

# SAR TEST REPORT

# No. I14Z49111-SEM01

### For

## **TCL Communication Ltd.**

## **UMTS Triband / GSM Quadband mobile phone**

Model Name: 2067X

With

**Hardware Version:01** 

**Software Version: C97** 

FCC ID: 2ACCJA003

Issued Date: 2015-1-15



#### Note:

The test results in this test report relate only to the devices specified in this report. This report shall not be reproduced except in full without the written approval of CTTL.

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# **Revision Version**

Report Number	Revision	Issue Date	Description	
I14Z49111-SEM01	Rev.0	2015-1-15	Initial creation of test report	



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## 1 Test Laboratory

## 1.1 Testing Location

Company Name:	CTTL(Shouxiang)	
Address:	No. 51 Shouxiang Science Building, Xueyuan Road, Haidian District,	
	Beijing, P. R. China100191	

## **1.2 Testing Environment**

Temperature:	18°C~25°C,
Relative humidity:	30%~ 70%
Ground system resistance:	< 0.5 Ω
Ambient noise & Reflection:	< 0.012 W/kg

## 1.3 Project Data

Project Leader:	Qi Dianyuan
Test Engineer:	Lin Xiaojun
Testing Start Date:	January7, 2015
Testing End Date:	January9, 2015

## 1.4 Signature

Lin Xiaojun

(Prepared this test report)

Qi Dianyuan

(Reviewed this test report)

Xiao Li

Deputy Director of the laboratory

(Approved this test report)



## 2 Statement of Compliance

The maximum results of Specific Absorption Rate (SAR) found during testing for TCL Communication Ltd.UMTS Triband / GSM Quadband mobile phone2067X are as follows:

Table 2.1: HighestReported SAR(1g)

Exposure Configuration	Technology Band	Highest Reported SAR 1g(W/Kg)	Equipment Class
Hood	GSM 850	0.60	
Head (Congretion Distance Omm)	PCS 1900	0.42	PCE
(Separation Distance 0mm)	UMTS FDD 5	0.86	
Pody worn	GSM 850	0.71	
Body-worn (Separation Distance 10mm)	PCS 1900	0.80	PCE
(Separation distance formin)	UMTS FDD 5	0.94	

The SAR values found for the Mobile Phone are below the maximum recommended levels of 1.6 W/Kg as averaged over any 1g tissue according to the ANSI C95.1-1999.

For body worn operation, this device has been tested and meets FCC RF exposure guidelines when used with any accessory that contains no metal and which provides a minimum separation distance of 10 mm between this device and the body of the user. Use of other accessories may not ensure compliance with FCC RF exposure guidelines.

The EUT battery must be fully charged and checked periodically during the test to ascertain uniform power output.

The measurement together with the test system set-up is described in annex C of this test report. A detailed description of the equipment under test can be found in chapter 4 of this test report. The highestreported SAR value is obtained at the case of **(Table 2.1)**, and the values are: **0.94 W/kg(1g)**.

Table 2.2: The sum of reported SAR values for GSM/WCDMA and Bluetooth

	Position	WCDMA	BT*	Sum
Highest reported SAR value for Head	Right hand, Touch cheek	0.86	0.37	1.23
Highest reported SAR value for Body	Rear	0.94	0.19	1.13

BT\* - Estimated SAR for Bluetooth (see the table 13.2)

According to the above tables, the maximum sum of reported SAR values is **1.23 W/kg (1g)**. The detail for simultaneous transmission consideration isdescribed in chapter 13.



# **3 Client Information**

## **3.1 Applicant Information**

Company Name:	TCL Communication Ltd.
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## 3.2 Manufacturer Information

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City:	ShangHai
Postal Code:	201203
Country:	P.R.China
Contact:	Gong Zhizhou
Email:	zhizhou.gong@tcl.com
Telephone:	0086-21-51798260
Fax:	0086-21-61460602



# 4 Equipment Under Test (EUT) and Ancillary Equipment (AE)

#### 4.1 About EUT

Description:	UMTS Triband / GSM Quadband mobile phone		
Model name:	2067X		
Operating mode(s):	GSM 850/900/1800/1900, WCDMA 850/900/2100, BT		
	825 – 848.8 MHz (GSM 850)		
Tested Tx Frequency:	1850.2 – 1910 MHz (GSM 1900)		
	826.4–846.6 MHz (WCDMA 850 Band V)		
GPRS Multislot Class:	10		
EGPRS Multislot Class:	10		
GPRS capability Class:	В		
WCDMA Catagory	HSDPA: 8		
WCDMA Category:	HSUPA: 5		
	GSM: Rel6		
Release Version:	GPRS: Rel6		
	UMTS: R6		
Test device Production information:	Production unit		
Device type:	Portable device		
Antenna type:	Integrated antenna		
Accessories/Body-worn configurations:	Headset		
Form factor:	104 mm ×52.3 mm×17.25 mm		

## 4.2 Internal Identification of EUT used during the test

EUT ID*	IMEI	HW Version	SW Version
EUT1	356789060009550	01	C97
EUT2	356789060009619	01	C97

<sup>\*</sup>EUT ID: is used to identify the test sample in the lab internally.

Note: It is performed to test SAR with the EUT1 and conducted power with the EUT2.

## 4.3 Internal Identification of AE used during the test

AE ID*	Description	Model	SN	Manufacturer
AE1	Battery	CAB3120000C1	/	BYD
AE2	Headset	CCB3160A15C1	/	Juwei

<sup>\*</sup>AE ID: is used to identify the test sample in the lab internally.



### **5 TEST METHODOLOGY**

#### 5.1 Applicable Limit Regulations

**ANSI C95.1–1999:**IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz to 300 GHz.

It specifies the maximum exposure limit of **1.6 W/kg** as averaged over any 1 gram of tissue for portable devices being used within 20 cm of the user in the uncontrolled environment.

## 5.2 Applicable Measurement Standards

**IEEE 1528–2013:** Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Body Due to Wireless Communications Devices:ExperimentalTechniques.

**KDB447498 D01:General RF Exposure Guidance v05r02:**Mobile and Portable Devices RF Exposure ProceduresandEquipment Authorization Policies.

KDB648474 D04 Handset SAR v01r02:SAR Evaluation Considerations for Wireless Handsets.

**KDB 865664 D01SAR measurement 100 MHz to 6 GHz v01r03:**SAR Measurement Requirements for 100 MHz to 6 GHz

**KDB 865664 D02RF Exposure Reporting v01r01:**RF Exposure Compliance Reporting and Documentation Considerations



## 6 Specific Absorption Rate(SAR)

#### 6.1 Introduction

SAR is related to the rate at which energy is absorbed per unit mass in an object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and general population/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

#### 6.2 SAR Definition

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density  $(\rho)$ . The equation description is as below:

$$SAR = \frac{d}{dt}(\frac{dW}{dm}) = \frac{d}{dt}(\frac{dW}{\rho dv})$$

SAR is expressed in units of Watts per kilogram (W/kg)

SAR measurement can be either related to the temperature elevation in tissue by

$$SAR = c(\frac{\delta T}{\delta t})$$

Where: C is the specific head capacity,  $\delta T$  is the temperature rise and  $\delta t$  is the exposure duration, or related to the electrical field in the tissue by

$$SAR = \frac{\sigma |E|^2}{\rho}$$

Where:  $\sigma$  is the conductivity of the tissue,  $\rho$  is the mass density of tissue and E is the RMS electrical field strength.

However for evaluating SAR of low power transmitter, electrical field measurement is typically applied.



# 7 Tissue Simulating Liquids

## 7.1 Targets for tissue simulating liquid

Table 7.1: Targets for tissue simulating liquid

				<u> </u>	
Frequency (MHz)	Liquid Type	Conductivity (σ)	± 5% Range	Permittivity (ε)	± 5% Range
835	Head	0.90	0.86~0.95	41.5	39.4~43.6
835	Body	0.97	0.92~1.02	55.2	52.4~58.0
1900	Head	1.40	1.33~1.47	40.0	38.0~42.0
1900	Body	1.52	1.44~1.60	53.3	50.6~56.0

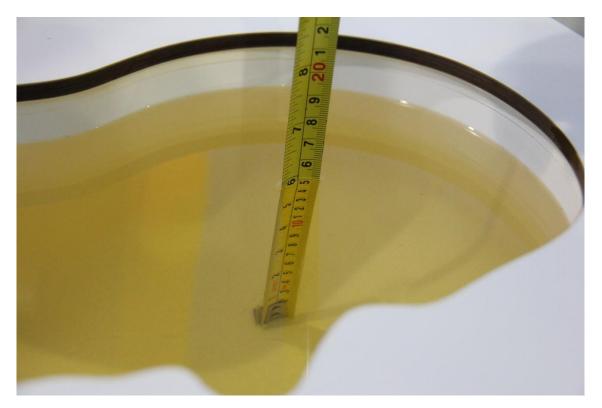
## 7.2 Dielectric Performance

Table 7.2: Dielectric Performance of Tissue Simulating Liquid

Measurement Date (yyyy-mm-dd)	Туре	Frequency	Permittivity ε	Drift (%)	Conductivity σ (S/m)	Drift (%)
2015-1-7	Head	835 MHz	42.21	1.71	0.922	2.44
	Body	835 MHz	54.85	-0.63	0.963	-0.72
2015-1-9	Head	1900 MHz	40.05	0.13	1.382	-1.29
	Body	1900 MHz	54.06	1.43	1.508	-0.79

Note: The liquid temperature is 22.0  $^{\circ}\mathrm{C}$ 





Picture 7-1: Liquid depth in the Head Phantom (835MHz)



Picture 7-2: Liquid depth in the Flat Phantom (835MHz)





Picture 7-3: Liquid depth in the Head Phantom (1900 MHz)



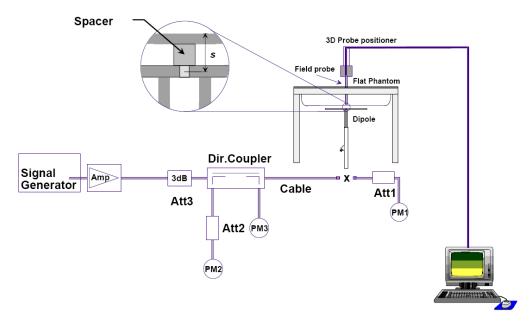
Picture 7-4 Liquid depth in the Flat Phantom (1900MHz)



## 8System verification

## 8.1 System Setup

In the simplified setup for system evaluation, the DUT is replaced by a calibrated dipole and the power source is replaced by a continuous wave that comes from a signal generator. The calibrated dipole must be placed beneath the flat phantom section of the SAM twin phantom with the correct distance holder. The distance holder should touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The equipment setup is shown below:



Picture 8.1 System Setup for System Evaluation



**Picture 8.2 Photo of Dipole Setup** 



## 8.2System Verification

SAR system verification is required to confirm measurement accuracy, according to the tissue dielectricmedia, probe calibration points and other system operating parameters required for measuring the SAR of a test device. The system verification must be performed for each frequency band and within the validrange of each probe calibration point required for testing the device.

The system verification results are required that the area scan estimated 1-g SAR is within 3% of the zoom scan 1-g SAR. The details are presented in annex B.

**Table 8.1: System Verification of Head** 

Measurement		Target val	ue (W/kg)	Measured	value(W/kg)	Devi	ation
Date	Frequency	10 g	1 g	10 g	1 g	10 g	1 g
(yyyy-mm-dd)		Average	Average	Average	Average	Average	Average
2015-1-7	835 MHz	6.17	9.43	6.16	9.80	-0.16%	3.92%
2015-1-9	1900 MHz	21.1	40.6	20.4	38.8	-3.32%	-4.43%

**Table 8.2: System Verification of Body** 

Measurement		Target val	ue (W/kg)	Measured v	value (W/kg)	Devia	ation
Date	Frequency	10 g	1 g	10 g	1 g	10 g	1 g
(yyyy-mm-dd)		Average	Average	Average	Average	Average	Average
2015-1-7	835 MHz	6.33	9.55	6.04	9.16	-4.58%	-4.08%
2015-1-9	1900 MHz	21.4	40.4	21.2	40.4	-0.93%	0%



### 9Measurement Procedures

#### 9.1 Tests to be performed

In order to determine the highest value of the peak spatial-average SAR of a handset, alldevice positions, configurations and operational modes shall be tested for each frequencyband according to steps 1 to 3 below. A flowchart of the test process is shown in picture 9.1.

**Step 1**: The tests described in 9.2 shall be performed at the channel that is closest to the centre of the transmit frequency band ( $f_c$ ) for:

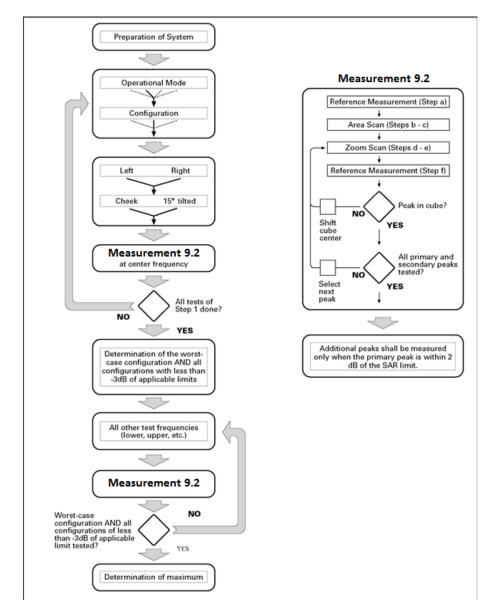
- a) all device positions (cheek and tilt, for both left and right sides of the SAM phantom, asdescribed in annex D),
- b) all configurations for each device position in a), e.g., antenna extended and retracted, and
- c) all operational modes, e.g., analogue and digital, for each device position in a) and configuration in b) in each frequency band.

