H = Digit 8
                      temps(t): Array of temperature in steps of 5 deg C from -35 deg C to 90 deg C
Calc xtal_infl_temp = 22+A+(B/10)
Calc a1 = (C+D/10+E/100)*(-0.1)
Calc a3 = (8.20+(C+D/10+E/10)*(0.2)+(F+G/10+H/100)*(0.02)*(0.00001))
-Calc xtal curve ppm[26]
                             From I=0 to 25:
        -delta temp = temps[i]-25
        -xtal curve ppm[i] = a1*delta temp+a3*delta temp*delta temp*delta temp
- xtal max ppm = max value from the array xtal curve ppm
-UUT: Set Freq=438.025M , Mode Tx , DAC: hot:127, cold:127, lin:63, infl:63
-Adjust warp so ppm < 0.2 . Mark as table->warp dac center (=158). If Not in range 122 –390 then error.
-Check if warp dac center-64 < 0 OR warp dac center+64 > 511 Then "Min/Max warp DAC value is out of
-UUT set warp = warp dac center+64, Meas and record: high warp freg[Hz], meas var high[V].
-UUT set warp = warp_dac_center-64, Meas and record : low_warp_freq[Hz], meas_var_low[V].
       1) comp range v = meas var low-meas var high;
       2) ppm_range = (low_warp_freq-high_warp_freq)/high_warp_freq * 1e6;
       3) table->osc_sensitivity = fabs(ppm_range/comp_range_v); " If < 10 OR > 40 then error "
-Read ic temp1 till it < 35. Then report as TEMP1.
-Setup radio: set freq, mode=tx.
-Set DAC: infl=64, linear=63, hot=127, cold=127
-Set table->warp dac center.
-Measure frequency @ warp dac center @ TC off. Mark as ic infl ref.
- ?table->lin dac > 50; lin dac = 50; lin dac= table->lin dac
Set max_hot_error & max_cold_error arrays.
 - SortErr for hot & cold.
- table->hot dac = best match hot % 128;
- table->lin_dac = best_match_hot / 128;
- table->cold dac = best match cold % 128;
-Calc table->match error curve[26] and table->best comp curve[26]:
  match error curve[i] = abs(tc_curves[best_match_cold][i]-comp_curve_v[i])
```

```
HOT:
   same as cold just replace best_match_cold with best_match_hot.
Sort hot and cold Err array
Meaning:
Sort the max hot err & max cold err arrays.
From the lowest to biggest.
Just the first 512 lowest errors of all 8192 errors.
Implementation:
 Scan 512 times the 8192 array.
 Each scan find the element that have the lowest error and at the end of scan,
 just swap this record (error, index) with the first place element.
(put the lowest in the first place, and next scan start from the next place.)
Find index of array max hot err & and index of array max cold err where:
  1 - There linear is same(linear=curve idx /128)
  2 - The max err between them, is the minimum of all cases.
lin_dac_array[64]; init all elements to 0
Scan 8192 times. Till
          - cur lin dac1 = max cold curve[rank1].curve idx / 128;
          - If cur lin dac1 is in lin dac array then skip.
          - If not skip:
                      lin dac array[num lin dac] = cur lin dac1;
                      num lin dac++;
                      Scan 8192 times: Each curve:
                                       cur lin dac2=max hot curve[rank2].curve idx /128;
                                       if (cur lin dac2 == cur lin dac1)
                                              cur min max err = max(max cold curve[rank1].error,
max_hot_curve[rank2].error)
                                       if(cur min max err < min max err)
                                               min max err = cur min max err
                                               best hot = max hot curve[rank2].curve idx;
                                               best cold = max cold curve[rank1].curve idx;
             -if num lin dac > 64 then stop
Find Inflection
-Read ic temp1 till it < 35. Then report as TEMP1.
-Setup radio: set freq. mode=tx.
-Set DAC: infl=64, linear=63, hot=127, cold=127
-Set table-> warp dac center
-Measure frequency @ warp_dac_center @ TC off. Mark as ic_infl_ref .
