
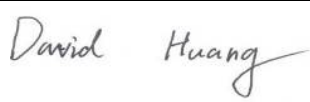



# SAR TEST REPORT



Report No.: 16070501-FCC-H

Supersede Report No.: N/A

Applicant	Borqs BeiJing Ltd.	
Product Name	6 inch Tablet Remote	
Model No.	XR6	
Serial Model No.	XR6P10,XR6P11	
Standards	FCC 47 CFR Part2(2.1093) ANSI/IEEE C95.1-1999 IEEE 1528-2013 & Published RF Exposure KDB Procedures	
Test Date	May 17, 2016 to May 18, 2016	
Issue Date	May 27, 2016	
Test Result	PASS	
Equipment complied with the specification	<input checked="" type="checkbox"/>	
Equipment did not comply with the specification	<input type="checkbox"/>	
		
Wiky Jam Test Engineer	David Huang Checked By	
This test report may be reproduced in full only Test result presented in this test report is applicable to the tested sample only		

Issued by:

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## Laboratory Introduction

SIEMIC, headquartered in the heart of Silicon Valley, with superior facilities in US and Asia, is one of the leading independent testing and certification facilities providing customers with one-stop shop services for Compliance Testing and Global Certifications.



In addition to testing and certification, SIEMIC provides initial design reviews and compliance management throughout a project. Our extensive experience with China, Asia Pacific, North America, European, and International compliance requirements, assures the fastest, most cost effective way to attain regulatory compliance for the global markets.

### Accreditations for Conformity Assessment

Country/Region	Scope
USA	EMC, RF/Wireless, SAR, Telecom
Canada	EMC, RF/Wireless, SAR, Telecom
Taiwan	EMC, RF, Telecom, SAR, Safety
Hong Kong	RF/Wireless, SAR, Telecom
Australia	EMC, RF, Telecom, SAR, Safety
Korea	EMI, EMS, RF, SAR, Telecom, Safety
Japan	EMI, RF/Wireless, SAR, Telecom
Singapore	EMC, RF, SAR, Telecom
Europe	EMC, RF, SAR, Telecom, Safety

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# 1 EUT INFORMATION

<u>EUT Information</u>		
<b>EUT Description</b>	6 inch Tablet Remote	
<b>Model No</b>	XR6	
<b>Serial Model No.</b>	XR6P10,XR6P11	
<b>Input Power</b>	Li-ion Battery Charging Voltage:3.8V , 2740mAh Charge Limit:4.2V	
<b>Transmit Power(Average)</b>	2.4G Wifi: IEEE 802.11b: 15.47 dBm ; IEEE 802.11g: 14.33 dBm; IEEE 802.11n20: 13.09 dBm ; IEEE 802.11n40: 11.37 dBm	5.2G Wifi: IEEE 802.11a: 14.28 dBm ; IEEE 802.11n20: 13.25 dBm ; IEEE 802.11n40: 12.31 dBm
<b>Highest Reported SAR Level(s)</b>	<b>0.54W/Kg 1g Body Tissue</b>	
<b>Classification Per Stipulated Test Standard</b>	Portable Device, Class B, No DTM Mode	
<b>Multi-SIM</b>	NA	
<b>Co-located TX</b>	WiFi cannot transmit simultaneously with Bluetooth	
<b>Antenna Type(s)</b>	PIFA Antenna(WLAN)	

## **2 TECHNICAL DETAILS**

<b>Purpose</b>	Compliance testing of 6 inch Tablet Remote model XR6 with stipulated standard
<b>Applicant / Client</b>	Borqs BeiJing Ltd. Tower A, Building B23, Universal Business Park, No. 10 Jiuxianqiao Road, Chaoyang District Beijing, 100015 China
<b>Manufacturer</b>	Borqs BeiJing Ltd. Tower A, Building B23, Universal Business Park, No. 10 Jiuxianqiao Road, Chaoyang District Beijing, 100015 China
<b>Laboratory performing the tests</b>	SIEMIC(China-Shenzhen) Laboratories Zone A, Floor 1, Building 2, Wan Ye Long Technology Park, South Side of Zhoushi Road, Bao'an District, Shenzhen 518108, Guangdong, P.R.C. Tel: +(86) 0755-26014629 VIP Line:950-4038-0435
<b>Test report reference number</b>	16070501-FCC-H
<b>Date EUT received</b>	May 16, 2016
<b>Standard applied</b>	See Page 34
<b>Dates of test (from – to)</b>	May 17, 2016 to May 18, 2016
<b>No of Units:</b>	1
<b>Equipment Category:</b>	DTS
<b>Trade Name:</b>	VIZIO
<b>Model Name:</b>	XR6
<b>Serial Model No.</b>	XR6P10,XR6P11
<b>RF Operating Frequency (ies)</b>	WIFI:802.11b/g/n(20M): 2412-2462 MHz(TX/RX) WIFI:802.11n(40M):2422-2452 MHz(TX/RX) WIFI:802.11a(40M):5180-5240 MHz(TX/RX)
<b>Modulation:</b>	Wifi: DSSS, OFDM
<b>GPRS/EGPRS Multi-slot class</b>	8/10/12
<b>FCC ID</b>	2ABDK-XR6

### 3 INTRODUCTION

#### Introduction

This measurement report shows compliance of the EUT with ANSI/IEEE C95.1-1999 and FCC 47 CFR Part2 (2.1093)

The test procedures, as described in IEEE 1528-2013 Standard for IEEE Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques(300MHz~6GHz) and Published RF Exposure KDB Procedures

#### SAR Definition

Specific Absorption Rate is defined as the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dV) of a given density ( $\rho$ ).

$$SAR = \frac{d}{dt} \left( \frac{dW}{dm} \right) = \frac{d}{dt} \left( \frac{dW}{\rho dV} \right)$$

SAR is expressed in units of watts per kilogram (W/kg). SAR can be related to the electric field at a point by

$$SAR = \frac{\sigma |E|^2}{\rho}$$

where:

$\sigma$  = conductivity of the tissue (S/m)  
 $\rho$  = mass density of the tissue (kg/m<sup>3</sup>)  
 $E$  = rms electric field strength (V/m)

## 4 SAR MEASUREMENT SETUP

### Dosimetric Assessment System

These measurements were performed with the automated near-field scanning system OPENSAR from SATIMO. The system is based on a high precision robot (working range: 850 mm), which positions the probes with a positional repeatability of better than  $\pm 0.02$  mm. Special E- and H-field probes have been developed for measurements close to material discontinuity, the sensors of which are directly loaded with a Schottky diode and connected via highly resistive lines to the data acquisition unit.

The SAR measurements were conducted with dosimetric probe (manufactured by SATIMO), designed in the classical triangular configuration and optimized for dosimetric evaluation. The probe has been calibrated according to the procedure described in SAR standard with accuracy of better than  $\pm 10\%$ . The spherical isotropy was evaluated with the procedure described in SAR standard and found to be better than  $\pm 0.25$  dB. The phantom used was the SAM Phantom as described in FCC supplement C, IEEE P1528 and CENELEC EN62209-1.

### Measurement System Diagram



**The OPENSAR system for performing compliance tests consist of the following items:**

1. A standard high precision 6-axis robot (KUKA) with controller and software.
2. KUKA Control Panel (KCP).
3. A dosimetric probe, i.e., an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
4. The functions of the PC plug-in card are to perform the time critical task such as signal filtering, surveillance of the robot operation fast movement interrupts.



5. A computer operating Windows XP.
6. OPENSAR software.
7. Tablet Remote control with teaches pendant and additional circuitry for robot safety such as warning lamps, etc.
8. The SAM phantom enabling testing left-hand right-hand and body usage.
9. The Position device for handheld EUT.
10. Tissue simulating liquid mixed according to the given recipes (see Application Note).
11. System validation dipoles to validate the proper functioning of the system.

## EP100 Probe



Construction Symmetrical design with triangular Core. Built-in shielding against static charges Calibration in air from 100 MHz to 2.5 GHz. In brain and muscle simulating tissue at frequencies from 800 to 6000 MHz (accuracy of 8%) .

Frequency 100 MHz to 6 GHz;

Linearity ; 0.25 dB (100 MHz to 6 GHz) ,

Directivity : 0.25 dB in brain tissue (rotation around probe axis) 0.5 dB in brain tissue (rotation normal probe axis)

Dynamic : 0.001W/kg to > 100W/kg;

Range Linearity: 0.25 dB

Surface : 0.2 mm repeatability in air and liquids

Dimensions Overall length: 330 mm

Tip length: 16 mm

Body diameter: 8 mm

Tip diameter: 2.6 mm

Distance from probe tip to dipole centers: <1.5 mm

Application General dosimetric up to 6 GHz

Compliance tests of GSM Tablet Remotes

Fast automatic scanning in arbitrary phantoms

The SAR measurements were conducted with the dosimetric probe designed in the classical triangular configuration and optimized for dosimetric evaluation. The probe is constructed using the thick film technique, with printed resistive lines on ceramic substrates.