If more than three frequencies need to be tested according to 11.1 (i.e.,  $N_c > 3$ ), then allfrequencies, configurations and modes shall be tested for all of the above test conditions.

**Step 2**: For the condition providing highest peak spatial-average SAR determined in Step 1,perform all tests described in 9.2 at all other test frequencies, i.e., lowest and highest frequencies. In addition, for all other conditions (device position, configuration and operational mode) where the peak spatial-average SAR value determined in Step 1 is within 3 dB of the applicable SAR limit, it is recommended that all other test frequencies shall betested as well.

**Step 3**: Examine all data to determine the highest value of the peak spatial-average SARfound in Steps 1 to 2.





Picture 9.1Block diagram of the tests to be performed

### 9.2General Measurement Procedure

The area and zoom scan resolutions specified in the table below must be applied to the SAR measurements andfully documented in SAR reports to qualify for TCB approval. Probe boundary effect error compensation isrequired for measurements with the probe tip closer than half a probe tip diameter to the phantom surface. Boththe probe tip diameter and sensor offset distance must satisfy measurement PIOcols; to ensure probe boundaryeffect errors are minimized and the higher fields closest to the phantom surface can be correctly measured and extrapolated to the phantom surface for computing 1-g SAR. Tolerances of the post-processing algorithms must be verified by the test laboratory for the scan resolutions used in the SAR measurements, according to thereference distribution functions specified in IEEE Std 1528-2003. The results should be documented as part of thesystem validation records and may be requested to support test results when all the measurement parameters in thefollowing table are not satisfied.



			≤ 3 GHz	> 3 GHz
Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface			5 ± 1 mm	½·δ·ln(2) ± 0.5 mm
	Maximum probe angle from probe axis to phantom surface normal at the measurement location		30°±1°	20° ± 1°
			≤ 2 GHz: ≤ 15 mm 2 – 3 GHz: ≤ 12 mm	3 – 4 GHz: ≤ 12 mm 4 – 6 GHz: ≤ 10 mm
Maximum area scan spatial resolution: $\Delta x_{Area}$ , $\Delta y_{Area}$		When the x or y dimension of the measurement plane orientation, measurement resolution must be dimension of the test device with point on the test device.	is smaller than the above, the e < the corresponding x or y	
Maximum zoom scan sp	atial resolu	tion: Δx <sub>Zoom</sub> , Δy <sub>Zoom</sub>	≤ 2 GHz: ≤ 8 mm 2 – 3 GHz: ≤ 5 mm*	3 – 4 GHz: ≤ 5 mm* 4 – 6 GHz: ≤ 4 mm*
	uniform grid: Δz <sub>Zoom</sub> (n)		≤ 5 mm	3 – 4 GHz: ≤ 4 mm 4 – 5 GHz: ≤ 3 mm 5 – 6 GHz: ≤ 2 mm
Maximum zoom scan spatial resolution, normal to phantom surface	graded	Δz <sub>Zoom</sub> (1): between 1 <sup>st</sup> two points closest to phantom surface	≤ 4 mm	3 – 4 GHz: ≤ 3 mm 4 – 5 GHz: ≤ 2.5 mm 5 – 6 GHz: ≤ 2 mm
	grid $\Delta z_{Zoom}(n>1)$ : between subsequent points		≤ 1.5·Δz	Zoom(n-1)
Minimum zoom scan volume	x, y, z	I	≥ 30 <b>mm</b>	3 – 4 GHz: ≥ 28 mm 4 – 5 GHz: ≥ 25 mm 5 – 6 GHz: ≥ 22 mm

Note: δ is the penetration depth of a plane-wave at normal incidence to the tissue medium; see draft standard IEEE P1528-2011 for details.

#### 9.3 Power Drift

To control the output power stability during the SAR test, DASY4 system calculates the power drift by measuring the E-field at the same location at the beginning and at the end of the measurement for each test position. These drift values can be found in Table 14.1 to Table 14.12 labeled as: (Power Drift [dB]). This ensures that the power drift during one measurement is within 5%.

When zoom scan is required and the <u>reported</u> SAR from the area scan based 1-g SAR estimation procedures of KDB 447498 is ≤ 1.4 W/kg, ≤ 8 mm, ≤ 7 mm and ≤ 5 mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.



## 10Area Scan Based 1-g SAR

#### 10.1Requirement of KDB

According to the KDB447498 D01 v05, when the implementation is based the specific polynomial fit algorithm as presented at the 29th Bioelectromagnetics Society meeting (2007) and the estimated 1-gSAR is  $\leq$  1.2 W/kg, a zoom scan measurement is not required provided it is also not needed for any otherpurpose; for example, if the peak SAR location required for simultaneous transmission SAR testexclusion can be determined accurately by the SAR system or manually to discriminate between distinctive peaks and scattered noisy SAR distributions from area scans.

There must not be any warning or alert messages due to various measurement concernsidentified by the SAR system; for example, noise in measurements, peaks too close to scan boundary, peaks are too sharp, spatial resolution and uncertainty issues etc. The SAR system verification must also demonstrate that the area scan estimated 1-g SAR is within 3% of the zoom scan 1-g SAR (See Annex B). When all the SAR results for each exposure condition in a frequency band and wireless mode are based on estimated 1-g SAR, the 1-g SAR for the highest SAR configuration must be determined by a zoom scan.

### 10.2Fast SAR Algorithms

The approach is based on the area scan measurement applying a frequencydependent attenuation parameter. This attenuation parameter was empirically determined by analyzing a large number of phones. The MOTOROLA FAST SAR was developed and validated by the MOTOROLA Research Group in Ft. Lauderdale.

In the initial study, an approximation algorithm based on Linear fit was developed. The accuracyof the algorithm has been demonstrated across a broad frequency range (136-2450 MHz)and for both 1- and 10-g averaged SAR using a sample of 264 SAR measurements from 55wireless handsets. For the sample size studied, the root-mean-squared errors of the algorithmare 1.2% and 5.8% for 1- and 10-g averaged SAR, respectively. The paper describing thealgorithm in detail is expected to be published in August 2004 within the Special Issue of Transactions on MTT.

In the second step, the same research group optimized the fitting algorithm to an Polynomial fit whereby the frequency validity was extended to cover the range 30-6000MHz. Details ofthis study can be found in the BEMS 2007 Proceedings.

Both algorithms are implemented in DASY software.



# 11 Conducted Output Power

# 11.1 Manufacturing tolerance

Table 11.1: GSM Speech

		•				
	GSM 850					
Channel	Channel 251	Channel 190	Channel 128			
Target (dBm)	32.0	32.0	32.0			
Tune-up(dBm)	32.5	32.5	32.5			
	GSN	/I 1900				
Channel	Channel 810	Channel 661	Channel 512			
Target (dBm)	29.3	29.3	29.3			
Tune-up(dBm)	29.8	29.8	29.8			

### Table 11.2: GPRS

	1000 11121 01 110					
	GSM 850 GPRS (GMSK)					
	Channel	251	190	128		
1 Typlot	Target (dBm)	32.0	32.0	32.0		
1 Txslot	Tune-up(dBm)	32.5	32.5	32.5		
O Tyroloto	Target (dBm)	30.9	30.9	30.9		
2 Txslots	Tune-up(dBm)	31.4	31.4	31.4		
		GSM 1900 GPRS (GN	MSK)			
	Channel	810	661	512		
1 Typlot	Target (dBm)	29.3	29.3	29.3		
1 Txslot	Tune-up(dBm)	29.8	29.8	29.8		
2 Typloto	Target (dBm)	28.1	28.1	28.1		
2 Txslots	Tune-up(dBm)	28.6	28.6	28.6		

### Table 11.3: EGPRS

Table 11.5. EST NO						
	GSM 850 EGPRS (GMSK)					
	Channel 251 190 128					
1 Tyolot	Target (dBm)	32.0	32.0	32.0		
1 Txslot	Tune-up(dBm)	32.5	32.5	32.5		
2 Tycloto	Target (dBm)	30.9	30.9	30.9		
2 Txslots	Tune-up(dBm)	31.4	31.4	31.4		
	(	SSM 1900 EGPRS (G	MSK)			
	Channel	810	661	512		
1 Tyolot	Target (dBm)	29.3	29.3	29.3		
1 Txslot	Tune-up(dBm)	29.8	29.8	29.8		
2 Txslots	Target (dBm)	28.1	28.1	28.1		
2 1 351015	Tune-up(dBm)	28.6	28.6	28.6		



### Table 11.4: WCDMA

	WCDM	A 850 CS	
Channel	Channel 4233	Channel 4182	Channel 4132
Target (dBm)	23	23	23
Tune-up(dBm)	24.0	24.0	24.0
	HSUPA (	sub-test 1)	
Channel	Channel 4233	Channel 4182	Channel 4132
Target (dBm)	18.6	18.6	18.6
Tune-up(dBm)	19.6	19.6	19.6
	HSUPA (	sub-test 2)	
Channel	Channel 4233	Channel 4182	Channel 4132
Target (dBm)	17.6	17.6	17.6
Tune-up(dBm)	18.6	18.6	18.6
	HSUPA (	sub-test 3)	
Channel	Channel 4233	Channel 4182	Channel 4132
Target (dBm)	18.1	18.1	18.1
Tune-up(dBm)	19.1	19.1	19.1
	HSUPA (	sub-test 4)	
Channel	Channel 4233	Channel 4182	Channel 4132
Target (dBm)	18.6	18.6	18.6
Tune-up(dBm)	19.6	19.6	19.6
	HSUPA (	sub-test 5)	
Channel	Channel 4233	Channel 4182	Channel 4132
Target (dBm)	21.5	21.5	21.5
Tune-up(dBm)	22.5	22.5	22.5

## Table 11.5: Bluetooth

Bluetooth					
Channel	Channel 0	Channel 39	Channel 78		
Target (dBm)	8.5	8.5	8.5		
Tune-up(dBm)	9.5	9.5	9.5		



#### 11.2 GSM Measurement result

During the process of testing, the EUT was controlled via Agilent Digital Radio Communication tester (E5515C) to ensure the maximum power transmission and proper modulation. This result contains conducted output power for the EUT. In all cases, the measured peak output power should be greater and within 5% than EMI measurement.

Table 11.6: The conducted power measurement results for GSM850/1900

GSM		Conducted Power (dBm)	
850MHz	Channel 251(848.8MHz)	Channel 190(836.6MHz)	Channel 128(824.2MHz)
OSUMINZ	31.86	31.86	31.90
CCM		Conducted Power(dBm)	
GSM 1900MHz	Channel 810(1909.8MHz)	Channel 661(1880MHz)	Channel 512(1850.2MHz)
1900MHZ	29.58	29.30	29.18

Table 11.7: The conducted power measurement results for GPRS

			•					
GSM 850	Meası	red Power	(dBm)	calculation	Averaged Power (dBm)			
GPRS (GMSK)	251	190	128		251	190	128	
1 Txslot	31.81	31.83	31.83	-9.03dB	22.78	22.80	22.80	
2 Txslots	30.91	30.87	30.91	-6.02dB	24.89	24.85	24.89	
PCS1900	Meası	red Power	(dBm)	calculation	Avera	ged Power	(dBm)	
GPRS (GMSK)	810	661	512		810	661	512	
1 Txslot			29.16	-9.03dB	20.60	20.26	20.13	
2 Txslots			27.96	-6.02dB	22.24	22.00	21.94	

Table 11.8: The conducted power measurement results for EGPRS

GSM 850	Measu	ıred Power	(dBm)	calculation	Avera	(dBm)		
EGPRS (GMSK)	251	190	128		251	190	128	
1 Txslot	31.80	31.81	31.84	-9.03dB	22.77	22.78	22.81	
2 Txslots	30.90	30.87	30.91	-6.02dB	24.88	24.85	24.89	
PCS1900	Measu	ıred Power	(dBm)	calculation	Avera	ged Power	(dBm)	
EGPRS (GMSK)	810	661	512		810	661	512	
1 Txslot	29.62	29.27	29.18	-9.03dB	20.59	20.24	20.15	
2 Txslots	28.27	28.02	27.91	-6.02dB	22.25	22.00	21.89	

NOTES:

To average the power, the division factor is as follows:

1TX-slot = 1 transmit time slot out of 8 time slots=> conducted power divided by (8/1) => -9.03dB

2TX-slots = 2 transmit time slots out of 8 time slots=> conducted power divided by (8/2) => -6.02dB

According to the conducted power as above, the body measurements are performed with 2Txslots of GPRS/EGPRS for GSM850 and PCS1900.