- ?table->lin dac > 50 : lin dac = 50
                                                  lin dac= table->lin dac
                                           ;
ppm = 1
-Till ppm \leq 0.15:
  - Set DAC :infl: 64 , hot:table->hot dac, cold:table->cold dac, lin:lin dac
  - delay 0.2 Sec
   - Read freq. Calc ppm = (freq-ic_infl_ref)*1000000/(ic_infl_ref);
  -if (fabs(ppm) > min ppm error)
        - if (counter == 0)
             - old infl dac = infl dac;
              - old_ppm = ppm;
              - ? (ppm > 0) :
                                 infl_dac -= 10 ;
                                                      infl dac += 10;
       - if(counter !=0)
                - if ( (old_ppm != ppm) && (old_infl_dac != infl_dac) )
                          - num steps = old infl dac - infl dac
                          -?((old_ppm < -0.5) && (ppm > 0.5)) || ((old_ppm > 0.5) && (ppm < -0.5)) :
                                    num_steps = (int) (num_steps/2);;
                          - pull_sens = fabs ( num_steps / (old_ppm - ppm) );
               - old infl dac = infl dac;
```

- old ppm = ppm;

```
- infl_dac -= (int) (ppm * pull_sens);
  -counter ++
  }/* END: "if ( fabs(ppm) > Min ppm error)" */
- ? infl_dac < 0 : infl_dac = 0 ;;
- ? infl_dac >127 : infl_dac =127 ;
-? (old infl dac + infl dac)= 0 \text{ Or} = 254 \text{ Or counter} > 15)
                                                                       // (254=127*2)
      - stop!
      -? Counter >10: "Failed inflection, too many times"
                                                            ; "Infl dac is out of range";
-If Pass
- Report infl dac As "INFL SET AMB".
-Read temperature .Report as IC_TEMP. Mark as ic_temp , ? ((ic_temp < 20)||(ic_temp > 35)) :" TEMP
SENSOR OFF/NOT CONNECTED" ::
-table->infl dac = (int) (infl dac+ (1/infl dac step) * (ic temp-table->xtal infl temp+infl tmp offset));
Final Warp
-UUT setup: freq, mode tx
-Set warp center
-Set DAC values
-Find the table->warp_dac for ppm < 0.15:
    ppm = (freq - LO freq)/LO freq * 1000000;
Main Data Base
typedef struct to table
 double to curves[NUMBER COMP CURVES][MAX NUMBER OF TEMPS]: /* Voltage Vs Temperature
Curve array.*/
double temps[MAX NUMBER OF TEMPS];
                                                        /* Temperature Array.*/
double osc_contrib[MAX_NUMBER_OF_TEMPS]; /*oscillator offset contrib to tc */
double reg_contrib[MAX_NUMBER_OF_TEMPS]; /*regulator offset contrib to tc */
double xtal infl temp: /* crystal's inflection temperature. The point between the upper and lower turning points
in xtal curve ppm */
 double xtal curve ppm[MAX NUMBER OF TEMPS]: /* Crystal polynomial equation in ppm */
double xtal max ppm; /* crystal maximum ppm in the polynomial equation */
int warp_dac_center; /* The warp DAC value needed to set the oscillator to the desired reference frequency */
double osc sensitivity; /* The sensitivity of the oscillator's frequency to the voltage applied to the varactor. */
double comp_curve_v[MAX_NUMBER_OF_TEMPS]; /* the translated crystal curve in voltage including the
osc contrib[] and reg contrib[] */
double best_comp_curve[MAX_NUMBER_OF_TEMPS]; /* best IC compensation curve */
double match error curve[MAX NUMBER OF TEMPS]; /* the difference between best comp curve[] and
comp curve v[] */
int lin dac;
int hot dac;
int cold dac:
int infl dac;
 int warp dac;
}COMPENSATION TABLE;
```

2. Reference Oscillator Warping

Adjustment of the reference oscillator is critical for proper radio operation. Improper adjustment will not only result in poor operation, but also a misaligned radio that will interfere with other users operating on adjacent channels. For this reason, the reference oscillator should be checked every time the radio is serviced. The frequency counter used for this procedure must have a stability of 0.1 PPM (or better).

General Tuning Procedure

Set the power supply to the voltage specified above and power up the radio.

Remove any audio input signals to minimize frequency inaccuracy

Set the radio to the Carrier Squelch Environment, to 25kHz Channel Spacing and to the lowest transmit power level to reduce current drain during tuning.