It is connected to the KRC box on the robot arm and provides an automatic detection of the phantom surface. The 3D file of the phantom is include in OpenSAR software. The Video Positioning System allow the system to take the automatic reference and to move the probe safely and accurately on the phantom.

### **E-Field Probe Calibration Process**

Probe calibration is realized, in compliance with CENELEC EN50361; CEI/IEC 62209 and IEEE 1528 std, with CALISAR, SATIMO proprietary calibration system. The calibration is performed with the technique using reference waveguide.



$$SAR = \frac{4 (P_{fw} - P_{bw})}{ab\delta} \cos^2 \left( \pi \frac{y}{a} \right) e^{-(2z/\delta)}$$

Where :

- P<sub>fw</sub> = Forward Power
- P<sub>bw</sub> = Backward Power
- a and b = Waveguide dimensions
- = Skin depth

*Keithley configuration:*

Rate = Medium; Filter =ON; RDGS=10; FILTER TYPE =MOVING AVERAGE; RANGE AUTO

*After each calibration, a SAR measurement is performed on a validation dipole and compared with a NPL calibrated probe, to verify it.*

Each probe is calibrated according to a dosimetric assessment procedure described in SAR standard with accuracy better than +/- 10%. The spherical isotropy was evaluated with the procedure described in SAR standard and found to be better than +/-0.25dB. The sensitivity parameters (NormX, NormY, NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe are tested.

The free space E-field from probe outputs is determined in a test chamber. This is performed in a TEM cell for frequencies below 0.8 GHz, and in a waveguide above 0.8 GHz for free space. For the free space calibration, the probe is placed in the volumetric center of the cavity and at the proper orientation with the field. E-field correlation calibration is performed in a flat phantom filled with the appropriate simulated brain tissue.

## SAM Phantom

The SAM Phantom SAM29 is constructed of a fiberglass shell integrated in a wooden table. The shape of the shell is in compliance with the specification set in IEEE 1528 and CENELEC EN62209-1, IEC62209-2.

The phantom enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region.

A cover prevents the evaporation of the liquid.

Reference markings on the Phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points in the robot.

Shell Thickness: 2 0.2 mm

Filling Volume: Approx. 25 liters

Dimensions (H x L x W): 810 x 1000 x 500 mm

Liquid is filled to at least 15mm from the bottom of Phantom.



## Device Holder

In combination with the Generic Twin Phantom V3.0, the Mounting Device enables the rotation of the mounted transmitter in spherical coordinates whereby the rotation points is the ear opening. The devices can be easily, accurately, and repeatedly positioned according to the FCC and CENELEC specifications. The device holder can be locked at different phantom locations (left head, right head, flat phantom).



*Note: A simulating human hand is not used due to the complex anatomical and geometrical structure of the hand that may produced infinite number of configurations [10]. To produce the worst-case condition (the hand absorbs antenna output power), the hand is omitted during the tests.*

## Data Evaluation

The OPENSAR software automatically executes the following procedure to calculate the field units from the microvolt readings at the probe connector. The parameters used in the valuation are stored in the configuration modules of the software:

Probe Parameters	- Sensitivity	Norm <sub>i</sub>
	- Conversion factor	ConvFi
	- Diode compression point Dcpi	
Device Parameter	- Frequency	f
	- Crest factor	cf
Media Parametrs	- Conductivity	σ
	- Density	ρ

These parameters must be set correctly in the software. They can either be found in the component documents or be imported into the software from the configuration files issued for the OPENSAR components.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

Where  $V_i$  = Compensated signal of channel  $i$  ( $i = x, y, z$ )

$U_i$  = Input signal of channel  $i$  ( $i = x, y, z$ )

$cf$  = Crest factor of exciting field (DASY parameter)

$dcp_i$  = Diode compression point (DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated:

$$E\text{-field probes: } E_i = \sqrt{\frac{V_i}{\text{Norm}_i \cdot \text{ConvF}}}$$

$$H\text{-field probes: } H_i = \sqrt{V_i} \cdot \frac{a_{i0} + a_{i1}f + a_{i2}f^2}{f}$$

Where  $V_i$  = Compensated signal of channel  $i$  ( $i = x, y, z$ )  
 $\text{Norm}_i$  = Sensor sensitivity of channel  $i$  ( $i = x, y, z$ )  
 $\mu\text{V}/(\text{V/m})^2$  for E0field Probes  
 $\text{ConvF}$  = Sensitivity enhancement in solution  
 $a_{ij}$  = Sensor sensitivity factors for H-field probes

$f$  = Carrier frequency (GHz)  
 $E_i$  = Electric field strength of channel  $i$  in V/m  
 $H_i$  = Magnetic field strength of channel  $i$  in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{\text{tot}} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{\text{tot}}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$

where  $SAR$  = local specific absorption rate in mW/g  
 $E_{\text{tot}}$  = total field strength in V/m  
 $\sigma$  = conductivity in [mho/m] or [siemens/m]  
 $\rho$  = equivalent tissue density in g/cm<sup>3</sup>

Note that the density is normally set to 1 (or 1.06), to account for actual brain density rather than the density of the simulation liquid.

The power flow density is calculated assuming the excitation field as a free space field.

$$P_{\text{pwe}} = \frac{E_{\text{tot}}^2}{3770} \quad \text{or} \quad P_{\text{pwe}} = H_{\text{tot}}^2 \cdot 37.7$$

where  $P_{\text{pwe}}$  = Equivalent power density of a plane wave in mW/cm<sup>2</sup>  
 $E_{\text{tot}}$  = total electric field strength in V/m  
 $H_{\text{tot}}$  = total magnetic field strength in A/m

## SAR Evaluation – Peak Spatial - Average

The procedure for assessing the peak spatial-average SAR value consists of the following steps

- **Power Reference Measurement**

The reference and drift jobs are useful jobs for monitoring the power drift of the device under test in the batch process. Both jobs measure the field at a specified reference position, at a selectable distance from the phantom surface. The reference position can be either the selected section's grid reference point or a user point in this section. The reference job projects the selected point onto the phantom surface, orients the probe perpendicularly to the surface, and approaches the surface using the selected detection method.

- **Area Scan**

The area scan is used as a fast scan in two dimensions to find the area of high field values, before doing a finer measurement around the hot spot. The sophisticated interpolation routines implemented in OPENSAR software can find the maximum locations even in relatively coarse grids. The scan area is defined by an editable grid. This grid is anchored at the grid reference point of the selected section in the phantom. When the area scan's property sheet is brought-up, grid was at to 15 mm by 15 mm and can be edited by a user.

- **Zoom Scan**

Zoom scans are used to assess the peak spatial SAR values within a cubic averaging volume containing 1 g and 10 g of simulated tissue. The default zoom scan measures 5 x 5 x 7 points within a cube whose base faces are centered around the maximum found in a preceding area scan job within the same procedure. If the preceding Area Scan job indicates more than one maximum, the number of Zoom Scans has to be enlarged accordingly (The default number inserted is 1).

- **Power Drift measurement**

The drift job measures the field at the same location as the most recent reference job within the same procedure, and with the same settings. The drift measurement gives the field difference in dB from the reading conducted within the last reference measurement. Several drift measurements are possible for one reference measurement. This allows a user to monitor the power drift of the device under test within a batch process. In the properties of the Drift job, the user can specify a limit for the drift and have OPENSAR software stop the measurements if this limit is exceeded.

## SAR Evaluation – Peak SAR

The procedure for spatial peak SAR evaluation has been implemented according to the IEEE1529 standard. It can be conducted for 1 g and 10 g. The OPENSAR system allows evaluations that combine measured data and robot positions, such as:

- maximum search
- extrapolation
- boundary correction
- peak search for averaged SAR

During a maximum search, global and local maximum searches are automatically performed in 2-D after each Area Scan measurement with at least 6 measurement points. It is based on the evaluation of the local SAR gradient calculated by the Quadratic Shepard's method. The algorithm will find the global maximum and all local maxima within -2 dB of the global maxima for all SAR distributions.



## Extrapolation

Extrapolation routines are used to obtain SAR values between the lowest measurement points and the inner phantom surface. The extrapolation distance is determined by the surface detection distance and the probe sensor offset. Several measurements at different distances are necessary for the extrapolation.

They are used in the Cube Scan to obtain SAR values between the lowest measurement points and the inner phantom surface. The routine uses the fourth order least square polynomial method for extrapolation. For a grid using 5x5x7 measurement points with 5mm resolution amounting to 343 measurement points, the uncertainty of the extrapolation routines is less than 1% for 1 g and 10 g cubes.