<sup>1)</sup> Division Factors



### 11.3 WCDMA Measurement result

**Table 11.9: The conducted Power for WCDMA850** 

ltom	band	FDDV result						
ltem	ARFCN	4233(846.6MHz)	4182(836.4MHz)	4132(826.4MHz)				
WCDMA	\	23.38	23.50	23.60				
	1	18.51	18.54	18.73				
	2	17.57	17.57	17.79				
HSUPA	3	18.03	18.03	18.17				
	4	18.54	18.57	18.71				
	5	21.47	21.48	21.67				

## 11.3 BT Measurement result

The output power of BT antenna is as following:

Mode	Conducted Power (dBm)							
iviode	Channel 0 (2402MHz)	Channel 39 (2441MHz)	Channel 78(2480MHz)					
GFSK	7.53	8.57	9.25					

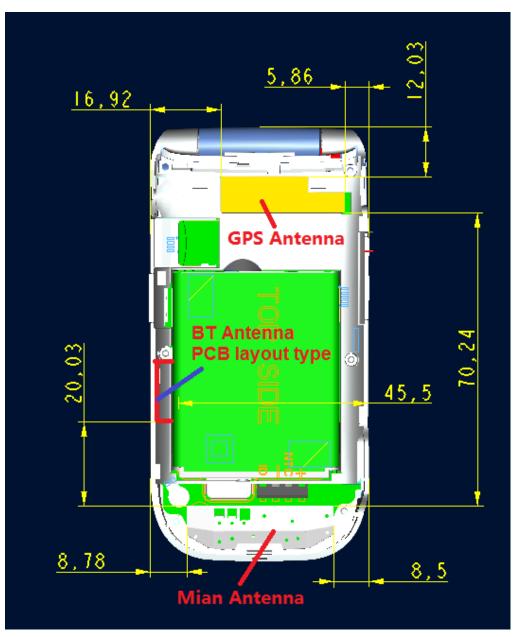


## 12 Simultaneous TX SAR Considerations

#### 12.1 Introduction

The following procedures adopted from "FCC SAR Considerations for Cell Phones with Multiple Transmitters" are applicable to handsets with built-in unlicensed transmitters such as 802.11 a/b/g and Bluetooth devices which may simultaneously transmit with the licensed transmitter. For this device, the BT can transmit simultaneous with other transmitters.

## 12.2 Transmit Antenna Separation Distances



**Picture 12.1 Antenna Locations** 



#### 12.3Standalone SAR Test Exclusion Considerations

Standalone 1-g head or bodySAR evaluation by measurement or numerical simulation is not required when thecorresponding SAR Exclusion Threshold condition, listed below, is satisfied. The 1-g SAR test exclusion threshold for 100 MHz to 6 GHz at test separation distances≤ 50 mm are determined by:

[(max. power of channel, including tune-up tolerance, mW)/(min. test separation distance, mm)]  $\cdot$  [ $\sqrt{f(GHz)}$ ]  $\leq$  3.0 for 1-g SAR, where

- f(GHz) is the RF channel transmit frequency in GHz
- Power and distance are rounded to the nearest mW and mm before calculation
- The result is rounded to one decimal place for comparison

Table 12.1: Standalone SAR test exclusion considerations

Band/Mode	F(GHz)	Position	SAR test exclusion	RF outp	SAR test	
	F(GHZ)	Position	threshold(mW)	dBm	mW	exclusion
Bluetooth	2.441	Head	9.60	9.25	8.41	Yes
	2.441	Body	19.20	9.25	8.41	Yes



### 13Evaluation of Simultaneous

Table 13.1: The sum of reported SAR values for GSM/WCDMA and Bluetooth

	Position	WCDMA	BT*	Sum	
Highest reported	Right hand, Touch cheek	0.86	0.37	1.23	
SAR value for Head	,				
Highest reported	Rear	0.94	0.19	1.13	
SAR value for Body	Neai	0.94	0.19	1.13	

BT\* - Estimated SAR for Bluetooth (see the table 13.2)

Table 13.2: Estimated SAR for Bluetooth

Position	F (GHz)	Distance (mm)	Upper limi	Estimated <sub>1g</sub>	
	r (GHZ)	Distance (mm)	dBm	mW	(W/kg)
Head	2.441	5	9.5	8.91	0.37
Body	2.441	10	9.5	8.91	0.19

<sup>\* -</sup> Maximum possible output power declared by manufacturer

When standalone SAR test exclusion applies to an antenna that transmits simultaneously with other antennas, the standalone SAR must be estimated according to following to determine simultaneous transmission SAR test exclusion:

(max. power of channel, including tune-up tolerance, mW)/(min. test separation distance,mm)]·[ $\sqrt{f(GHz)/x}$ ] W/kg for test separation distances  $\leq$  50 mm; where x = 7.5 for 1-g SAR.

When the minimum test separation distance is < 5 mm, a distance of 5 mm is applied to determine SAR test exclusion

#### **Conclusion:**

According to the above tables, the sum of reported SAR values is < 1.6W/kg. So the simultaneous transmission SAR with volume scans is not required.



## 14 SAR Test Result

It is determined by user manual for the distance between the EUT and the phantom bottom.

The distance is 10mm and just applied to the condition of body worn accessory.

It is performed for all SAR measurements with area scan based 1-g SAR estimation (Fast SAR). A zoom scan measurement is added when the estimated 1-gSAR is the highest measured SAR in each exposure configuration, wireless mode and frequency band combination or more than 1.2W/kg.

The calculated SAR is obtained by the following formula:

Reported SAR = Measured SAR  $\times 10^{(P_{Target} - P_{Measured})/10}$ 

Where P<sub>Target</sub> is the power of manufacturing upper limit;

P<sub>Measured</sub> is the measured power in chapter 11.

Mode	Duty Cycle
Speech for GSM850/1900	1:8.3
GPRS/EGPRS for GSM850/1900	1:4
WCDMA850	1:1

#### 14.1SAR results for Fast SAR

Table 14.1: SAR Values (GSM 850 MHz Band - Head)

	Applicat Town and two CO FOC													
				Ambient	Temperature	: 22.5°C L	iquid Tempera	ture: 22.0°C						
Freque	-requency Test		Figure	Conducted	Max.	Measured	Reported	Measured	Reported	Power				
		Side	Position	No.	Power	tune-upPow	SAR(10g)	SAR(10g)	SAR(1g)	SAR(1g)(	Drift			
MHz	Ch.		Position	INO.	(dBm)	er (dBm)	(W/kg)	(W/kg)	(W/kg)	W/kg)	(dB)			
848.8	251	Left	Touch	Fig.1	31.86	32.5	0.302	0.35	0.515	0.60	-0.06			
836.6	190	Left	Touch	/	31.86	32.5	0.241	0.28	0.385	0.45	-0.04			
824.2	128	Left	Touch	/	31.90	32.5	0.186	0.21	0.300	0.34	0.02			
848.8	251	Left	Tilt	/	31.86	32.5	0.043	0.05	0.062	0.07	0.10			
836.6	190	Left	Tilt	/	31.86	32.5	0.037	0.04	0.053	0.06	0.05			
824.2	128	Left	Tilt	/	31.90	32.5	0.031	0.04	0.046	0.05	0.10			
848.8	251	Right	Touch	/	31.86	32.5	0.184	0.21	0.282	0.33	-0.07			
836.6	190	Right	Touch	/	31.86	32.5	0.140	0.16	0.212	0.25	-0.09			
824.2	128	Right	Touch	/	31.90	32.5	0.114	0.13	0.175	0.20	-0.07			
848.8	251	Right	Tilt	/	31.86	32.5	0.048	0.06	0.068	80.0	-0.04			
836.6	190	Right	Tilt	/	31.86	32.5	0.036	0.04	0.052	0.06	-0.05			
824.2	128	Right	Tilt	/	31.90	32.5	0.033	0.04	0.043	0.05	0.06			



## Table 14.2: SAR Values (GSM 850 MHz Band-Body)

			Am	bient Temp	erature: 22.5°	C Liqu	id Temperatu	re: 22.0 °C			
Frequ	ency Ch.	Mode (number of	Test Position	Figure No.	Conducted	Max. tune-upP ower	Measured SAR(10g)	Reported SAR(10g)	Measured SAR(1g)	Reported SAR(1g)(	Power Drift
IVITZ	Cn.	timeslots)			(dBm)	(dBm)	(W/kg)	(W/kg)	(W/kg)	W/kg)	(dB)
848.8	251	GPRS (2)	Front	/	30.91	31.4	0.219	0.25	0.311	0.35	-0.16
836.6	190	GPRS (2)	Front	/	30.87	31.4	0.194	0.22	0.278	0.31	-0.05
824.2	128	GPRS (2)	Front	/	30.91	31.4	0.169	0.19	0.246	0.28	-0.01
848.8	251	GPRS (2)	Rear	Fig.2	30.91	31.4	0.462	0.52	0.633	0.71	-0.05
836.6	190	GPRS (2)	Rear	/	30.87	31.4	0.365	0.41	0.533	0.60	-0.08
824.2	128	GPRS (2)	Rear	/	30.91	31.4	0.307	0.34	0.448	0.50	-0.04
848.8	251	GPRS (2)	Rear Unfold	/	30.91	31.4	0.433	0.48	0.581	0.65	-0.01
836.6	190	GPRS (2)	Rear Unfold	/	30.87	31.4	0.343	0.39	0.498	0.56	-0.08
824.2	128	GPRS (2)	Rear Unfold	/	30.91	31.4	0.306	0.34	0.412	0.46	0.09
848.8	251	EGPRS (2)	Rear	/	30.91	31.4	0.402	0.45	0.587	0.66	-0.06
848.8	251	Speech	Rear headset	/	31.86	32.5	0.189	0.22	0.282	0.33	0.15

Note1: The distance between the EUT and the phantom bottom is 10mm.

Note2: The type of Headset is CCB3160A15C1.

Table 14.3: SAR Values(GSM1900 MHz Band - Head)

				Ambient	Temperature:	22.5 °C L	iquid Tempera	ture: 22.0 °C			
Freque	ency		Test	Eiguro	Conducted	Max.	Measured	Reported	Measured	Reported	Power
		Side	Position	Figure No.	Power	tune-upPow	SAR(10g)	SAR(10g)	SAR(1g)	SAR(1g)(	Drift
MHz	Ch.		Position	NO.	(dBm)	er (dBm)	(W/kg)	(W/kg)	(W/kg)	W/kg)	(dB)
1909.8	810	Left	Touch	/	29.58	29.8	0.183	0.19	0.305	0.32	0.11
1880	661	Left	Touch	/	29.30	29.8	0.183	0.21	0.318	0.36	0.10
1850.2	512	Left	Touch	Fig.3	29.18	29.8	0.226	0.26	0.368	0.42	0.03
1909.8	810	Left	Tilt	/	29.58	29.8	0.031	0.03	0.051	0.05	0.10
1880	661	Left	Tilt	/	29.30	29.8	0.038	0.04	0.062	0.07	0.10
1850.2	512	Left	Tilt	/	29.18	29.8	0.047	0.05	0.078	0.09	0.10
1909.8	810	Right	Touch	/	29.58	29.8	0.097	0.10	0.168	0.18	-0.01
1880	661	Right	Touch	/	29.30	29.8	0.102	0.11	0.179	0.20	0.03
1850.2	512	Right	Touch	/	29.18	29.8	0.142	0.16	0.213	0.25	-0.08
1909.8	810	Right	Tilt	/	29.58	29.8	0.030	0.03	0.050	0.05	0.10
1880	661	Right	Tilt	/	29.30	29.8	0.036	0.04	0.060	0.07	0.12
1850.2	512	Right	Tilt	/	29.18	29.8	0.052	0.06	0.086	0.10	-0.02



Table 14.4: SAR Values (GSM 1900 MHz Band-Body)

			Ambi	ent Temp	erature: 22.5°	C Liquid	Temperature	: 22.0 °C			
Freque	encv	Mode	Test	Figure	Conducted	Max.	Measured	Reported	Measured	Reported	Power
	1	(number of	Position	Figure No.	Power	tune-upPo	SAR(10g)	SAR(10g)	SAR(1g)	SAR(1g)(	Drift
MHz	Ch.	timeslots)	Position	NO.	(dBm)	wer (dBm)	(W/kg)	(W/kg)	(W/kg)	W/kg)	(dB)
1909.8	810	GPRS (2)	Front	/	28.26	28.6	0.230	0.25	0.391	0.42	0.1
1880	661	GPRS (2)	Front	/	28.02	28.6	0.237	0.27	0.400	0.46	0.08
1850.2	512	GPRS (2)	Front	/	27.96	28.6	0.239	0.28	0.399	0.46	0.06
1909.8	810	GPRS (2)	Rear	Fig.4	28.26	28.6	0.407	0.44	0.736	0.80	-0.04
1880	661	GPRS (2)	Rear	/	28.02	28.6	0.389	0.44	0.703	0.80	0.01
1850.2	512	GPRS (2)	Rear	/	27.96	28.6	0.382	0.44	0.690	0.80	-0.05
1909.8	810	GPRS (2)	Rear	/	28.26	28.6	0.204	0.22	0.340	0.37	-0.03
1909.6	010		Unfold		20.20	20.0	0.204	0.22	0.340	0.37	-0.03
1880	661	GPRS (2)	Rear	/	28.02	28.6	0.228	0.26	0.379	0.43	0.08
1000	001		Unfold		20.02	20.0	0.220	0.20	0.579	0.43	0.00
1850.2	512	GPRS (2)	Rear	,	27.96	28.6	0.224	0.26	0.371	0.43	-0.05
1000.2	312		Unfold	,	27.90	20.0	0.224	0.20	0.57 1	0.43	-0.03
1909.8	810	EGPRS (2)	Rear	/	28.27	28.6	0.404	0.44	0.729	0.79	-0.03
1909.8	810	Speech	Rear	,	29.58	29.8	0.236	0.25	0.374	0.39	0.06
1303.0	010	Ореесп	Headset	,	29.30	23.0	0.230	0.23	0.374	0.39	0.00

Note1: The distance between the EUT and the phantom bottom is 10mm.