If the radio's frequency range is NOT Low Band (29.7-50MHz) perform the following procedure

Disable modulation (Environment Override) to minimize frequency inaccuracy.

If the radio's frequency range is Low Band (29.7-50MHz) perform the following procedure Enable the microphone path (Environment Override).

Set the radio to the transmit frequency indicated in table 2.

Key up the radio.

If the radio's frequency range is Low Band (29.7-50MHz) perform the following procedure Set the IC value of the Transmit Power to \$32.

If the radio's frequency range is NOT Low Band (29.7-50MHz) perform the following procedure

Disable the digital modulation in the FRAC-N to minimize frequency inaccuracy.

Measure the transmit frequency and compare it with the specification limits +/-30Hz.

If the measured frequency is within the specification limits.

Dekey the radio.

Reference Oscillator Tuning done.

If the measured frequency is outside the specification limits.

Read the codeplug value for the Oscillator Warp.

While the transmit frequency is outside the specification limits.

Update the IC value of the Oscillator Warp without codeplug update.

Re-measure the transmit frequency and compare it with the specification limits.

Repeat steps (I) (ii) until the transmit frequency is within the specification limits.

Write the value of the tuned Oscillator Warp to the codeplug.

Dekey the radio.

Reference Oscillator Tuning done.

<u>Table 2</u> <u>Tuning Profile</u>

These tables list for each band at which softpot frequency each parameter must be tuned or calculated.

	UHF (1-28W)							
	None	F1	F2	F3	F4	F5	F6	F7
XTAL Temperature Comp.	•	•	•	•	•	•	•	Tune
Ref Osc Warp	•	•	•	•	•	•	•	Tune
Supply Voltage Threshold	Tune	•	•	•	•	•	•	•
PA Bias Voltage	Tune	•	•	•	•	•	•	•
TX Power	•	Tune	Calc.	Calc.	Tune	Calc.	Calc.	Tune
PA Control Voltage Limit	•	Tune	Tune	Tune	Tune	Tune	Tune	Tune
Modulation Balance	•	Tune	Tune	Tune	Tune	Tune	Tune	Tune
Deviation Limit (Voice)	•	Tune	Calc.	Calc.	Tune	Calc.	Calc.	Tune
Signaling Deviation	•	•	•	•	Tune	•	•	•
Front End Tuning	•	OF4	OF4	OF4	Tune	OF4	OF4	OF4
Rated Audio	•	•	•	•	Tune	•	•	•
RX Squelch	•	Tune	Calc.	Calc.	Tune	Calc.	Calc.	Tune
RSSI (MPT)	•	•	•	•	Tune	•	•	•

NOTES: • = No tuning required

Calc. = Linear interpolation using adjacent tune values

CFx = Use value obtained for Fx
OFx = Use offset calculated for Fx

25kHz = Use the values obtained for 25kHz channel spacing

Fixed = Use a fixed value (see appropriate table)

3. Transmitter Power Tuning

Overview: The softpots used for PA power setting do not contain the DAC values directly like they do in the portable radio. Instead they store the parameters (Mcp, Kcp) for approximation of the dependency between power and DAC setting. This procedure allows to set any power within the range of the PA without re-tuning. The PA output power (Pcp) levels are stored in the softpots for HIGH and LOW POWER. The following equations are used to calculate the DAC value for the desired power.

$$DAC \ PWR \ SET = 100 * \frac{4 * Kcp - Pcp}{Mcp}$$
 Equ. 1

$$Pcp = 25 * \sqrt{desired power}$$
 Equ. 2

The power is not stored directly in the softpots to avoid square root calculation by the radio software.

General Tuning Procedure

Set the power supply to the voltage specified above and power up the radio.

Read the tuning parameters from the radio and determine the values for DAC1 and DAC2.

Set the radio to the Carrier Squelch Environment and highest Transmit Power Level.

Disable modulation (Environment Override) and remove any audio input signals to minimize frequency inaccuracy.

This procedure is to be performed for all Power Tuning Channels indicated in table 1.

Set the radio to the appropriate transmit frequency.

Key up the radio.

Set the IC value of the Transmit Power to the value DAC1.

Measure the transmit power and note the value as P1.

Set the IC value of the Transmit Power to the value DAC2.