## Definition of Reference Points

### Ear Reference Point

Figure 6.2 shows the front, back and side views of the SAM Phantom. The point "M" is the reference point for the center of the mouth, "LE" is the left ear reference point (ERP), and "RE" is the right ERP. The ERPs are 15mm posterior to the entrance to the ear canal (EEC) along the B-M line (Back-Mouth), as shown in Figure 6.1. The plane passing through the two ear canals and M is defined as the Reference Plane. The line N-F (Neck-Front) is perpendicular to the reference plane and passing through the RE (or LE) is called the Reference Pivoting Line (see Figure 6.1). Line B-M is perpendicular to the N-F line. Both N-F and B-M lines are marked on the external phantom shell to facilitate handset positioning [5].



**Figure 6.1 Close-up side view of ERP's**



**Figure 6.2 Front, back and side view of SAM**

## Device Reference Points

Two imaginary lines on the device need to be established: the vertical centerline and the horizontal line. The test device is placed in a normal operating position with the "test device reference point" located along the "vertical centerline" on the front of the device aligned to the "ear reference point" (See Fig. 6.3). The "test device reference point" is then located at the same level as the center of the ear reference point. The test device is positioned so that the "vertical centerline" is bisecting the front surface of the device at its top and bottom edges, positioning the "ear reference point" on the outer surface of both the left and right head phantoms on the ear reference point [5].



**Figure 6.3 Handset Vertical Center & Horizontal Line Reference Points**



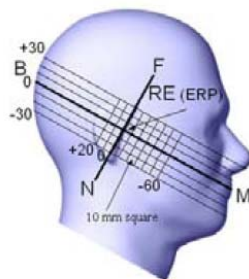
## Test Configuration – Positioning for Cheek / Touch

1. Position the device close to the surface of the phantom such that point A is on the (virtual) extension of the line passing through points RE and LE on the phantom (see Figure below), such that the plane defined by the vertical center line and the horizontal line of the device is approximately parallel to the sagittal plane of the phantom



**Figure 7.1 Front, Side and Top View of Cheek/Touch Position**

2. Translate the device towards the phantom along the line passing through RE and LE until the device touches the ear.
3. While maintaining the device in this plane, rotate it around the LE-RE line until the vertical centerline is in the plane normal to MB-NF including the line MB (called the reference plane).
4. Rotate the device around the vertical centerline until the device (horizontal line) is symmetrical with respect to the line NF.
5. While maintaining the vertical centerline in the reference plane, keeping point A on the line passing through RE and LE and maintaining the device contact with the ear, rotate the device about the line NF until any point on the device is in contact with a phantom point below the ear (cheek). See Figure below.



**Figure 7.2 Side view w/ relevant markings**

## Test Configuration – Positioning for Ear / 15° Tilt

With the test device aligned in the Cheek/Touch Position”:

1. While maintaining the orientation of the device, retracted the device parallel to the reference plane far enough to enable a rotation of the device by 15 degrees.
2. Rotate the device around the horizontal line by 15 degrees.
3. While maintaining the orientation of the device, move the device parallel to the reference plane until any part of the device touches the head. (In this position, point A is located on the line RE-LE). The tilted position is obtained when the contact is on the pinna. If the contact is at any location other than the pinna, the angle of the device shall be reduced. The tilted position is obtained when any part of the device is in contact with the ear as well as a second part of the device is in contact with the head (see Figure below).

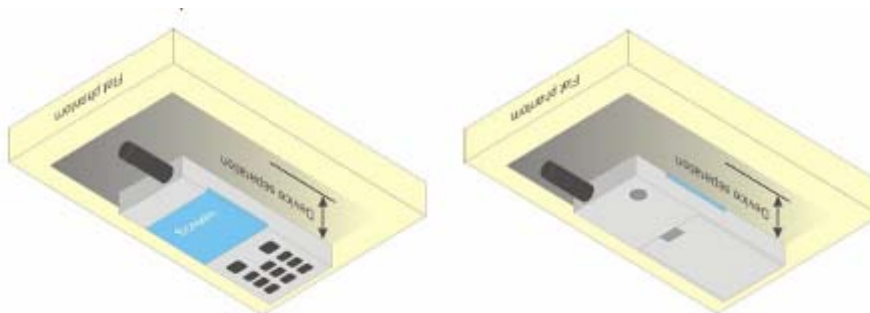


**Figure 7.3 Front, Side and Top View of Ear/15° Tilt Position**

## Test Position – Body Worn Configurations

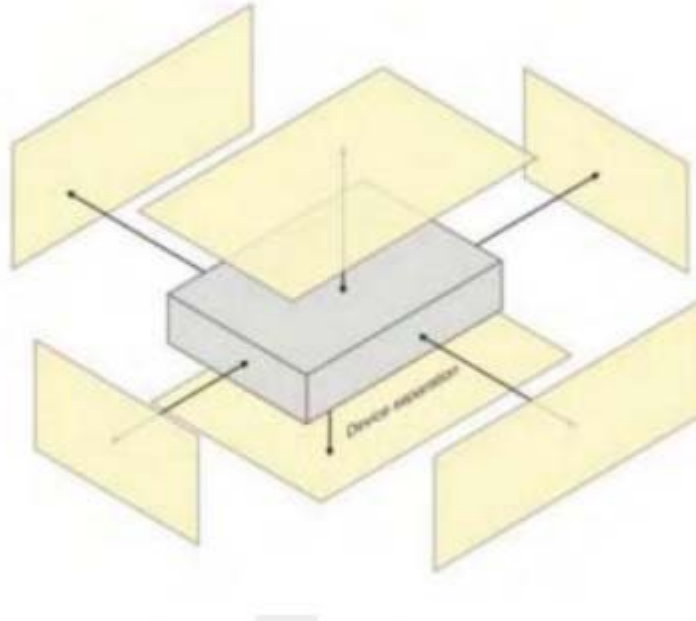
Body Worn Position

- (a) To position the device parallel to the phantom surface with either keypad up or down.
- (b) To adjust the device parallel to the flat phantom.
- (c) To adjust the distance between the device surface and the flat phantom to 1.5 cm or holster surface and the flat phantom to 0 cm.



## Test Position –Hotspot mode exposure position condition

For handsets that support hotspot mode operations, with wireless router capabilities and various web browsing function, the relevant hand and body exposure condition are tested according to the hotspot SAR procedures in KDB 941225. A test separation distance of 10 mm is required between the phantom and all surface and edges with a transmitting antenna located within 25mm from that surface or edge. When form factor of a handset is smaller than 9cm x 5cm, a test separation distance of 5mm (instead of 10mm) is required for testing hotspot mode. When the separate distance required for body-worn accessory testing is larger than or equal to that tested for hotspot mode, in the same wireless mode and for the same surface of the phone, the hotspot mode SAR data may be used to support body-worn accessory SAR compliance for that particular configuration (surface).



## 5 ANSI/IEEE C95.1 – 1999 RF EXPOSURE LIMIT

In order for users to be aware of the body operating requirements for meeting RF exposure compliance, operating instructions and cautions statements are included in the user's manual.

### Uncontrolled Environment

Uncontrolled Environments are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure. The general population/uncontrolled exposure limits are applicable to situations in which the general public may be exposed or in which persons who are exposed as a consequence of their employment may not be made fully aware of the potential for exposure or cannot exercise control over their exposure. Members of the general public would come under this category when exposure is not employment-related; for example, in the case of a wireless transmitter that exposes persons in its vicinity.

### Controlled Environment

Controlled Environments are defined as locations where there is exposure that may be incurred by persons who are aware of the potential for exposure, (i.e. as a result of employment or occupation). In general, occupational/controlled exposure limits are applicable to situations in which persons are exposed as a consequence of their employment, who have been made fully aware of the potential for exposure and can exercise control over their exposure. This exposure category is also applicable when the exposure is of a transient nature due to incidental passage through a location where the exposure levels may be higher than the general population/uncontrolled limits, but the exposed person is fully aware of the potential for exposure and can exercise control over his or her exposure by leaving the area or by some other appropriate means.

**Table 8.1 Human Exposure Limits**

	UNCONTROLLED ENVIRONMENT General Population (W/kg) or (mW/g)	CONTROLLED ENVIRONMENT Professional Population (W/kg) or (mW/g)
SPATIAL PEAK SAR <sup>1</sup> Brain	1.60	8.00
SPATIAL AVERAGE SAR <sup>2</sup> Whole Body	0.08	0.40
SPATIAL PEAK SAR <sup>3</sup> Hands, Feet, Ankles, Wrists	4.00	20.00

<sup>1</sup> The Spatial Peak value of the SAR averaged over any 1 gram of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.

<sup>2</sup> The Spatial Average value of the SAR averaged over the whole body.