Note2: The type of Headset is CCB3160A15C1.

Table 14.5: SAR Values(WCDMA 850 MHz Band - Head)

				Ambient	Temperature:	22.5 °C Li	quid Tempera	ture: 22.0 °C	•		
Frequ	iency		Toot	Figure	Conducted	Max.	Measured	Reported	Measured	Reported	Power
	<u> </u>	Side	Test	Figure	Power	tune-upPowe	SAR(10g)	SAR(10g)	SAR(1g)	SAR(1g)(	Drift
MHz	Ch.		Position	No.	(dBm)	r (dBm)	(W/kg)	(W/kg)	(W/kg)	W/kg)	(dB)
846.6	4233	Left	Touch	/	23.38	24	0.360	0.42	0.546	0.63	0.09
836.4	4182	Left	Touch	/	23.5	24	0.311	0.35	0.515	0.58	0.01
826.4	4132	Left	Touch	/	23.6	24	0.256	0.28	0.420	0.46	-0.02
846.6	4233	Left	Tilt	/	23.38	24	0.045	0.05	0.066	0.08	0.14
836.4	4182	Left	Tilt	/	23.5	24	0.039	0.04	0.057	0.06	-0.08
826.4	4132	Left	Tilt	/	23.6	24	0.035	0.04	0.052	0.06	-0.03
846.6	4233	Right	Touch	Fig.5	23.38	24	0.422	0.49	0.742	0.86	0.09
836.4	4182	Right	Touch	/	23.5	24	0.390	0.44	0.676	0.76	0.09
826.4	4132	Right	Touch	/	23.6	24	0.265	0.29	0.487	0.53	0.11
846.6	4233	Right	Tilt	/	23.38	24	0.063	0.07	0.091	0.11	-0.13
836.4	4182	Right	Tilt	/	23.5	24	0.056	0.06	0.080	0.09	-0.10
826.4	4132	Right	Tilt	1	23.6	24	0.033	0.04	0.047	0.05	0.03



## Table 14.6: SAR Values (WCDMA 850 MHz Band-Body)

Ambient Temperature: 22.5 °C Liquid Temperature: 22.0 °C  Conducted Max Measured Reported Measured Rep				ent Temperatu	ıre: 22.5°C	Liquid Tempe	rature: 22.0°	CC		
Frequ	iencv	Test	Figure	Conducted	Max.	Measured	Reported	Measured	Reported	Power
		Position	No.	Power	tune-upPowe	SAR(10g)	SAR(10g)	SAR(1g)	SAR(1g)(	Drift
MHz	Ch.	Position	NO.	(dBm)	r (dBm)	(W/kg)	(W/kg)	(W/kg)	W/kg)	(dB)
846.6	4233	Front	/	23.38	24	0.305	0.35	0.427	0.49	0.06
836.4	4182	Front	/	23.5	24	0.278	0.31	0.400	0.45	-0.01
826.4	4132	Front	/	23.6	24	0.277	0.30	0.418	0.46	0.08
846.6	4233	Rear	Fig.6	23.38	24	0.589	0.68	0.816	0.94	-0.01
836.4	4182	Rear	/	23.5	24	0.526	0.59	0.768	0.86	0.01
826.4	4132	Rear	/	23.6	24	0.545	0.60	0.795	0.87	-0.04
846.6	4233	Rear	,	23.38	24	0.551	0.64	0.784	0.00	0.03
040.0	4233	Unfold	,	23.30	24	0.551	0.04	0.764	0.90	0.03
836.4	4182	Rear	/	23.5	24	0.519	0.58	0.758	0.85	-0.13
030.4	4102	Unfold	,	23.3	24	0.519	0.56	0.736	0.65	-0.13
826.4	4132	Rear	,	23.6	24	0.521	0.57	0.779	0.85	-0.02
020.4	4132	Unfold	,	23.0	24	0.521	0.57	0.779	0.65	-0.02
846.6	4233	Rear	,	23.38	24	0.336	0.39	0.490	0.57	0.01
040.0	4233	Headset	,	20.00	24	0.550	0.39	0.490	0.37	0.01

Note1: The distance between the EUT and the phantom bottom is 10mm.

Note2: The type of Headset is CCB3160A15C1.



## 14.2SAR results for Standard procedure

There is zoom scan measurement to beadded forthe highest measured SAR in each exposure configuration/band.

## Table 14.7: SAR Values (GSM 850 MHz Band - Head)

				Ambient	:Temperature:	: 22.5 °C L	iquid Tempera	ture: 22.0 °C			
Frequ	ency		Test	Figure	Conducted	Max.	Measured	Reported	Measured	Reported	Power
-	Ť	Side		Figure	Power	tune-upPow	SAR(10g)	SAR(10g)	SAR(1g)	SAR(1g)(	Drift
MHz	Ch.		Position	No.	(dBm)	er (dBm)	(W/kg)	(W/kg)	(W/kg)	W/kg)	(dB)
848.8 251 Left Touch Fig.1 31.86 32.5 0.302 <b>0.35</b> 0.515 <b>0.60</b> -0.0								-0.06			

#### Table 14.8: SAR Values (GSM 850 MHz Band-Body)

			Ambi	ent Tempe	rature: 22.5°C	Liquid	l Temperature	e: 22.0 °C			
Frequ MHz	ency Ch.	Mode (number of timeslots)	Test Position	Figure No.	Conducted Power (dBm)	Max. tune-upP ower (dBm)	Measured SAR(10g) (W/kg)	Reported SAR(10g) (W/kg)	Measured SAR(1g) (W/kg)	Reported SAR(1g)( W/kg)	Power Drift (dB)
848.8	251	GPRS (2)	Rear	Fig.2	30.91	31.4	0.462	0.52	0.633	0.71	-0.05

Note1: The distance between the EUT and the phantom bottom is 10mm.

## Table 14.9: SAR Values (GSM 1900 MHz Band - Head)

							•			,		
					Ambient	Temperature:	22.5 °C L	iquid Tempera	ture: 22.0 °C			
Fi	reque	ency		Test	Eiguro	Conducted	Max.	Measured	Reported	Measured	Reported	Power
		,	Side	Position	Figure No.	Power	tune-upPow	SAR(10g)	SAR(10g)	SAR(1g)	SAR(1g)(	Drift
M	Hz	Ch.		FUSITION	INO.	(dBm)	er (dBm)	(W/kg)	(W/kg)	(W/kg)	W/kg)	(dB)
185	50.2	512	Left	Touch	Fig.3	29.18	29.8	0.226	0.26	0.368	0.42	0.03

## Table 14.10: SAR Values (GSM 1900 MHz Band-Body)

			Ambier	nt Temper	ature: 22.5°C	Liquid T	emperature:	22.0°C			
Freque	encv	Mode	Toot	Figure	Conducted	Max.	Measured	Reported	Measured	Reported	Power
	I	(number of	Test	Figure	Power	tune-upPo	SAR(10g)	SAR(10g)	SAR(1g)	SAR(1g)(	Drift
MHz	Ch.	timeslots)	Position	No.	(dBm)	wer (dBm)	(W/kg)	(W/kg)	(W/kg)	W/kg)	(dB)
1909.8	810	GPRS (2)	Rear	Fig.4	28.26	28.6	0.407	0.44	0.736	0.80	-0.04

Note1: The distance between the EUT and the phantom bottom is 10mm.

#### Table 14.11: SAR Values (WCDMA 850 MHz Band - Head)

				-						,		
					Ambient	Temperature:	22.5 °C Li	quid Tempera	ture: 22.0 °C			
Frequency Test Figure Conducted Max. Measured Reported Reported Power										Power		
	'	, 	Side	Position	No.	Power	tune-upPowe	SAR(10g)	SAR(10g)	SAR(1g)	SAR(1g)(	Drift
	MHz	Ch.		FUSITION	INO.	(dBm)	r (dBm)	(W/kg)	(W/kg)	(W/kg)	W/kg)	(dB)
	846.6	4233	Right	Touch	Fig.5	23.38	24	0.422	0.49	0.742	0.86	0.09

## Table 14.12: SAR Values (WCDMA 850 MHz Band-Body)

			Ambi	ient Temperatu	ıre: 22.5°C	Liquid Tempe	rature: 22.0°	°C		
Fregu	uency	Toot	Figure	Conducted	Max.	Measured	Reported	Measured	Reported	Power
	1	Test	Figure	Power	tune-upPowe	SAR(10g)	SAR(10g)	SAR(1g)	SAR(1g)(	Drift
MHz	Ch.	Position	No.	(dBm)	r (dBm)	(W/kg)	(W/kg)	(W/kg)	W/kg)	(dB)
846.6	846.6 4233 Rear Fig.6				24	0.589	0.68	0.816	0.94	-0.01

Note1: The distance between the EUT and the phantom bottom is 10mm.



## 15SAR Measurement Variability

SAR measurement variability must be assessed for each frequency band, which is determined by the SARprobe calibration point and tissue-equivalent medium used for the device measurements. When both headand body tissue-equivalent media are required for SAR measurements in a frequency band, the variabilitymeasurement procedures should be applied to the tissue medium with the highest measured SAR, using the highest measured SAR configuration for that tissue-equivalent medium.

The following procedures are applied to determine if repeatedmeasurements are required.

- 1) Repeated measurement is not required when the original highest measured SAR is < 0.80 W/kg; steps2) through 4) do not apply.
- 2) When the original highest measured SAR is ≥ 0.80 W/kg, repeat that measurement once.
- 3) Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is > 1.20 or when the original or repeated measurement is ≥ 1.45W/kg (~ 10% from the 1-g SAR limit).
- 4) Perform a third repeated measurement only if the original, first or second repeated measurement is ≥1.5 W/kg and the ratio of largest to smallest SAR for the original, first and second repeatedmeasurements is > 1.20.

Table 15.1: SAR Measurement Variability for Body WCDMA 850 (1g)

Frequ	iency	Test	Spacing	Original	First	The	Second
MHz	Ch.	Position	(mm)	SAR (W/kg)	Repeated SAR (W/kg)	Ratio	Repeated SAR (W/kg)
846.6	4233	Rear	10	0.816	0.821	1.01	1



# **16 Measurement Uncertainty**

## 16.1 Measurement Uncertainty for Normal SAR Tests (300MHz~3GHz)

10.	i weasurement of	icei te	illity for 140	illiai SAIX	ICSIS	(SOOI	VII 12~	JUI 12	,	
No.	Error Description	Type	Uncertainty	Probably	Div.	(Ci)	(Ci)	Std.	Std.	Degree
			value	Distribution		1g	10g	Unc.	Unc.	of
								(1g)	(10g)	freedo
										m
Meas	surement system									
1	Probe calibration	В	5.5	N	1	1	1	5.5	5.5	8
2	Isotropy	В	4.7	R	$\sqrt{3}$	0.7	0.7	1.9	1.9	8
3	Boundary effect	В	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	8
4	Linearity	В	4.7	R	$\sqrt{3}$	1	1	2.7	2.7	8
5	Detection limit	В	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	8
6	Readout electronics	В	0.3	R	$\sqrt{3}$	1	1	0.3	0.3	8
7	Response time	В	0.8	R	$\sqrt{3}$	1	1	0.5	0.5	∞
8	Integration time	В	2.6	R	$\sqrt{3}$	1	1	1.5	1.5	8
9	RF ambient conditions-noise	В	0	R	$\sqrt{3}$	1	1	0	0	8
10	RFambient conditions-reflection	В	0	R	$\sqrt{3}$	1	1	0	0	8
11	Probe positioned mech. restrictions	В	0.4	R	$\sqrt{3}$	1	1	0.2	0.2	8
12	Probe positioning with respect to phantom shell	В	2.9	R	$\sqrt{3}$	1	1	1.7	1.7	8
13	Post-processing	В	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	8
<u> </u>		I.	Test	sample related	ì	l .	I.	I.		
14	Test sample positioning	A	3.3	N	1	1	1	3.3	3.3	71
15	Device holder uncertainty	A	3.4	N	1	1	1	3.4	3.4	5
16	Drift of output power	В	5.0	R	$\sqrt{3}$	1	1	2.9	2.9	8
			Phan	tom and set-u	p					
17	Phantom uncertainty	В	4.0	R	$\sqrt{3}$	1	1	2.3	2.3	8
18	Liquid conductivity (target)	В	5.0	R	$\sqrt{3}$	0.64	0.43	1.8	1.2	8
19	Liquid conductivity (meas.)	A	2.06	N	1	0.64	0.43	1.32	0.89	43
20	Liquid permittivity (target)	В	5.0	R	$\sqrt{3}$	0.6	0.49	1.7	1.4	8
21	Liquid permittivity (meas.)	A	1.6	N	1	0.6	0.49	1.0	0.8	521