Measure the transmit power and note the value as P2.

Dekey the radio.

Calculate Mcp and Kcp with the following equations:

$$M = -\frac{\sqrt{P2} - \sqrt{P1}}{DAC2 - DAC1}$$
 Equ. 3

$$Mcp = 2500 * M$$
 Equ. 4

$$Kcp = 6.25 * (\sqrt{P1} + M * DAC1)$$
 Equ. 5

Write the values Kcp and Mcp the codeplug.

Repeat steps (A) to (J) for all the channels that require actual tuning. Values for the untuned channels are to be interpolated by the test controller and programmed into the codeplug.

Transmit Power Tuning done.

4. Modulation Balance Tuning:

Modulation balance balances the modulation sensitivity of the VCO and reference modulation (synthesizer low frequency port) lines. Balance algorithm is critical to the operation of signaling schemes that have very low frequency components (e.g. PL) and could result in distorted waveforms if improperly adjusted. The radio stores only one set of tuning data for all supported channel spacings (12.5, 20 and 25 kHz). Therefore, tuning should only be performed for 12.5 kHz channel spacing.

In the radio the deviation for 12.5 kHz is set by reducing the modulation sensitivity within the synthesizer IC. The reduction of the low audio frequency components is done by a division by 2 in the digital modulator and very accurate. The high audio frequency components are attenuated by a resistive network that has typically 6.3 dB. This inaccuracy will bring the modulation out of balance in the not tuned channel spacing. Tuning at 12.5 kHz will reduce the low frequency components at 25 kHz channel spacing, while tuning at 25 kHz will increase the low frequency components at 12.5 kHz channel spacing. Due to the fact that the upper spec limit is only 1dB, but the lower spec limit is -3 dB, tuning at 12.5 kHz improves the margin.

General Tuning Procedure

Set the power supply to the voltage specified above and power up the radio.

Set the radio to the External Signal Modulation Balance Environment, to 12.5kHz Channel Spacing and to the lowest transmit power level to reduce current drain during tuning.

This procedure is to be performed for all Modulation Balance Attenuator Tuning Channels indicated in table 2.

Set the radio to the appropriate Modulation Balance Attenuator Tuning Channel.

Remove any audio signals applied to any audio inputs to avoid a transmit frequency offset. Key up the radio.

If the radio's frequency range is Low Band (29.7-50MHz) perform the following procedure Set the IC value of the Transmit Power to \$32.

Update the IC value of the VCO Attenuator to its maximum setting (\$255) without codeplug update.

Apply an 80Hz tone @ 100mV RMS to the Auxiliary Transmit Audio Path.

Measure the transmit deviation, note the value as D1.

Apply a 3kHz tone @ 100mV RMS to the Auxiliary Transmit Audio Path.

Measure the transmit deviation, note the value as D2.

Find the ratio of the measured transmit deviation values in dB using equation 20*log(D1/D2).

If the ratio of the measured transmit deviations is within $\pm 0.15~\text{dB}$

Dekey the radio.

Modulation Balance Tuning for the set Tuning Channel done. Continue with step (A) for the next Modulation Balance Attenuator Tuning Channel

If the ratio of the measured transmit deviations is NOT within $\pm 0.15~\text{dB}$

Read the codeplug value for the Modulation Balance Attenuator.

While the ratio of the measured transmit deviations is outside the specification limits.

Disable modulation (Environment Override) to minimize frequency offset.

Update the IC value of the Modulation Balance Attenuator without codeplug update.

Enable modulation (Environment Override).

Repeat steps (E) to (I).

Repeat steps (a) to (d) until the ratio of the measured transmit deviations is inside the specification limits

NOTE 1: Modulation must be removed from the Fractional –N Synthesizer while it is being programmed. **Dekey the radio.**

Write the value of the tuned Modulation Balance Attenuator to the codeplug.

Modulation Balance Tuning done

5. Modulation Limit Tuning

Modulation limit tuning sets the maximum deviation of the carrier. The radio stores only one set (7 values across the frequency band) of tuning data for 25kHz channel spacing. Therefore, tuning across the frequency band must only be performed for 25 kHz channel spacing. For 12.5 and 20kHz channel spacings an offset value in the codeplug is used to reduce the deviation. The offset value should be tuned at one frequency only.