<sup>3</sup> The Spatial Peak value of the SAR averaged over any 10 grams of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.

## 6 SYSTEM AND LIQUID VERIFICATION

### Basic SAR system validation requirements

The SAR system must be validated against its performance specifications before it is deployed. When SAR probes, system components or software are changed, upgraded or recalibrated, these must be validated with the SAR system(s) that operates with such components. Reference dipoles are used with the required tissue-equivalent media for system validation,

The detailed system validation results are maintained by each test laboratory, which are normally not required for equipment approval. Only a tabulated summary of the system validation status, according to the validation date(s), measurement frequencies, SAR probes and tissue dielectric parameters is required in the SAR report.

### System Setup

The system performance check verifies that the system operates within its specifications. System and operator errors can be detected and corrected. It is recommended that the system performance check be performed prior to any usage of the system in order to guarantee reproducible results. The system performance check uses normal SAR measurements in a simplified setup with a well characterized source. This setup was selected to give a high sensitivity to all parameters that might fail or vary over time. The system check does not intend to replace the calibration of the components, but indicates situations where the system uncertainty is exceeded due to drift or failure.

In the simplified setup for system evaluation, the DUT is replaced by a calibrated dipole and the power source is replaced by a continuous wave that comes from a signal generator. The calibrated dipole must be placed beneath the flat phantom section of the SAM twin phantom with the correct distance holder. The distance holder should touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The equipment setup is shown below:

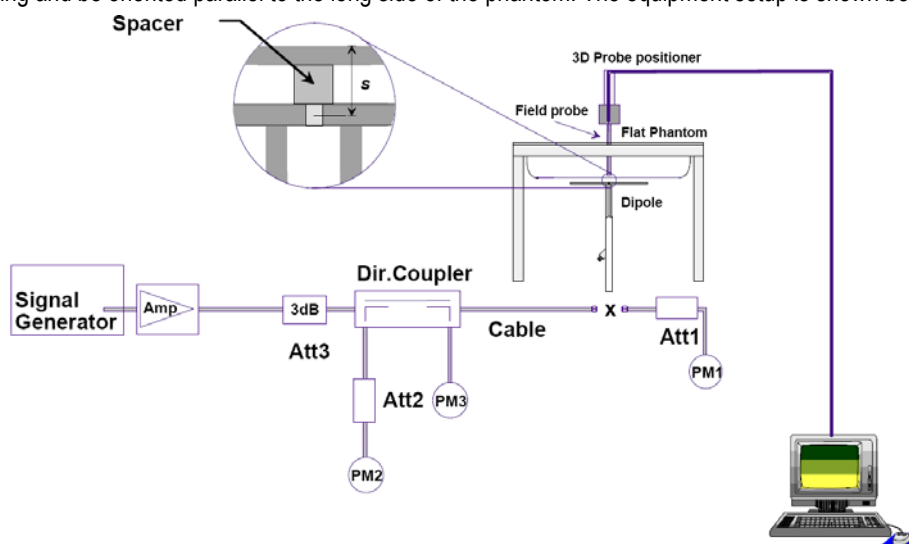


Fig 8.1 System Setup for System Evaluation

1. Signal Generator
2. Amplifier
3. Directional Coupler
4. Power Meter
5. Calibrated Dipole

Note: The output power on dipole port must be calibrated to 30 dBm (1000 mW) before dipole is connected.

## System Verification Results

Frequency (MHz)	1 g SAR	10 g SAR	Local SAR at surface (above feed-point)	Local SAR at surface (y = 2 cm offset from feed-point) <sup>a</sup>
300	3.0	2.0	4.4	2.1
450	4.9	3.3	7.2	3.2
835	9.5	6.2	4.1	4.9
900	10.8	6.9	16.4	5.4
1450	29.0	16.0	50.2	6.5
1800	38.1	19.8	69.5	6.8
1900	39.7	20.5	72.1	6.6
2000	41.1	21.1	74.6	6.5
2450	52.4	24.0	104.2	7.7
3000	63.8	25.7	140.2	9.5

Prior to SAR assessment, the system is verified to 10% of the SAR measurement on the reference dipole at the time of calibration by the calibration facility. Full system validation status and result summary can be found in ANNEX A

### Target and measurement SAR after Normalized (1W):

Measurement Date	Frequency (MHz)	Liquid Type (head/body)	Target SAR1g (W/kg)	Measured SAR1g (W/kg)	Normalized SAR1g (W/kg)	Deviation (%)
May 17, 2016	2450	body	56.05	0.542	54.2	-3.30
May 18, 2016	5200	body	158.88	1.592	159.2	0.20

Note: system check input power: 10mW

## Liquid Verification

The dielectric parameters were checked prior to assessment using the HP85070C dielectric probe kit. The dielectric parameters measured are reported in each correspondent section.

### **KDB 865664 recommended Tissue Dielectric Parameters**

The head and body tissue parameters given in this below table should be used to measure the SAR of transmitters operating in 100 MHz to 6 GHz frequency range. The tissue dielectric parameters of the tissue medium at the test frequency should be within the tolerance required in this document. The dielectric parameters should be linearly interpolated between the closest pair of target frequencies to determine the applicable dielectric parameters corresponding to the device test frequency.

The head tissue dielectric parameters recommended by IEEE Std 1528-2013 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in a human head. Other head and body tissue parameters that have not been specified in 1528 are derived from tissue dielectric parameters computed from the 4-Cole-Cole equations described above and extrapolated according to the head parameters specified in 1528.

Target Frequency	Head		Body	
(MHz)	$\epsilon_r$	$\sigma$ (S/m)	$\epsilon_r$	$\sigma$ (S/m)
150	52.3	0.76	61.9	0.80
300	45.3	0.87	58.2	0.92
450	43.5	0.87	56.7	0.94
835	41.5	0.90	55.2	0.97
900	41.5	0.97	55.0	1.05
915	41.5	0.98	55.0	1.06
1450	40.5	1.20	54.0	1.30
1610	40.3	1.29	53.8	1.40
1800 – 2000	40.0	1.40	53.3	1.52
2450	39.2	1.80	52.7	1.95
3000	38.5	2.40	52.0	2.73
5800	35.3	5.27	48.2	6.00

( $\epsilon_r$  = relative permittivity,  $\sigma$  = conductivity and  $\rho = 1000 \text{ kg/m}^3$ )

### **Liquid Confirmation Result:**

Date	Freq.(MHz)	Liquid Parameters	Measured	Target	Delta (%)	Limit $\pm$ (%)
May 17, 2016	2450	Relative Permittivity ( $\epsilon_r$ ):	52.72	52.70	0.04	5
		Conductivity ( $\sigma$ ):	1.98	1.94	2.06	5
May 18, 2016	5200	Relative Permittivity ( $\epsilon_r$ ):	50.67	50.70	-0.06	5
		Conductivity ( $\sigma$ ):	5.13	5.11	0.39	5