Combined standard uncertainty	$u_c' = \sqrt{\sum_{i=1}^{21} c_i^2 u_i^2}$			9.25	9.12	257
Expanded uncertainty (confidence interval of 95 %)	$u_e = 2u_c$			18.5	18.2	

16.2 Measurement Uncertainty for Normal SAR Tests (3~6GHz)

z Wieasurement Oi	icei ta	inity for No	IIIIai SAN	16212	13~0	9112)			
Error Description	Type	Uncertainty	Probably	Div.	(Ci)	(Ci)	Std.	Std.	Degree
		value	Distribution		1g	10g	Unc.	Unc.	of
							(1g)	(10g)	freedo
									m
surement system									
Probe calibration	В	6.5	N	1	1	1	6.5	6.5	∞
Isotropy	В	4.7	R	$\sqrt{3}$	0.7	0.7	1.9	1.9	∞
Boundary effect	В	2.0	R	$\sqrt{3}$	1	1	1.2	1.2	∞
Linearity	В	4.7	R	$\sqrt{3}$	1	1	2.7	2.7	∞
Detection limit	В	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞
Readout electronics	В	0.3	R	$\sqrt{3}$	1	1	0.3	0.3	∞
Response time	В	0.8	R	$\sqrt{3}$	1	1	0.5	0.5	∞
Integration time	В	2.6	R	$\sqrt{3}$	1	1	1.5	1.5	∞
RF ambient conditions-noise	В	0	R	$\sqrt{3}$	1	1	0	0	∞
RFambient conditions-reflection	В	0	R	$\sqrt{3}$	1	1	0	0	∞
Probe positioned mech. restrictions	В	0.8	R	$\sqrt{3}$	1	1	0.5	0.5	∞
Probe positioning with respect to phantom shell	В	6.7	R	$\sqrt{3}$	1	1	3.9	3.9	∞
Post-processing	В	4.0	R	$\sqrt{3}$	1	1	2.3	2.3	∞
		Test	sample related	d					
Test sample positioning	A	3.3	N	1	1	1	3.3	3.3	71
Device holder uncertainty	A	3.4	N	1	1	1	3.4	3.4	5
Drift of output power	В	5.0	R	$\sqrt{3}$	1	1	2.9	2.9	∞
		Phan	tom and set-u	р					
Phantom uncertainty	В	4.0	R	$\sqrt{3}$	1	1	2.3	2.3	∞
Liquid conductivity (target)	В	5.0	R	$\sqrt{3}$	0.64	0.43	1.8	1.2	∞
Liquid conductivity	A	2.06	N	1	0.64	0.43	1.32	0.89	43
	surement system  Probe calibration  Isotropy  Boundary effect  Linearity  Detection limit  Readout electronics  Response time  Integration time  RF ambient  conditions-noise  RFambient  conditions-reflection  Probe positioned  mech. restrictions  Probe positioning  with respect to phantom shell  Post-processing  Test sample positioning  Device holder  uncertainty  Drift of output power  Phantom uncertainty  Liquid conductivity (target)	Error Description  Surement system  Probe calibration  Isotropy  Banch Banch Banch Banch Banch Banch Probe positioned mech. restrictions  Probe positioning with respect to phantom shell  Post-processing  Test sample positioning Device holder uncertainty Drift of output power  Phantom uncertainty Banch Ban	Error Description  Surement system Probe calibration B 6.5 Isotropy B 4.7 Boundary effect B 2.0 Linearity B 4.7 Detection limit B 1.0 Readout electronics B 0.3 Response time B 2.6 RF ambient conditions-noise RFambient conditions-reflection Probe positioned mech. restrictions Probe positioning with respect to phantom shell Post-processing B 4.0  Test sample positioning Device holder uncertainty Drift of output power  Phantom uncertainty Liquid conductivity (target)  B 6.5  Uncertainty value  Uncertainty value  Uncertainty  B 6.5  A 7.  Uncertainty  D 8 6.5  A 9.3  B 1.0  A 9.8  B 1.0  B 1.0	Error Description Type Uncertainty value Distribution  Surement system  Probe calibration B 6.5 N Isotropy B 4.7 R Boundary effect B 2.0 R Linearity B 4.7 R Detection limit B 1.0 R Readout electronics B 0.3 R Response time B 0.8 R Integration time B 2.6 R  RF ambient conditions-noise RFambient conditions-reflection B 0.8 R  Probe positioned mech. restrictions Probe positioning B 4.0 R  Test sample positioning B 4.0 R  Test sample positioning Device holder uncertainty Drift of output power  Phantom uncertainty B 4.0 R  Liquid conductivity (target)  B 5.0 R	Error Description       Type       Uncertainty value       Probably Distribution       Div.         surement system         Probe calibration       B       6.5       N       1         Isotropy       B       4.7       R $\sqrt{3}$ Boundary effect       B       2.0       R $\sqrt{3}$ Linearity       B       4.7       R $\sqrt{3}$ Linearity       B       4.7       R $\sqrt{3}$ Detection limit       B       1.0       R $\sqrt{3}$ Readout electronics       B       0.3       R $\sqrt{3}$ Response time       B       0.8       R $\sqrt{3}$ RF       ambient conditions-noise       B       0.8       R $\sqrt{3}$ RFambient conditions-reflection       B       0       R $\sqrt{3}$ Probe positioned mech. restrictions       B       0.8       R $\sqrt{3}$ Probe positioning with respect to phantom shell       B       6.7       R $\sqrt{3}$ Post-processing       B       4.0       R $\sqrt{3}$ Test sample positioning positioning positioning       A       3.3       N <td>Error DescriptionType valueUncertainty valueProbably DistributionDiv. Its</td> <td>Error Description         Type value         Uncertainty value         Probably Distribution         Div. lig         (Ci) log           Surement system           Probe calibration         B         6.5         N         1         1         1           Isotropy         B         4.7         R         <math>\sqrt{3}</math>         0.7         0.7           Boundary effect         B         2.0         R         <math>\sqrt{3}</math>         1         1           Linearity         B         4.7         R         <math>\sqrt{3}</math>         1         1           Detection limit         B         1.0         R         <math>\sqrt{3}</math>         1         1           Readout electronics         B         0.3         R         <math>\sqrt{3}</math>         1         1           Response time         B         0.8         R         <math>\sqrt{3}</math>         1         1           RF ambient conditions-noise         B         0         R         <math>\sqrt{3}</math>         1         1           RFambient conditions-reflection         B         0         R         <math>\sqrt{3}</math>         1         1           Probe positioning with respect to phantom shell         B         6.7         R         <math>\sqrt{3}</math>         1         1     &lt;</td> <td>Surement system         value         Distribution         lg         l0g         Unc. (lg)           Probe calibration         B         6.5         N         1         1         1         5.5           Isotropy         B         4.7         R         √3         0.7         0.7         1.9           Boundary effect         B         2.0         R         √3         1         1         1.2           Linearity         B         4.7         R         √3         1         1         1.2           Detection limit         B         1.0         R         √3         1         1         0.6           Readout electronics         B         0.3         R         √3         1         1         0.6           Readout electronics         B         0.8         R         √3         1         1         0.6           Response time         B         0.8         R         √3         1         1         0.5           RF         ambient conditions-noise         B         0.8         R         √3         1         1         0.5           RFambient conditions-reflection phantom shell         B         0.8         R</td> <td>  Type   Uncertainty   Probably   Div.   Ci)   Ci)   Std.   Std.   Unc.   Cin   Cin   Unc.   Cin   Cin</td>	Error DescriptionType valueUncertainty valueProbably DistributionDiv. Its	Error Description         Type value         Uncertainty value         Probably Distribution         Div. lig         (Ci) log           Surement system           Probe calibration         B         6.5         N         1         1         1           Isotropy         B         4.7         R $\sqrt{3}$ 0.7         0.7           Boundary effect         B         2.0         R $\sqrt{3}$ 1         1           Linearity         B         4.7         R $\sqrt{3}$ 1         1           Detection limit         B         1.0         R $\sqrt{3}$ 1         1           Readout electronics         B         0.3         R $\sqrt{3}$ 1         1           Response time         B         0.8         R $\sqrt{3}$ 1         1           RF ambient conditions-noise         B         0         R $\sqrt{3}$ 1         1           RFambient conditions-reflection         B         0         R $\sqrt{3}$ 1         1           Probe positioning with respect to phantom shell         B         6.7         R $\sqrt{3}$ 1         1     <	Surement system         value         Distribution         lg         l0g         Unc. (lg)           Probe calibration         B         6.5         N         1         1         1         5.5           Isotropy         B         4.7         R         √3         0.7         0.7         1.9           Boundary effect         B         2.0         R         √3         1         1         1.2           Linearity         B         4.7         R         √3         1         1         1.2           Detection limit         B         1.0         R         √3         1         1         0.6           Readout electronics         B         0.3         R         √3         1         1         0.6           Readout electronics         B         0.8         R         √3         1         1         0.6           Response time         B         0.8         R         √3         1         1         0.5           RF         ambient conditions-noise         B         0.8         R         √3         1         1         0.5           RFambient conditions-reflection phantom shell         B         0.8         R	Type   Uncertainty   Probably   Div.   Ci)   Ci)   Std.   Std.   Unc.   Cin   Cin   Unc.   Cin   Cin



	(meas.)									
20	Liquid permittivity (target)	В	5.0	R	$\sqrt{3}$	0.6	0.49	1.7	1.4	8
21	Liquid permittivity (meas.)	A	1.6	N	1	0.6	0.49	1.0	0.8	521
Combined standard uncertainty		$u_c^{'} =$	$\sqrt{\sum_{i=1}^{21} c_i^2 u_i^2}$					10.8	10.7	257
Expanded uncertainty (confidence interval of 95 %)		ı	$u_e = 2u_c$					21.6	21.4	

16.3 Measurement Uncertainty for Fast SAR Tests (300MHz~3GHz)

No.	Error Description	Type	Uncertainty	Probably	Div.	(Ci)	(Ci)	Std.	Std.	Degree
			value	Distribution		1g	10g	Unc.	Unc.	of
								(1g)	(10g)	freedo
										m
Mea	Measurement system									
1	Probe calibration	В	5.5	N	1	1	1	5.5	5.5	∞
2	Isotropy	В	4.7	R	$\sqrt{3}$	0.7	0.7	1.9	1.9	∞
3	Boundary effect	В	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞
4	Linearity	В	4.7	R	$\sqrt{3}$	1	1	2.7	2.7	∞
5	Detection limit	В	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞
6	Readout electronics	В	0.3	R	$\sqrt{3}$	1	1	0.3	0.3	∞
7	Response time	В	0.8	R	$\sqrt{3}$	1	1	0.5	0.5	∞
8	Integration time	В	2.6	R	$\sqrt{3}$	1	1	1.5	1.5	∞
9	RF ambient conditions-noise	В	0	R	$\sqrt{3}$	1	1	0	0	8
10	RFambient conditions-reflection	В	0	R	$\sqrt{3}$	1	1	0	0	8
11	Probe positioned mech. Restrictions	В	0.4	R	$\sqrt{3}$	1	1	0.2	0.2	∞
12	Probe positioning with respect to phantom shell	В	2.9	R	$\sqrt{3}$	1	1	1.7	1.7	∞
13	Post-processing	В	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞
14	Fast SAR z-Approximation	В	7.0	R	$\sqrt{3}$	1	1	4.0	4.0	8
Test sample related										
15	Test sample positioning	A	3.3	N	1	1	1	3.3	3.3	71
16	Device holder uncertainty	A	3.4	N	1	1	1	3.4	3.4	5



17	Drift of output power	В	5.0	R	$\sqrt{3}$	1	1	2.9	2.9	∞
		tom and set-uj	)							
18	Phantom uncertainty	В	4.0	R	$\sqrt{3}$	1	1	2.3	2.3	∞
19	Liquid conductivity (target)	В	5.0	R	$\sqrt{3}$	0.64	0.43	1.8	1.2	∞
20	Liquid conductivity (meas.)	A	2.06	N	1	0.64	0.43	1.32	0.89	43
21	Liquid permittivity (target)	В	5.0	R	$\sqrt{3}$	0.6	0.49	1.7	1.4	8
22	Liquid permittivity (meas.)	A	1.6	N	1	0.6	0.49	1.0	0.8	521
Combined standard uncertainty		$u_c^{'} =$	$\sqrt{\sum_{i=1}^{22} c_i^2 u_i^2}$					10.1	9.95	257
Expanded uncertainty (confidence interval of 95 %)		ı	$u_e = 2u_c$					20.2	19.9	

16.4 Measurement Uncertainty for Fast SAR Tests (3~6GHz)

No.	Error Description	Type	Uncertainty	Probably	Div.	(Ci)	(Ci)	Std.	Std.	Degree
			value	Distribution		1g	10g	Unc.	Unc.	of
								(1g)	(10g)	freedo
										m
Mea	surement system									
1	Probe calibration	В	6.5	N	1	1	1	6.5	6.5	∞
2	Isotropy	В	4.7	R	$\sqrt{3}$	0.7	0.7	1.9	1.9	∞
3	Boundary effect	В	2.0	R	$\sqrt{3}$	1	1	1.2	1.2	∞
4	Linearity	В	4.7	R	$\sqrt{3}$	1	1	2.7	2.7	∞
5	Detection limit	В	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞
6	Readout electronics	В	0.3	R	$\sqrt{3}$	1	1	0.3	0.3	∞
7	Response time	В	0.8	R	$\sqrt{3}$	1	1	0.5	0.5	∞
8	Integration time	В	2.6	R	$\sqrt{3}$	1	1	1.5	1.5	∞
9	RF ambient conditions-noise	В	0	R	$\sqrt{3}$	1	1	0	0	8
10	RFambient conditions-reflection	В	0	R	$\sqrt{3}$	1	1	0	0	8
11	Probe positioned mech. Restrictions	В	0.8	R	$\sqrt{3}$	1	1	0.5	0.5	8
12	Probe positioning with respect to phantom shell	В	6.7	R	$\sqrt{3}$	1	1	3.9	3.9	8
13	Post-processing	В	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞

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	1			1		1	1		1	
14	Fast SAR z-Approximation	В	14.0	R	$\sqrt{3}$	1	1	8.1	8.1	8
	Test sample related									
15	Test sample positioning	A	3.3	N	1	1	1	3.3	3.3	71
16	Device holder uncertainty	A	3.4	N	1	1	1	3.4	3.4	5
17	Drift of output power	В	5.0	R	$\sqrt{3}$	1	1	2.9	2.9	8
Phantom and set-up										
18	Phantom uncertainty	В	4.0	R	$\sqrt{3}$	1	1	2.3	2.3	$\infty$
19	Liquid conductivity (target)	В	5.0	R	$\sqrt{3}$	0.64	0.43	1.8	1.2	8
20	Liquid conductivity (meas.)	A	2.06	N	1	0.64	0.43	1.32	0.89	43
21	Liquid permittivity (target)	В	5.0	R	$\sqrt{3}$	0.6	0.49	1.7	1.4	8
22	Liquid permittivity (meas.)	A	1.6	N	1	0.6	0.49	1.0	0.8	521
Combined standard uncertainty		$u_c^{'} =$	$\sqrt{\sum_{i=1}^{22} c_i^2 u_i^2}$					13.3	13.2	257
(con	Expanded uncertainty (confidence interval of $u_e = 2u_c$ 95 %)							26.6	26.4	

# **17 MAIN TEST INSTRUMENTS**

**Table 17.1: List of Main Instruments** 

No.	Name Type		Serial Number	Calibration Date	Valid Period
01	Network analyzer	E5071C	MY46110673	February15,2014	One year
02	Power meter	NRVD	102083	Morob 45 2014	One year
03	Power sensor	NRV-Z5	100542	March 15,2014	
04	Signal Generator	E4438C	MY49070393	February08, 2014	One Year
05	Amplifier	60S1G4	0331848	No Calibration Requested	
06	BTS	E5515C	MY50263375	January30, 2014	One year
07	E-field Probe	SPEAG EX3DV4	3846	September24, 2014	One year
08	DAE	SPEAG DAE4	777	September17, 2014	One year
09	Dipole Validation Kit	SPEAG D835V2	4d069	August28, 2014	One year
10	Dipole Validation Kit	SPEAG D1900V2	5d101	July23, 2014	One year

\*\*\*END OF REPORT BODY\*\*\*



# **ANNEX A Graph Results**

## 850 Left Cheek High

Date: 2015-1-7

Electronics: DAE4 Sn777 Medium: Head 850 MHz

Medium parameters used (interpolated): f = 848.8 MHz;  $\sigma = 0.937$  S/m;  $\varepsilon_r = 42.005$ ;  $\rho = 1000$ 

kg/m<sup>3</sup>

Ambient Temperature: 22.5°C Liquid Temperature: 22.0°C

Communication System: GSM 850 Frequency: 848.8 MHz Duty Cycle: 1:8.3

Probe: EX3DV4 - SN3846 ConvF(9.18, 9.18, 9.18)

Cheek High/Area Scan (61x151x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm

Maximum value of SAR (interpolated) = 0.747 W/kg

**Cheek High/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 2.058 V/m; Power Drift = -0.06 dB

Peak SAR (extrapolated) = 1.20 W/kg

SAR(1 g) = 0.515 W/kg; SAR(10 g) = 0.302 W/kg

Maximum value of SAR (measured) = 0.765 W/kg

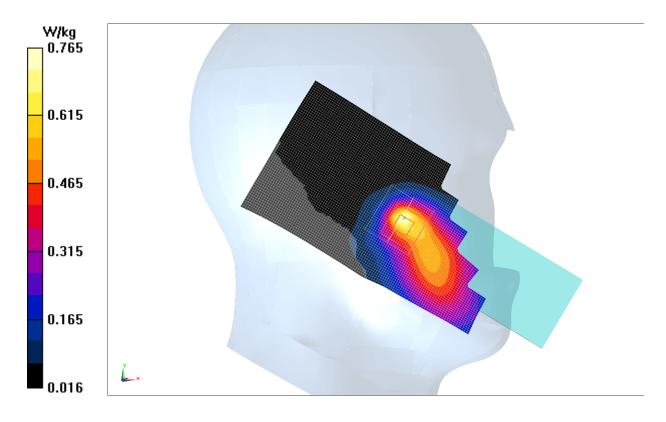


Fig.1 850MHz CH251



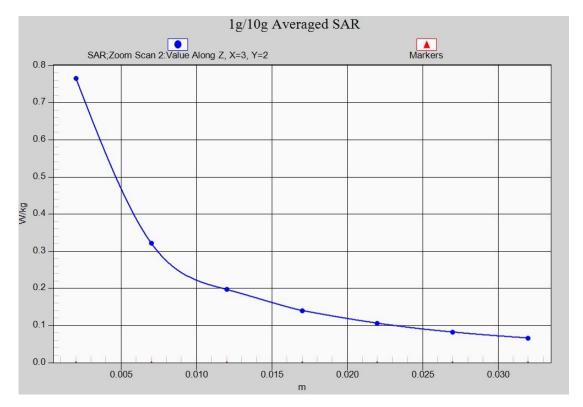


Fig. 1-1 Z-Scan at power reference point (850 MHz CH251)



# 850Body RearHigh with GPRS

Date: 2015-1-7

Electronics: DAE4 Sn777 Medium: Body 850 MHz

Medium parameters used (interpolated): f = 848.8 MHz;  $\sigma = 0.9767$  S/m;  $\varepsilon_r = 54.703$ ;  $\rho = 1000$ 

kg/m<sup>3</sup>

Ambient Temperature: 22.5°C Liquid Temperature: 22.0°C

Communication System: GSM 850 GPRS Frequency: 848.8 MHz Duty Cycle: 1:4

Probe: EX3DV4 - SN3846 ConvF(9.09, 9.09, 9.09)

Rear High/Area Scan (91x61x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm

Maximum value of SAR (interpolated) = 0.671 W/kg

**Rear High/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 23.32 V/m; Power Drift = -0.05 dB

Peak SAR (extrapolated) = 0.800 W/kg

SAR(1 g) = 0.633 W/kg; SAR(10 g) = 0.462 W/kg

Maximum value of SAR (measured) = 0.670 W/kg

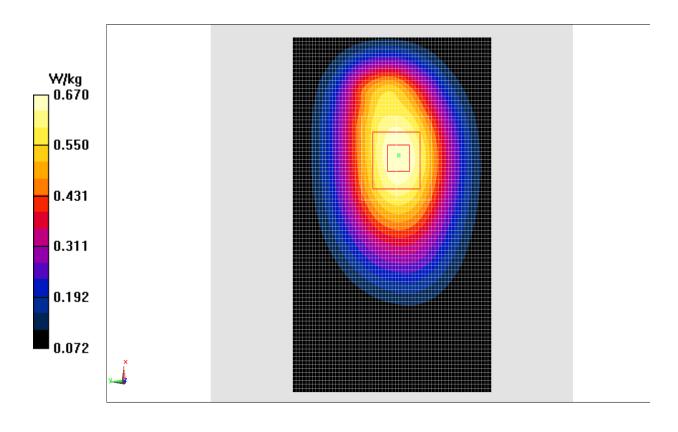


Fig.2 850 MHz CH251



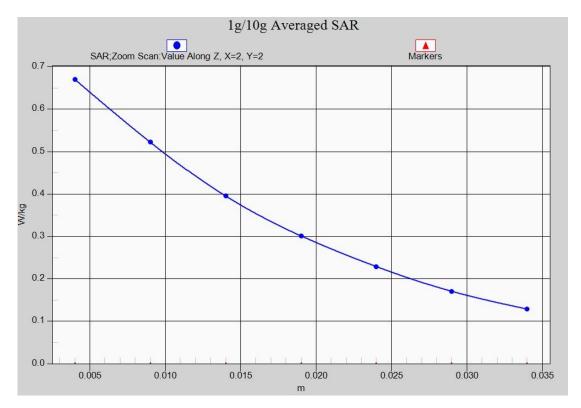


Fig. 2-1 Z-Scan at power reference point (850 MHz CH251)



### 1900 Left Cheek Low

Date: 2015-1-9

Electronics: DAE4 Sn777 Medium: Head 1900 MHz

Medium parameters used: f = 1850.2 MHz;  $\sigma = 1.338 \text{ S/m}$ ;  $\varepsilon_r = 40.274$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Ambient Temperature: 22.5°C Liquid Temperature: 22.0°C

Communication System: GSM 1900MHz Frequency: 1850.2MHz Duty Cycle: 1:8.3

Probe: EX3DV4 - SN3846 ConvF(7.26, 7.26, 7.26)

**Cheek Low/Area Scan (51x151x1):** Interpolated grid: dx=1.000 mm, dy=1.000 mm Maximum value of SAR (interpolated) = 0.479 W/kg

**Cheek Low/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 5.055 V/m; Power Drift = 0.03 dB

Peak SAR (extrapolated) = 0.551 W/kg

SAR(1 g) = 0.368 W/kg; SAR(10 g) = 0.226 W/kgMaximum value of SAR (measured) = 0.470 W/kg

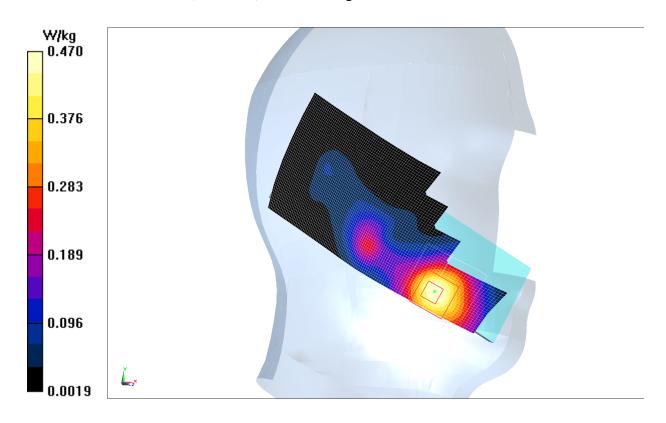


Fig.3 1900 MHz CH512



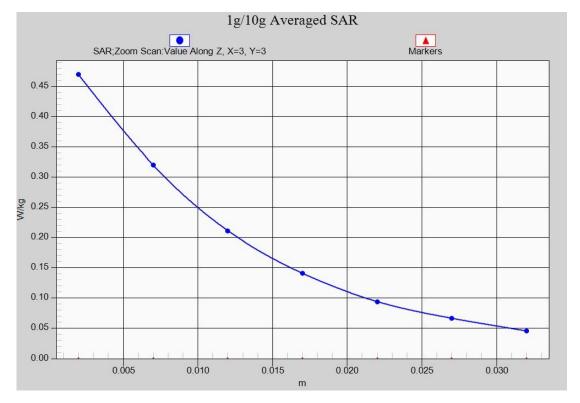


Fig. 3-1 Z-Scan at power reference point (1900 MHz CH512)



# 1900 Body RearHigh with GPRS

Date: 2015-1-9

Electronics: DAE4 Sn777 Medium: Body 1900 MHz

Medium parameters used: f = 1910 MHz;  $\sigma = 1.519 \text{ S/m}$ ;  $\varepsilon_r = 54.036$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Ambient Temperature: 22.5°C Liquid Temperature: 22.0°C

Communication System: GSM 1900MHz GPRS Frequency: 1910 MHz Duty Cycle: 1:4

Probe: EX3DV4 - SN3846 ConvF(7.15, 7.15, 7.15)

**RearHigh/Area Scan (91x61x1):** Interpolated grid: dx=1.000 mm, dy=1.000 mm Maximum value of SAR (interpolated) = 0.831 W/kg