MDC/LTR Low Band radios which use 5 kHz rated system deviation for 20kHz channel spacing do not have to be tuned at 20kHz channel spacing.

General Tuning Procedure

The Modulation Balance Tuning must already be done for this procedure to be valid.

Set the power supply to the voltage specified above and power up the radio.

Set the radio to the Carrier Squelch Environment, to 25kHz Channel Spacing and to the lowest transmit power level to reduce current drain during tuning.

Enable the microphone path (Environment Override).

This procedure is to be performed for all Modulation Limit Tuning Channels indicated in table 2

Set the radio to the appropriate Modulation Limit Tuning Channel.

Remove any audio signals applied to any audio inputs to avoid a transmit frequency offset.

Key up the radio.

If the radio's frequency range is Low Band (29.7-50MHz) perform the following procedure Set the IC value of the Transmit Power to \$32.

Apply a 1kHz tone @ 800mV RMS to the External Microphone Audio Path.

Measure the transmit deviation and compare it with the specification limits in the table 3.

Table 3 Reference Voice Deviation Tuning Limits

This table lists the tuning window for the reference voice deviation. All signaling deviations are based on this voice deviation. For 25/30 kHz channel spacing the deviation is tuned at multiple softpot frequencies. For all other channel spacings only an offset value is determined at one softpot frequency

Channel Spacing	Rated System Deviation	Deviation Tuning Window
25/30 kHz	5 kHz	4.40 – 4.60 kHz (Except Low Band R3 @ F6&F7) 4.20 – 4.40 kHz (Low Band R3 @ F6&F7)
20 kHz (Low Band 20 kHz systems in North America only)	5 kHz	4.40 – 4.60 kHz (Except Low Band R3 @ F6&F7) 4.20 – 4.40 kHz (Low Band R3 @ F6&F7)
20 kHz	4 kHz	3.40 – 3.60 kHz
12.5 kHz	2.5 kHz	2.20 – 2.30 kHz

If the measured transmit deviation is within the specification limits Dekey the radio.

Modulation Limit Tuning for the set Tuning Channel done. Continue with step (A) for the next Modulation Limit Tuning Channel

If the measured transmit deviation is outside the specification limits

Read the codeplug value for the VCO Attenuator.

While the measured transmit deviation is outside the specification limits.

Update the IC value of the VCO Attenuator without codeplug update.

Re-measure the transmit deviation and compare it with the specification limits.

Repeat steps (a) (b) until the measured transmit deviation is inside the specification limits Dekey the radio.

Write the value of the tuned VCO Attenuator to the codeplug.

VCO Attenuator Tuning for the set Tuning Channel done. Continue with step (A) for the next Modulation Limit Tuning Channel

This procedure is to be performed for all remaining Modulation Limit Tuning Channel Spacings (12.5 and 20kHz) and the Modulation Limit Tuning Channel indicated in table 2

Enable the microphone path (Environment Override) **and set the appropriate** Modulation Limit Tuning Channel Spacing.

Set the radio to the appropriate VCO Attenuator Tuning Channel for the set channel spacing.

Remove any audio signals applied to any audio inputs to avoid a transmit frequency offset. Key up the radio.

Apply a 1kHz tone @ 800mV RMS to the External Microphone Audio Path.

Measure the transmit deviation and compare it with the specification limits in Table 3.

If the measured transmit deviation is within the specification limits

Dekey the radio.

VCO Attenuator Tuning for the set Channel Spacing done. Continue with step (A) for the next Modulation Limit Tuning Channel Spacing

If the measured transmit deviation is outside the specification limits

Read the codeplug value for the VCO Attenuator.

While the measured transmit deviation is outside the specification limits.

Update the IC value of the VCO Attenuator without codeplug update.

Re-measure the transmit deviation and compare it with the specification limits.

Repeat steps (a) (b) until the measured transmit deviation is inside the specification limits Dekey the radio.

Write the value of the tuned VCO Attenuator to the codeplug.

Modulation Limit Tuning for the set Tuning Channel done. Continue with step (A) for the next Modulation Limit Tuning Channel