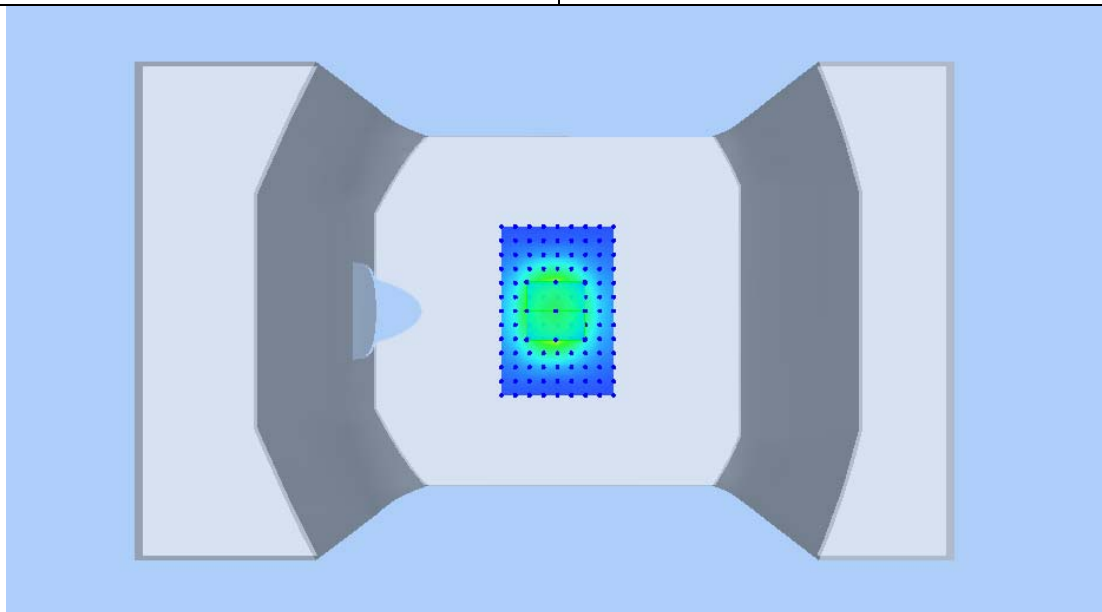
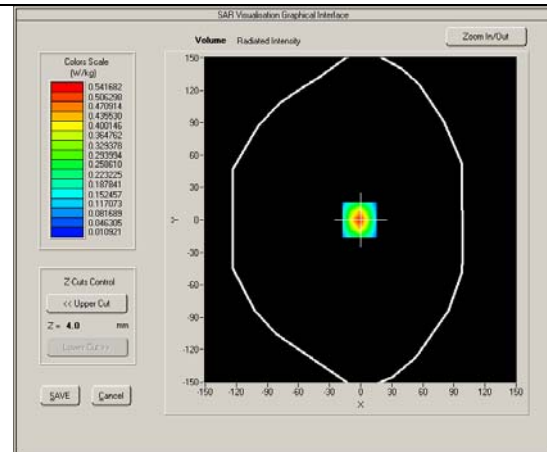
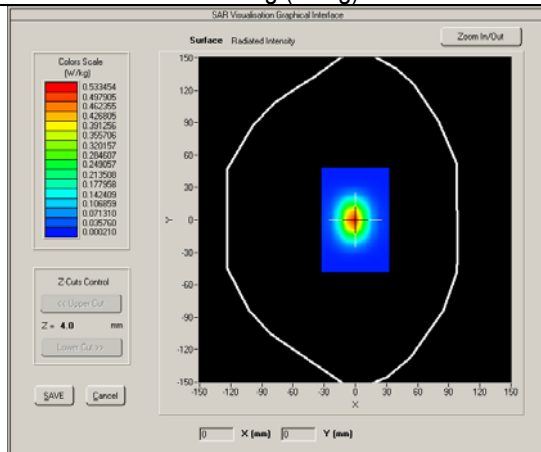
## System Verification Plots

Product Description: Dipole

Model: SID2450

Test Date: May 17, 2016

Medium(liquid type)	MSL_2450
Frequency (MHz)	2450.00
Relative permittivity (real part)	52.72
Conductivity (S/m)	1.98
Input power	10mW
Crest factor	1.0
E-Field Probe	SN 07/14 EP203
Conversion Factor	2.29
Area Scan	dx=8mm dy=8mm
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm
Variation (%)	-1.300000
SAR 10g (W/Kg)	0.310547
SAR 1g (W/Kg)	0.542391



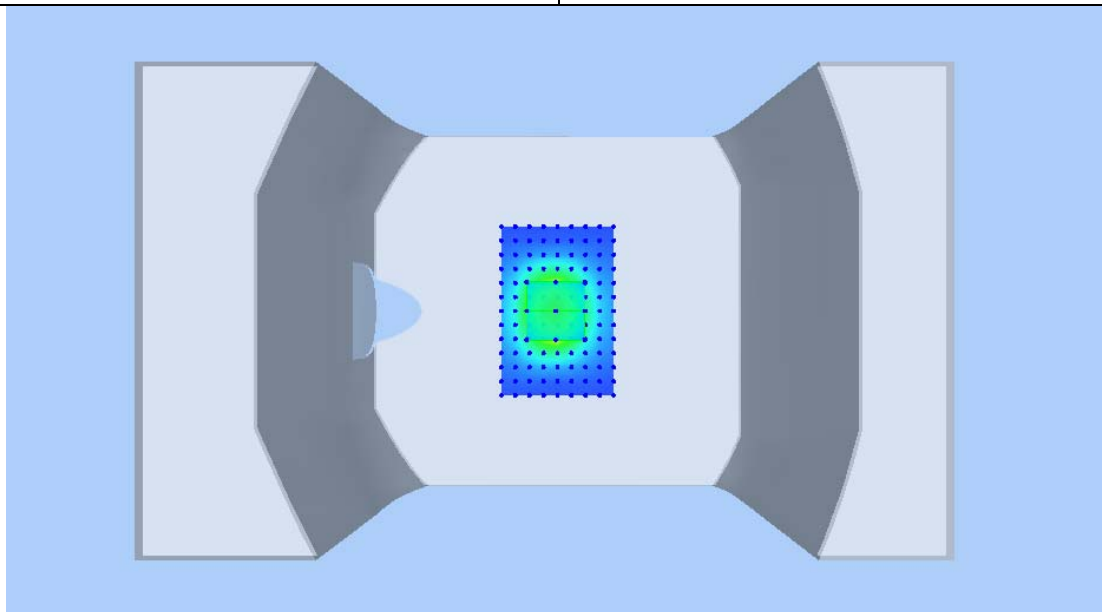
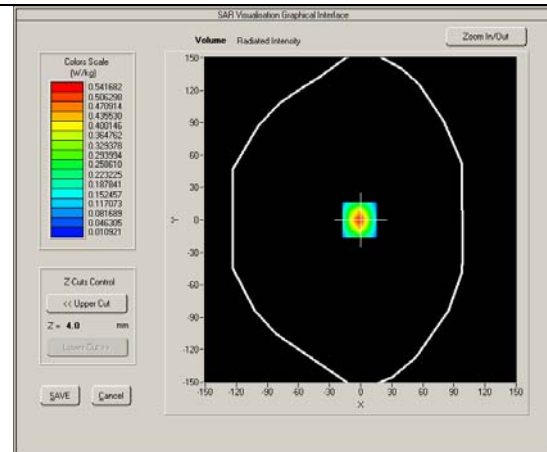
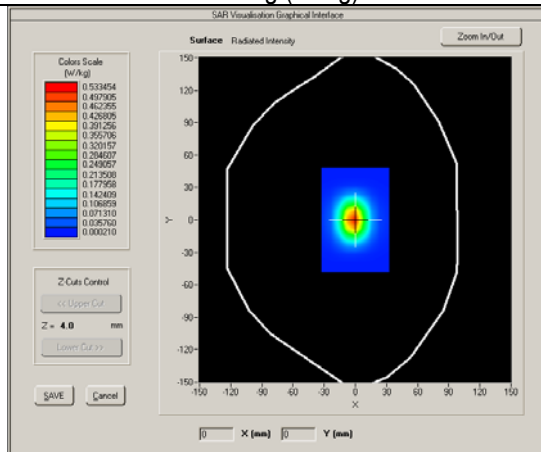


Product Description: Dipole

Model: SID5200

Test Date: May 18, 2016

Medium(liquid type)	MSL_5200
Frequency (MHz)	5200.00
Relative permittivity (real part)	50.67
Conductivity (S/m)	5.13
Input power	10mW
Crest factor	1.0
E-Field Probe	SN 07/14 EP203
Conversion Factor	2.04
Area Scan	dx=8mm dy=8mm
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm
Variation (%)	2.100000
SAR 10g (W/Kg)	0.740256
SAR 1g (W/Kg)	1.592452



## 7 UNCERTAINTY ASSESSMENT

The component of uncertainty may generally be categorized according to the methods used to evaluate them. The evaluation of uncertainty by the statistical analysis of a series of observations is termed a Type A evaluation of uncertainty. The evaluation of uncertainty by means other than the statistical analysis of a series of observation is termed a Type B evaluation of uncertainty. Each component of uncertainty, however evaluated, is represented by an estimated standard deviation, termed standard uncertainty, which is determined by the positive square root of the estimated variance

A Type A evaluation of standard uncertainty may be based on any valid statistical method for treating data. This includes calculating the standard deviation of the mean of a series of independent observations; using the method of least squares to fit a curve to the data in order to estimate the parameter of the curve and their standard deviations; or carrying out an analysis of variance in order to identify and quantify random effects in certain kinds of measurement.

A type B evaluation of standard uncertainty is typically based on scientific judgment using all of the relevant information available. These may include previous measurement data, experience and specification, data provided in calibration reports and uncertainties assigned to reference data taken from handbooks. Broadly speaking, the uncertainty is either obtained from an outdoor source or obtained from an assumed distribution, such as the normal distribution, rectangular or triangular distributions indicated in Table below :

Uncertainty Distribution	Normal	Rectangle	Triangular	U Shape
Multi-plying Factor <sup>(a)</sup>	1/ $\kappa$ <sup>(b)</sup>	1 / $\sqrt{3}$	1 / $\sqrt{6}$	1 / $\sqrt{2}$

(a) standard uncertainty is determined as the product of the multiplying factor and the estimated range of variations in the measured quantity

(b)  $\kappa$  is the coverage factor

### Standard Uncertainty for Assumed Distribution

The combined standard uncertainty of the measurement result represents the estimated standard deviation of the result. It is obtained by combining the individual standard uncertainties of both Type A and Type -sum-by taking the positive square root of the estimated variances.