**Rear High/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 12.79 V/m; Power Drift = -0.04 dB

Peak SAR (extrapolated) = 1.20 W/kg

SAR(1 g) = 0.736 W/kg; SAR(10 g) = 0.407 W/kg

Maximum value of SAR (measured) = 0.764 W/kg

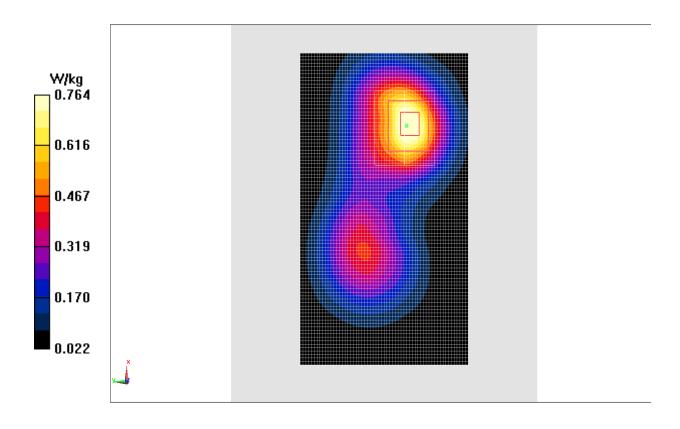


Fig.4 1900 MHz CH810



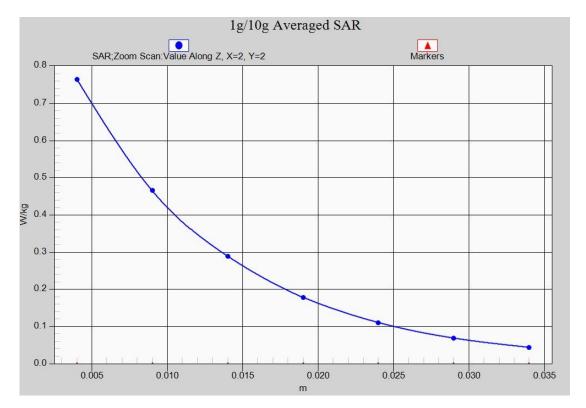


Fig.4-1 Z-Scan at power reference point (1900 MHz CH810)



# WCDMA 850 Right Cheek High

Date: 2015-1-7

Electronics: DAE4 Sn777 Medium: Head 850 MHz

Medium parameters used (interpolated): f = 846.6 MHz;  $\sigma = 0.935$  S/m;  $\varepsilon_r = 42.036$ ;  $\rho = 1000$ 

kg/m<sup>3</sup>

Ambient Temperature: 22.5°C Liquid Temperature: 22.0°C

Communication System: WCDMA; Frequency: 846.6 MHz; Duty Cycle: 1:1

Probe: EX3DV4 - SN3846ConvF(9.18, 9.18, 9.18)

Cheek High/Area Scan (61x151x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm

Maximum value of SAR (interpolated) = 0.954 W/kg

**Cheek High/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 3.077 V/m; Power Drift = 0.09 dB

Peak SAR (extrapolated) = 1.70 W/kg

SAR(1 g) = 0.742 W/kg; SAR(10 g) = 0.422 W/kg

Maximum value of SAR (measured) = 0.789 W/kg

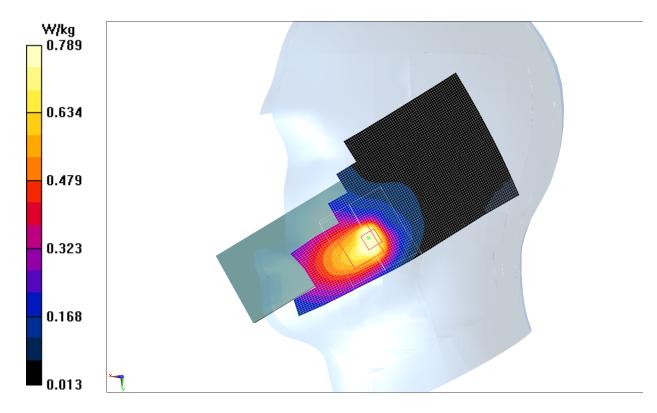


Fig.5 WCDMA 850 CH4233



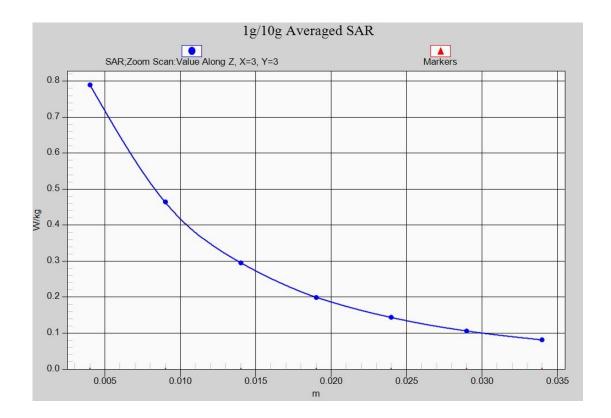


Fig.5-1 Z-Scan at power reference point (WCDMA 850 CH4233)



# WCDMA 850Body RearHigh

Date: 2015-1-7

Electronics: DAE4 Sn777 Medium: Body 850 MHz

Medium parameters used (interpolated): f = 846.6 MHz;  $\sigma = 0.9743$  S/m;  $\varepsilon_r = 54.726$ ;  $\rho = 1000$ 

 $kg/m^3$ 

Ambient Temperature: 22.5°C Liquid Temperature: 22.0°C

Communication System: WCDMA; Frequency: 826.4 MHz; Duty Cycle: 1:1

Probe: EX3DV4 - SN3846ConvF(9.09, 9.09, 9.09)

RearHigh/Area Scan (91x61x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm

Maximum value of SAR (interpolated) = 0.857 W/kg

Rear High/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

dz=5mm

Reference Value = 27.94 V/m; Power Drift = -0.01 dB

Peak SAR (extrapolated) = 1.06 W/kg

SAR(1 g) = 0.816 W/kg; SAR(10 g) = 0.589 W/kg

Maximum value of SAR (measured) = 0.866 W/kg

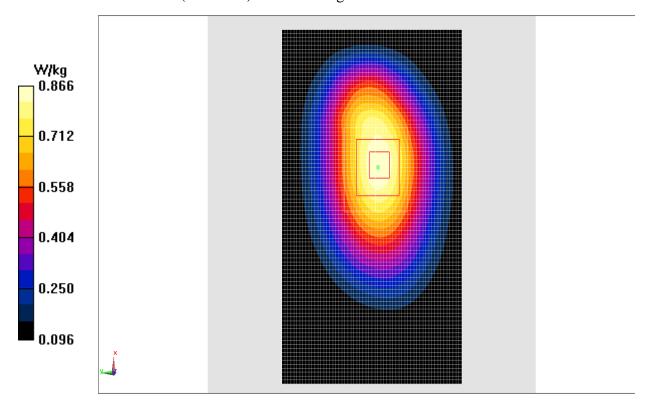


Fig.6 WCDMA 850 CH4233



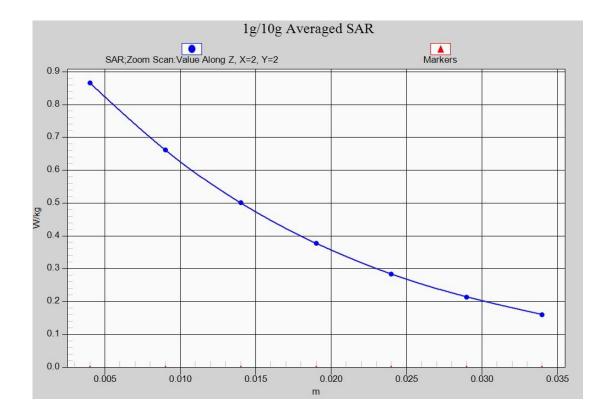


Fig. 6-1 Z-Scan at power reference point (WCDMA850 CH4233)



# ANNEX B SystemVerification Results

## 835MHz

Date: 2015-1-7

Electronics: DAE4 Sn777 Medium: Head 850 MHz

Medium parameters used: f = 835 MHz;  $\sigma = 0.922$  mho/m;  $\varepsilon_r = 42.21$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Ambient Temperature: 22.5°C Liquid Temperature: 22.0°C Communication System: CW Frequency: 835 MHz Duty Cycle: 1:1

Probe: EX3DV4 - SN3846ConvF(9.18, 9.18, 9.18)

System Validation /Area Scan (61x121x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm

Reference Value = 54.57 V/m; Power Drift = 0.12 dBSAR(1 g) = 2.44 W/kg; SAR(10 g) = 1.53 W/kg

Maximum value of SAR (interpolated) = 2.85 W/kg

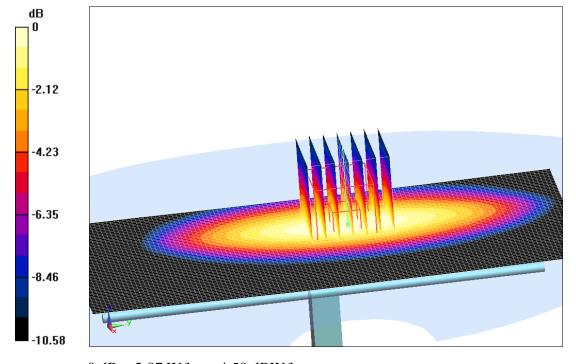
**System Validation /Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 54.57 V/m; Power Drift = 0.12 dB

Peak SAR (extrapolated) = 3.66 W/kg

SAR(1 g) = 2.45 W/kg; SAR(10 g) = 1.54 W/kg

Maximum value of SAR (measured) = 2.87 W/kg



0 dB = 2.87 W/kg = 4.58 dBW/kg

Fig.B.1 validation 835MHz 250mW



## 835MHz

Date: 2015-1-7

Electronics: DAE4 Sn777 Medium: Body 850 MHz

Medium parameters used: f = 835 MHz;  $\sigma = 0.9627$  S/m;  $\varepsilon_r = 54.85$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Ambient Temperature: 22.5°C Liquid Temperature: 22.0°C Communication System: CW Frequency: 835 MHz Duty Cycle: 1:1

Probe: EX3DV4 - SN3846 ConvF(9.09, 9.09, 9.09)

System Validation /Area Scan (61x121x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm

Reference Value = 50.531 V/m; Power Drift = -0.04 dB

Fast SAR: SAR(1 g) = 2.32 W/kg; SAR(10 g) = 1.52 W/kg

Maximum value of SAR (interpolated) = 2.68 W/kg

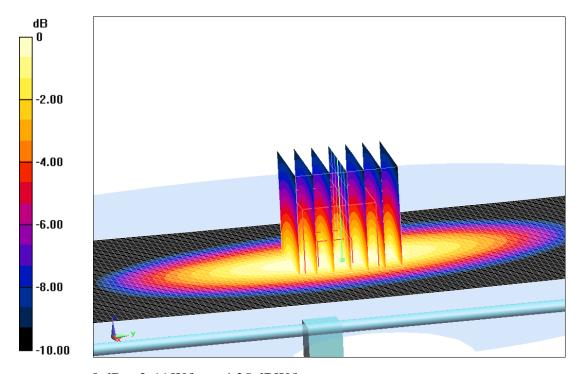
**System Validation /Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 50.531 V/m; Power Drift = -0.04 dB

Peak SAR (extrapolated) = 3.34 W/kg

SAR(1 g) = 2.29 W/kg; SAR(10 g) = 1.51 W/kg

Maximum value of SAR (measured) = 2.66 W/kg



0 dB = 2.66 W/kg = 4.25 dBW/kg

Fig.B.2 validation 835MHz 250mW



## 1900MHz

Date: 2015-1-9

Electronics: DAE4 Sn777 Medium: Head 1900 MHz

Medium parameters used: f = 1900 MHz;  $\sigma = 1.382 \text{ mho/m}$ ;  $\varepsilon_r = 40.05$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Ambient Temperature: 22.5°C Liquid Temperature: 22.0°C Communication System: CW Frequency: 1900 MHz Duty Cycle: 1:1

Probe: EX3DV4 - SN3846ConvF(7.26, 7.26, 7.26)

System Validation /Area Scan(61x81x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm

Reference Value = 90.793 V/m; Power Drift = -0.11 dB

SAR(1 g) = 9.83 W/kg; SAR(10 g) = 5.27 W/kg

Maximum value of SAR (interpolated) = 11.9 W/kg

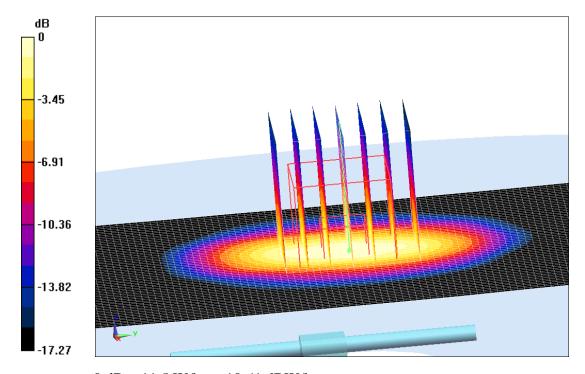
**System Validation /Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 90.793 V/m; Power Drift = -0.11 dB

Peak SAR (extrapolated) = 17.93 W/kg

SAR(1 g) = 9.71 W/kg; SAR(10 g) = 5.11 W/kg

Maximum value of SAR (measured) = 11.5 W/kg



0 dB = 11.5 W/kg = 10.61 dBW/kg

Fig.B.3 validation 1900MHz 250mW



## 1900MHz

Date: 2015-1-9

Electronics: DAE4 Sn777 Medium: Body 1900 MHz

Medium parameters used: f = 1900 MHz;  $\sigma = 1.508 \text{ S/m}$ ;  $\varepsilon_r = 54.06$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Ambient Temperature: 22.5°C Liquid Temperature: 22.0°C Communication System: CW Frequency: 1900 MHz Duty Cycle: 1:1

Probe: EX3DV4 - SN3846 ConvF(7.15, 7.15, 7.15)

System Validation/Area Scan (81x121x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm

Reference Value = 89.899 V/m; Power Drift = 0.13 dB

Fast SAR: SAR(1 g) = 10.2 W/kg; SAR(10 g) = 5.37 W/kg

Maximum value of SAR (interpolated) = 12.0 W/kg

System Validation/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

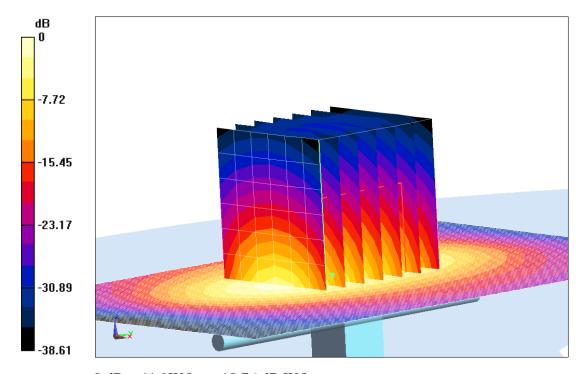
dz=5mm

Reference Value = 89.899 V/m; Power Drift = 0.13 dB

Peak SAR (extrapolated) = 18.6 W/kg

SAR(1 g) = 10.1 W/kg; SAR(10 g) = 5.31 W/kg

Maximum value of SAR (measured) = 11.9 W/kg



0 dB = 11.9W/kg = 10.76 dB W/kg

Fig.B.4validation 1900MHz 250mW



The SAR system verification must be required that the area scan estimated 1-g SAR is within 3% of the zoom scan 1-g SAR.

Table B.1 Comparison between area scan and zoom scan for system verification

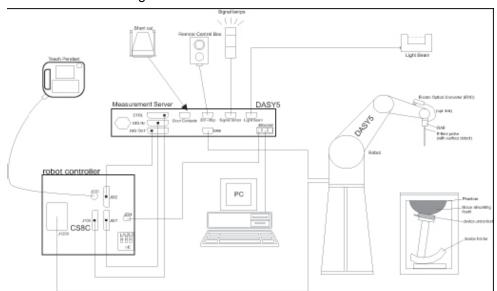
	•	•					
Band	Position	Area scan (1g)	Zoom scan (1g)	Drift (%)			
835	Head	2.44	2.45	-0.41			
835	Body	2.32	2.29	1.31			
1900	Head	9.83	9.71	1.24			
1900	Body	10.2	10.1	0.99			



# **ANNEX CSAR Measurement Setup**

### C.1 Measurement Set-up

The Dasy4 or DASY5 system for performing compliance tests is illustrated above graphically. This system consists of the following items:



Picture C.1SAR Lab Test Measurement Set-up

- A standard high precision 6-axis robot (StäubliTX=RX family) with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- An isotropic field probe optimized and calibrated for the targeted measurement.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc.
   The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The Electro-optical converter (EOC) performs the conversion from optical to electrical signals
  for the digital communication to the DAE. To use optical surface detection, a special version of
  the EOC is required. The EOC signal is transmitted to the measurement server.
- The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- The Light Beam used is for probe alignment. This improves the (absolute) accuracy of the probe positioning.
- A computer running WinXP and the DASY4 or DASY5 software.
- Remote control and teach pendant as well as additional circuitry for robot safety such as
- warning lamps, etc.
- The phantom, the device holder and other accessories according to the targeted measurement.



## C.2 Dasy4 or DASY5 E-field Probe System

The SAR measurements were conducted with the dosimetric probe designed in the classical triangular configuration and optimized for dosimetric evaluation. The probe is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multifiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY4 or DASY5 software reads the reflection durning a software approach and looks for the maximum using 2<sup>nd</sup> ord curve fitting. The approach is stopped at reaching the maximum.

### **Probe Specifications:**

Model: ES3DV3, EX3DV4

Frequency 10MHz — 6.0GHz(EX3DV4) Range: 10MHz — 4GHz(ES3DV3)

Calibration: In head and body simulating tissue at

Frequencies from 835 up to 5800MHz

Linearity:  $\pm$  0.2 dB(30 MHz to 6 GHz) for EX3DV4

± 0.2 dB(30 MHz to 4 GHz) for ES3DV3 DynamicRange: 10 mW/kg — 100W/kg

Probe Length: 330 mm

**Probe Tip** 

Length: 20 mm Body Diameter: 12 mm

Tip Diameter: 2.5 mm (3.9 mm for ES3DV3)
Tip-Center: 1 mm (2.0mm for ES3DV3)

Application: SAR Dosimetry Testing

Compliance tests ofmobile phones

Dosimetry in strong gradient fields

Picture C.3E-field Probe

# C.3 E-field Probe Calibration

Each E-Probe/Probe Amplifier combination has unique calibration parameters. A TEM cell calibration procedure is conducted to determine the proper amplifier settings to enter in the probe parameters. The amplifier settings are determined for a given frequency by subjecting the probe to a known E-field density (1 mW/cm²) using an RF Signal generator, TEM cell, and RF Power Meter.



Picture C.2Near-field Probe



The free space E-field from amplified probe outputs is determined in a test chamber. This calibration can be performed in a TEM cell if the frequency is below 1 GHz and inn a waveguide or other methodologies above 1 GHz for free space. For the free space calibration, the probe is placed 

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in the volumetric center of the cavity and at the proper orientation with the field. The probe is then rotated 360 degrees until the three channels show the maximum reading. The power density readings equates to 1 mW/cm<sup>2</sup>.

E-field temperature correlation calibration is performed in a flat phantom filled with the appropriate simulated brain tissue. The E-field in the medium correlates with the temperature rise in the dielectricmedium. For temperature correlation calibration a RF transparent thermistor-based temperature probe is used in conjunction with the E-field probe.

$$SAR = C \frac{\Delta T}{\Delta t}$$

Where:

 $\Delta t = \text{Exposure time (30 seconds)},$ 

C = Heat capacity of tissue (brain or muscle),

 $\Delta T$  = Temperature increase due to RF exposure.

$$SAR = \frac{\left|E\right|^2 \cdot \sigma}{\rho}$$

Where:

 $\sigma$  = Simulated tissue conductivity,

 $\rho$  = Tissue density (kg/m<sup>3</sup>).

## **C.4 Other Test Equipment**

## C.4.1 Data Acquisition Electronics(DAE)

The data acquisition electronics consist of a highly sensitive electrometer-gradepreamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converterand a command decoder with a control logic unit. Transmission to the measurement server isaccomplished through an optical downlink for data and status information, as well as an optical uplink for commands and the clock.

The mechanical probe mounting device includes two different sensor systems for frontal and sidewaysprobe contacts. They are used for mechanical surface detection and probe collision detection.

The input impedance of the DAE is 200 MOhm; the inputs are symmetrical and floating. Common mode rejection is above 80 dB.



PictureC.4: DAE



#### C.4.2 Robot

The SPEAG DASY system uses the high precision robots (DASY4: RX90XL; DASY5: RX160L) type from Stäubli SA (France). For the 6-axis controller system, the robot controller version from Stäubli is used. The Stäubli robot series have many features that are important for our application:

- High precision (repeatability 0.02mm)
- High reliability (industrial design)
- Low maintenance costs (virtually maintenance free due to direct drive gears; no belt drives)
- Jerk-free straight movements (brushless synchron motors; no stepper motors)
- > Low ELF interference (motor control fields shielded via the closed metallic construction shields)





**Picture C.5DASY 4** 

Picture C.6DASY 5

#### C.4.3 Measurement Server

The Measurement server is based on a PC/104 CPU broad with CPU (dasy4: 166 MHz, Intel Pentium; DASY5: 400 MHz, Intel Celeron), chipdisk (DASY4: 32 MB; DASY5: 128MB), RAM (DASY4: 64 MB, DASY5: 128MB). The necessary circuits for communication with the DAE electronic box, as well as the 16 bit AD converter system for optical detection and digital I/O interface are contained on the DASY I/O broad, which is directly connected to the PC/104 bus of the CPU broad.

The measurement server performs all real-time data evaluation of field measurements and surface detection, controls robot movements and handles safety operation. The PC operating system cannot interfere with these time critical processes. All connections are supervised by a watchdog, and disconnection of any of the cables to the measurement server will automatically disarm the robot and disable all program-controlled robot movements. Furthermore, the measurement server is equipped with an expansion port which is reserved for future applications. Please note that this expansion port does not have a standardized pinout, and therefore only devices provided by SPEAG can be connected. Devices from any other supplier could seriously damage the measurement server.







Picture C.7 Server for DASY 4

Picture C.8 Server for DASY 5

#### C.4.4 Device Holder for Phantom

The SAR in the phantom is approximately inversely proportional to the square of the distance between the source and the liquid surface. For a source at 5mm distance, a positioning uncertainty of ±0.5mm would produce a SAR uncertainty of ±20%. Accurate device positioning is thereforecrucial for accurate and repeatable measurements. The positions in which the devices must be measured are defined by the standards.

The DASY device holder is designed to cope with the different positions given in the standard. It has two scales for device rotation (with respect to the body axis) and device inclination (withrespect to the line between the ear reference points). The rotation centers for both scales is theear reference point (ERP). Thus the device needs no repositioning when changing the angles.

The DASY device holder is constructed of low-loss

POM material having the following

dielectric parameters: relative permittivity  $\varepsilon$  =3 and loss tangent  $\delta$  =0.02. The amount of dielectric materialhas been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.

<Laptop Extension Kit>

The extension is lightweight and made of POM, acrylic glass and foam. It fits easily on the upper part of the Mounting Device in place of the phone positioner. The extension is fully compatible with the Twin-SAM and ELI phantoms.



Picture C.9-1: Device HolderPicture C.9-2: Laptop Extension Kit

### C.4.5 Phantom

The SAM Twin Phantom V4.0 is constructed of a fiberglass shell integrated in a table. The shape of the shell is based on data from an anatomical study designed to

Represent the 90<sup>th</sup> percentile of the population. The phantom enables the dissymmetric evaluation ©Copyright. All rights reserved by CTTL.



of SAR for both left and right handed handset usage, as well as body-worn usage using the flat phantom region. Reference markings on the Phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points in the robot. The shell phantom has a 2mm shell thickness (except the ear region where shell thickness increases to 6 mm).

Shell Thickness: 2±0. 2 mm Filling Volume: Approx. 25 liters

Dimensions: 810 x 1000 x 500 mm (H x L x W)

Available: Special



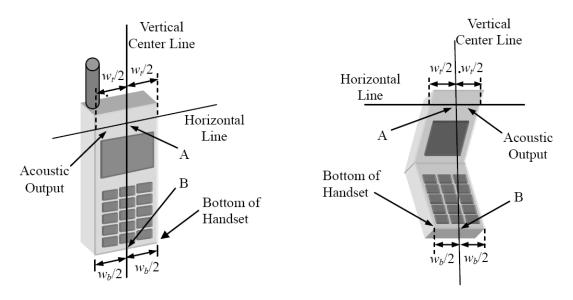
**Picture C.10: SAM Twin Phantom** 



# ANNEX DPosition of the wireless device in relation to the phantom

#### **D.1 General considerations**

This standard specifies two handset test positions against the head phantom – the "cheek" position and the "tilt" position.



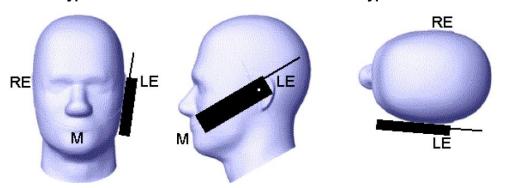
 $W_t$  Width of the handset at the level of the acoustic

 $W_b$  Width of the bottom of the handset

A Midpoint of the width  $w_t$  of the handset at the level of the acoustic output

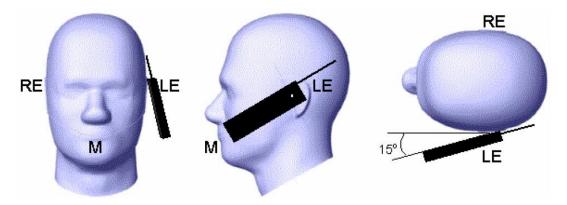
B Midpoint of the width  $W_h$  of the bottom of the handset

Picture D.1-a Typical "fixed" case handset 
Picture D.1-b Typical "clam-shell" case handset



Picture D.2 Cheek position of the wireless device on the left side of SAM

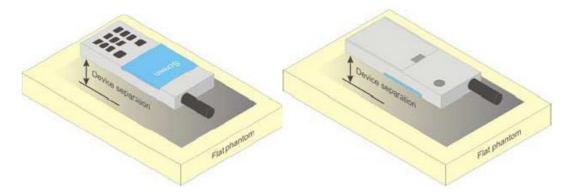




Picture D.3 Tilt position of the wireless device on the left side of SAM

### D.2 Body-worn device

A typical example of a body-worn device is a mobile phone, wireless enabled PDA or other battery operated wireless device with the ability to transmit while mounted on a person's body using a carry accessory approved by the wireless device manufacturer.



Picture D.4Test positions for body-worn devices

#### D.3 Desktop device

A typical example of a desktop device is a wireless enabled desktop computer placed on atable or desk when used.

The DUT shall be positioned at the distance and in the orientation to the phantom that corresponds to the intended use as specified by the manufacturer in the user instructions. For devices that employ an external antenna with variable positions, tests shall be performed for all antenna positions specified. Picture 8.5 show positions for desktop device SAR tests. If the intended use is not specified, the device shall be tested directly against the flat phantom.