Expanded uncertainty is a measure of uncertainty that defines an interval about the measurement result within which the measured value is confidently believed to lie. It is obtained by multiplying the combined standard uncertainty by a coverage factor. Typically, the coverage factor ranges from 2 to 3. Using a coverage factor allows the true value of a measured quantity to be specified with a defined probability within the specified uncertainty range. For purpose of this document, a coverage factor two is used, which corresponds to confidence interval of about 95 %.

The COMOSAR Uncertainty Budget is show in below table:

The following table includes the uncertainty table of the IEEE 1528 from 300MHz to 3GHz and KDB865664 to 6GHZ too, The values are determined by Satimo.

## UNCERTAINTY FOR SYSTEM PERFORMANCE CHECK

Uncertainty Component	Tol. (± %)	Prob. Dist.	Div.	c <sub>i</sub> (1 g)	c <sub>i</sub> (10 g)	1 g u <sub>i</sub> (± %)	10 g u <sub>i</sub> (± %)	V <sub>i</sub>
<b>Measurement System</b>								
Probe Calibration	5,8	N	1	1	1	5,8	5,8	∞
Axial Isotropy	3,5	R	√3	(1-cp) <sup>1/2</sup>	(1-cp) <sup>1/2</sup>	1,42887	1,42887	∞
Hemispherical Isotropy	5,9	R	√3	√Cp	√Cp	2,40866	2,40866	∞
Boundary Effect	1	R	√3	1	1	0,57735	0,57735	∞
Linearity	4,7	R	√3	1	1	2,71355	2,71355	∞
System Detection Limits	1	R	√3	1	1	0,57735	0,57735	∞
Readout Electronics	0,5	N	1	1	1	0,5	0,5	∞
Response Time	0	R	√3	1	1	0	0	∞
Integration Time	1,4	R	√3	1	1	0,80829	0,80829	∞
RF Ambient Conditions	3	R	√3	1	1	1,73205	1,73205	∞
Probe Positioner Mechanical Tolerance	1,4	R	√3	1	1	0,80829	0,80829	∞
Probe Positioning with respect to Phantom Shell	1,4	R	√3	1	1	0,80829	0,80829	∞
Extrapolation, interpolation and Integration Algorithms for Max. SAR Evaluation	2,3	R	√3	1	1	1,32791	1,32791	∞
<b>Dipole</b>								
Dipole Axis to Liquid Distance	2	N	√3	1	1	1,1547	1,1547	N-1
Input Power and SAR drift measurement	5	R	√3	1	1	2,88675	2,88675	∞
<b>Phantom and Tissue Parameters</b>								
Phantom Uncertainty (shape and thickness tolerances)	4	R	√3	1	1	2,3094	2,3094	∞
Liquid Conductivity - deviation from target values	5	R	√3	0,64	0,43	1,84752	1,2413	∞
Liquid Conductivity - measurement uncertainty	4	N	1	0,64	0,43	2,56	1,72	M
Liquid Permittivity - deviation from target values	5	R	√3	0,6	0,49	1,73205	1,41451	∞
Liquid Permittivity - measurement uncertainty	5	N	1	0,6	0,49	3	2,45	M
Combined Standard Uncertainty		RSS				9.6671	9.1645	
Expanded Uncertainty (95% CONFIDENCE INTERVAL)		k				19.3342	18.3290	

## UNCERTAINTY EVALUATION FOR HANDSET SAR TEST

Uncertainty Component	Tol. (± %)	Prob. Dist.	Div.	$c_i$ (1 g)	$c_i$ (10 g)	1 g $u_i$ (± %)	10 g $u_i$ (± %)	$v_i$
<b>Measurement System</b>								
Probe Calibration	5,8	N	1	1	1	5,8	5,8	∞
Axial Isotropy	3,5	R	$\sqrt{3}$	$(1-c_p)^{1/2}$	$(1-c_p)^{1/2}$	1,43	1,43	∞
Hemispherical Isotropy	5,9	R	$\sqrt{3}$	$\sqrt{C_p}$	$\sqrt{C_p}$	2,41	2,41	∞
Boundary Effect	1	R	$\sqrt{3}$	1	1	0,58	0,58	∞
Linearity	4,7	R	$\sqrt{3}$	1	1	2,71	2,71	∞
System Detection Limits	1	R	$\sqrt{3}$	1	1	0,58	0,58	∞
Readout Electronics	0,5	N	1	1	1	0,50	0,50	∞
Response Time	0	R	$\sqrt{3}$	1	1	0,00	0,00	∞
Integration Time	1,4	R	$\sqrt{3}$	1	1	0,81	0,81	∞
RF Ambient Conditions	3	R	$\sqrt{3}$	1	1	1,73	1,73	∞
Probe Positioner Mechanical Tolerance	1,4	R	$\sqrt{3}$	1	1	0,81	0,81	∞
Probe Positioning with respect to Phantom Shell	1,4	R	$\sqrt{3}$	1	1	0,81	0,81	∞
Extrapolation, interpolation and Integration Algorithms for Max. SAR Evaluation	2,3	R	$\sqrt{3}$	1	1	1,33	1,33	∞
<b>Test sample Related</b>								
Test Sample Positioning	2,6	N	1	1	1	2,60	2,60	N-1
Device Holder Uncertainty	3	N	1	1	1	3,00	3,00	N-1
Output Power Variation - SAR drift measurement	5	R	$\sqrt{3}$	1	1	2,89	2,89	∞
<b>Phantom and Tissue Parameters</b>								
Phantom Uncertainty (shape and thickness tolerances)	4	R	$\sqrt{3}$	1	1	2,31	2,31	∞
Liquid Conductivity - deviation from target values	5	R	$\sqrt{3}$	0,64	0,43	1,85	1,24	∞
Liquid Conductivity - measurement uncertainty	4	N	1	0,64	0,43	2,56	1,72	M
Liquid Permittivity - deviation from target values	5	R	$\sqrt{3}$	0,6	0,49	1,73	1,41	∞
Liquid Permittivity - measurement uncertainty	5	N	1	0,6	0,49	3,00	2,45	M
Combined Standard Uncertainty		RSS				10.39	9.92	
Expanded Uncertainty (95% CONFIDENCE INTERVAL)		k				20.78	19.84	

## 8 TEST INSTRUMENT

### TEST INSTRUMENTATION

Name of Equipment	Manufacturer	Type/Model	Serial Number	Calibration Date	Calibration Due
P C	Compaq	PV 3.06GHz	375052-AA1	N/A	N/A
Signal Generator	Agilent	8665B-008	3744A10293	05/15/2015	05/15/2016
MultiMeter	Keithley	MiltiMeter 2000	1259033	06/21/2015	06/21/2016
S-Parameter Network Analyzer	Agilent	8753ES	US39173518	08/04/2015	08/04/2016
Power Meter	HP	437B	3038A03648	05/17/2015	05/17/2016
E-field PROBE	MVG	SSE2	SN 27/15 EPGO262	07/09/2015	07/09/2016
DIPOLE 2450	SATIMO	SID 2450	SN 31/10 DIPJ138	06/13/2015	06/13/2016
DIPOLE 5200	SATIMO	SID 5200	SN 24/11 WGA16	06/18/2015	06/18/2016
Communication Antenna	SATIMO	ANTA3	SN 20/11 ANTA 3	06/21/2015	06/20/2016
Laptop POSITIONING DEVICE	SATIMO	LSH15	SN 24/11 LSH15	N/A	N/A
ePOSITIONING DEVICE	SATIMO	MSH73	SN 24/11 MSH73	N/A	N/A
DUMMY PROBE	ANTENNESSA		DP41	N/A	N/A
SAM PHANTOM	SATIMO	SAM87	SN 24/11 SAM87	N/A	N/A
Elliptic Phantom	SATIMO	ELLI20	SN 20/11ELLI20	N/A	N/A
PHANTOM TABLE	SATIMO	N/A	N/A	N/A	N/A
6 AXIS ROBOT	KUKA	KR5	949272	N/A	N/A
high Power Solid State Amplifier (80MHz~1000MHz)	Instruments for Industry	CMC150	M631-0408	N/A	N/A
Medium Power Solid State Amplifier (0.8~4.2GHz)	Instruments for Industry	S41-25	M629-0408	N/A	N/A
Wave Tube Amplifier 4-8 GHz at 20Watt	Hughes Aircraft Company	1277H02F000	81	N/A	N/A

## 9 OUTPUT POWER VERIFICATION

### Test Condition:

- Conducted Measurement  
EUT was set for low, mid, high channel with modulated mode and highest RF output power.  
The base station simulator was connected to the antenna terminal.
- Conducted Emissions Measurement Uncertainty  
All test measurements carried out are traceable to national standards. The uncertainty of the measurement at a confidence level of approximately 95% (in the case where distributions are normal), with a coverage factor of 2, in the range 30MHz – 40GHz is  $\pm 1.5\text{dB}$ .
- Environmental Conditions
 

Temperature	23°C
Relative Humidity	53%
Atmospheric Pressure	1019mbar
- Test Date : May 17th, 2016  
Tested By : Wiky Jam

### Test Procedures:

#### Tablet Remote radio output power measurement

- The transmitter output port was connected to base station emulator.
- Establish communication link between emulator and EUT and set EUT to operate at maximum output power all the time.
- Select lowest, middle, and highest channels for each band and different possible test mode.
- Measure the conducted peak burst power and conducted average burst power from EUT antenna port.

#### Other radio output power measurement

The output power was measured using power meter at low, mid, and hi channels.

### Test Result:

#### 2.4G Mode

Mode	Channel number	Frequency (MHz)	Data rate(Mbps)	Average Output Power(dBm)	Average Tune up limited(dBm)
802.11b	1	2412	1	15.45	$15 \pm 0.5$
	6	2437	1	15.47	$15 \pm 0.5$
	11	2462	1	15.38	$15 \pm 0.5$
802.11g	1	2412	6	14.33	$14 \pm 0.5$
	6	2437	6	14.07	$14 \pm 0.5$
	11	2462	6	13.99	$14 \pm 0.5$
802.11n(HT20)	1	2412	MCS0	12.94	$13 \pm 0.5$
	6	2437	MCS0	13.06	$13 \pm 0.5$
	11	2462	MCS0	13.09	$13 \pm 0.5$
802.11n(HT40)	3	2422	MCS0	11.05	$11 \pm 0.5$
	6	2437	MCS0	11.37	$11 \pm 0.5$
	9	2452	MCS0	11.28	$11 \pm 0.5$

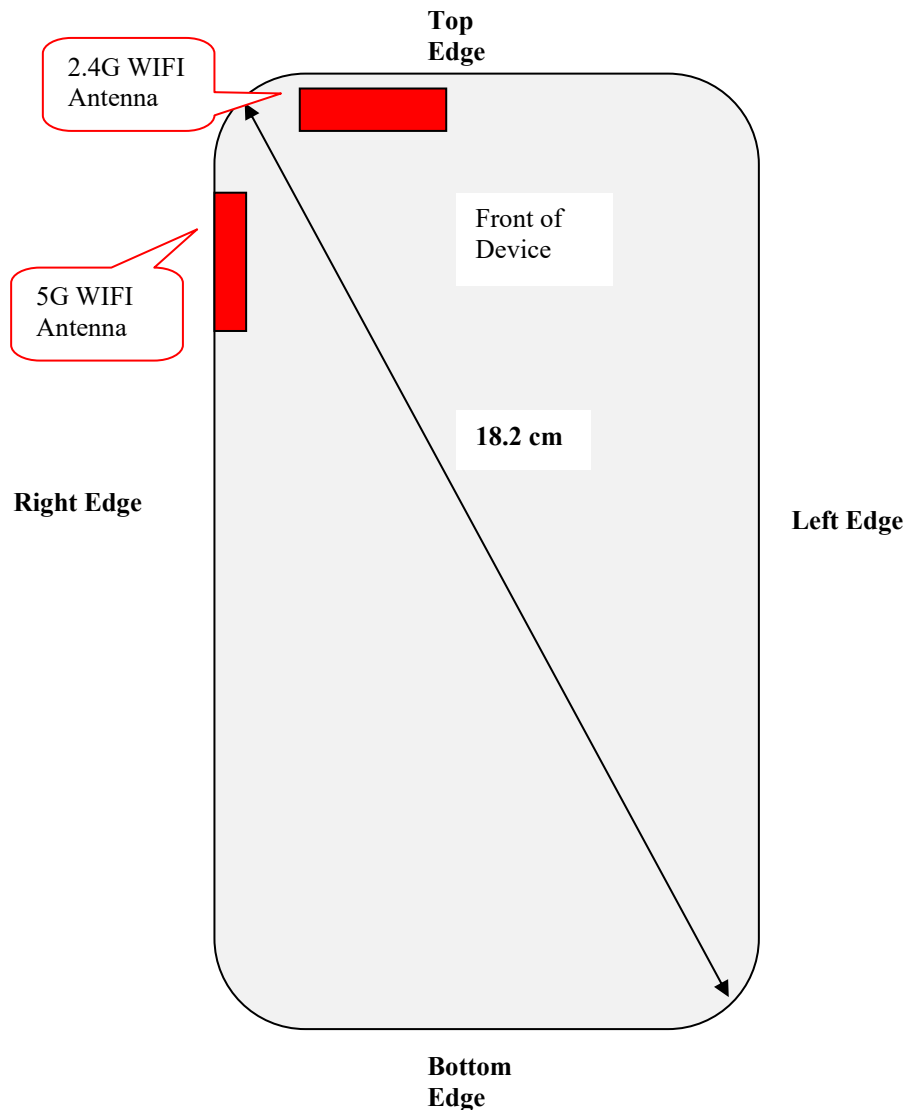
## 5G Mode

Mode	Channel number	Frequency (MHz)	Average Output Power(dBm)	Average Tune up limited(dBm)
802.11a	36	5180	14.28	14±0.5
	40	5200	14.22	14±0.5
	44	5240	14.26	14±0.5
802.11n(HT20)	36	5180	13.25	13±0.5
	40	5200	13.09	13±0.5
	44	5240	13.05	13±0.5
802.11n(HT40)	38	5190	12.31	12±0.5
	46	5230	12.18	12±0.5

**Note:** 1. WIFI power was test and only Maximum Power was provide here.  
 2. SAR Test Exclusion Threshold for WIFI is about 9.6mW, the maximum tune up power of WIFI is 15.5dBm=35.48mW, stand-alone SAR is required.

## 10 Exposure Conditions Consideration

### 1.EUT antenna location:



### 2.Test positions & distance of Antenna-User

Antenna	Edge/Antenna	Distance(mm)	SAR conclusion
2.4G WIFI	BACK	2	Yes
2.4G WIFI	Top	2	Yes
2.4G WIFI	Right	12	Yes
2.4G WIFI	Left	50	No
2.4G WIFI	Bottom	145	No
5G WIFI	BACK	2	Yes
5G WIFI	Top	30	No
5G WIFI	Right	5	Yes
5G WIFI	Left	70	No
5G WIFI	Bottom	110	No

Note: When the distance between the main antenna and the edge is >2.5cm, SAR is not required.



## 11 SAR TEST RESULTS

### Test Condition:

1. SAR Measurement  
The distance between the EUT and the antenna of the emulator is more than 50 cm and the output power radiated from the emulator antenna is at least 30 dB less than the output power of EUT.
2. Measurement Uncertainty: See page 26 for detail
3. Environmental Conditions
 

Temperature	23°C
Relative Humidity	53%
Atmospheric Pressure	1019mbar
4. Test Date : May 17th, 2016~ May 18th, 2016  
Tested By : Wiky Jam

### SAR Summary Test Result:

#### 2.4 G (802.11b)

Date of Measured : May 17,2016				Body Separation Distance:0.5cm			
Position	Channel	SAR 1g(W/kg)	Limit (W/kg)	Power Drift (%)	Maximum Turn-up Power(dBm)	measured output power (dBm)	Scaled Maximum SAR(W/kg)
Body-Front	Mid	0.099	1.6	2.75	15.5	15.47	0.10
Body-Back	Mid	0.533	1.6	0.81	15.5	15.47	0.54
Body-Right	Mid	0.055	1.6	0.24	15.5	15.47	0.06
Body-Top	Mid	0.052	1.6	0.98	15.5	15.47	0.05

#### 5 G (802.11a)

Date of Measured :May 18,2016				Body Separation Distance:0.5cm			
Position	Channel	SAR 1g(W/kg)	Limit (W/kg)	Power Drift (%)	Maximum Turn-up Power(dBm)	measured output power (dBm)	Scaled Maximum SAR(W/kg)
Body-Front	Mid	0.135	1.6	-0.94	14.5	14.22	0.14
Body-Back	Mid	0.245	1.6	-0.66	14.5	14.22	0.26
Body-Right	Mid	0.184	1.6	-0.82	14.5	14.22	0.20

### Measurement variability consideration

According to KDB 865664 D01v01 section 2.8.1, repeated measurements are required following the procedures as below:

1. Repeated measurement is not required when the original highest measured SAR is  $< 0.80\text{W/kg}$ ; steps 2) through 4) do not apply.
2. When the original highest measured SAR is  $\geq 0.80\text{ W/kg}$ , repeat that measurement once.
3. Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is  $> 1.20$  or when the original or repeated measurement is  $\geq 1.45\text{ W/kg}$  (~ 10% from the 1-g SAR limit).
4. Perform a third repeated measurement only if the original, first or second repeated measurement is  $\geq 1.5\text{ W/kg}$  and the ratio of largest to smallest SAR for the original, first and second repeated measurements is  $> 1.20$ .  
Measured SAR (W/Kg)

## **12 SAR MEASUREMENT REFERENCES**

### **References**

1. FCC 47 CFR Part 2 “Frequency Allocations and Radio Treaty Matters; General Rules and Regulations”
2. IEEE Std. C95.1-1999, “IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3kHz to 300GHz”, 1999
3. IEEE Std. 1528-2013, “IEEE Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques”, June 2013
4. IEC 62209-2, “Human exposure to radio frequency fields from hand-held and body-mounted wireless communication devices—Human models, instrumentation, and procedures – Part 2: Procedure to determine the specific absorption rate(SAR) for wireless communication devices used in close proximity to the human body(frequency range of 30MHz to 6GHz)”, March 2010
5. FCC KDB 447498 D01 v06, “RF Exposure Procedures and Equipment Authorization Policies For Mobile and Portable Device”, October 23, 2015
6. FCC KDB 941225 D01 v03r01, “3G SAR Measurement Procedures”, October 23, 2015
7. FCC KDB 865664 D01 v01r04, “SAR Measurement Requirements For 100MHz to 6GHz”, August 7, 2015
8. FCC KDB648474 D04 v01r03, “SAR Evaluation Considerations for Wireless Handsets”. October 23, 2015
9. FCC KDB 941225 D06 v02r01, Hot Spot SAR ,October 23, 2015
10. FCC KDB 248227 D01 v02r02, 802.11 Wi-Fi SAR ,October 23, 2015

## Maximum SAR measurement Plots

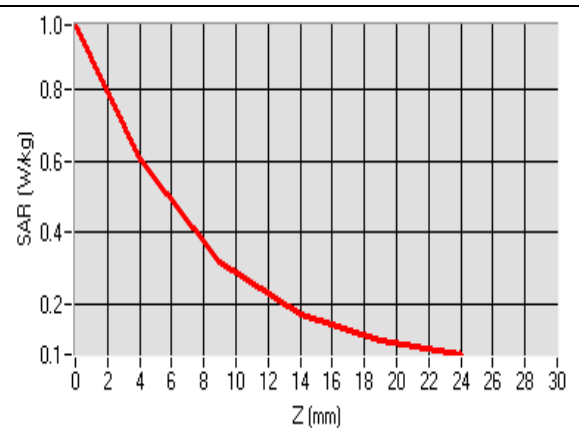
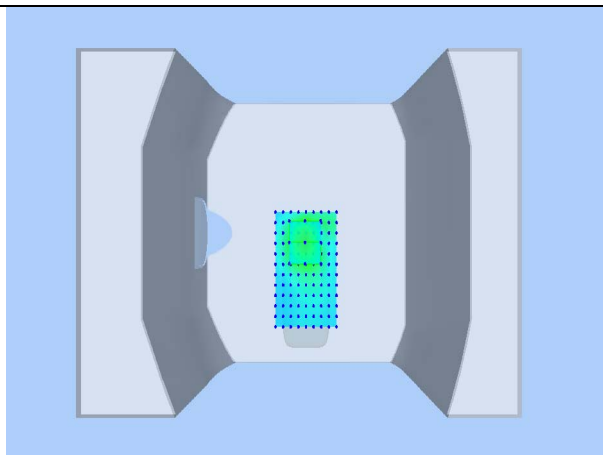
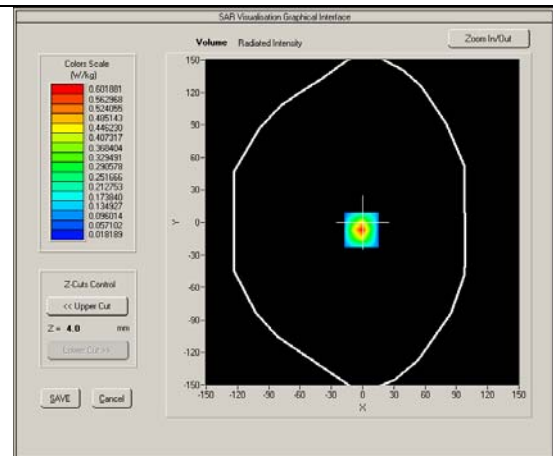
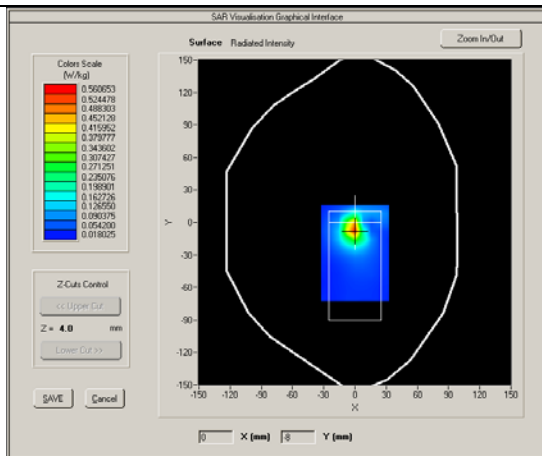
Test mode: 802.11b, Middle channel (Body-back)

Product Description: 6 inch Tablet Remote

Model: XR6

Test Date: May 17,2016

Medium(liquid type)	MSL_2450
Frequency (MHz)	2437.00
Relative permittivity (real part)	52.72
Conductivity (S/m)	1.98
E-Field Probe	SN 27/15 EPGO262
Crest factor	1.0
Conversion Factor	2.29
Sensor-Surface	4mm
Area Scan	dx=8mm dy=8mm
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm
Variation (%)	0.810000
SAR 10g (W/Kg)	0.241315
SAR 1g (W/Kg)	0.533397
<b>SURFACE SAR</b>	<b>VOLUME SAR</b>



Test mode: 802.11a, Middle channel (Body-back)

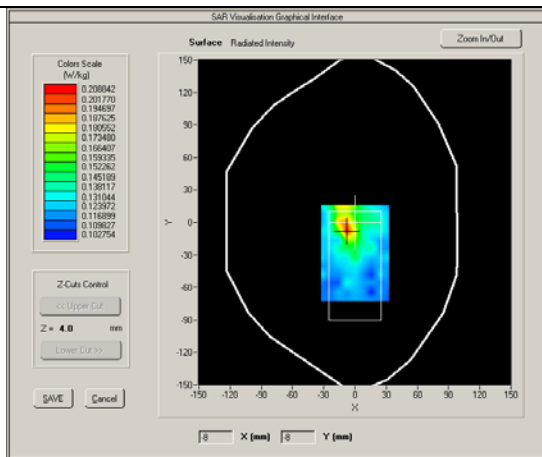
Product Description: 6 inch Tablet Remote

Model: XR6

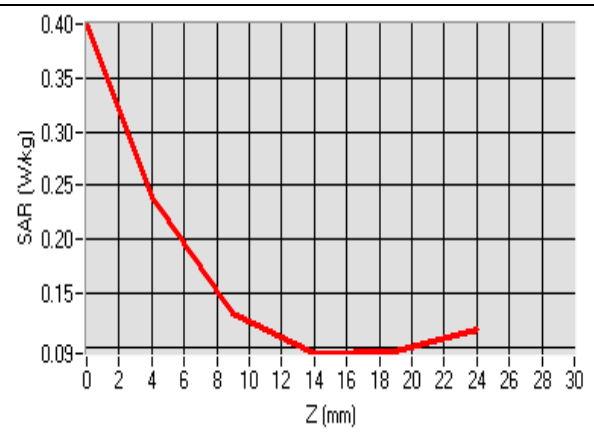
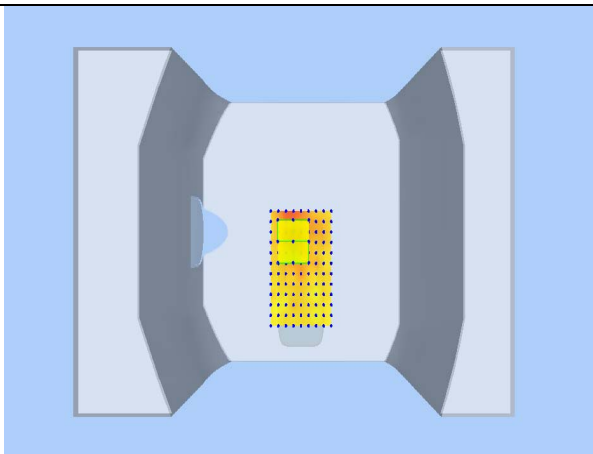
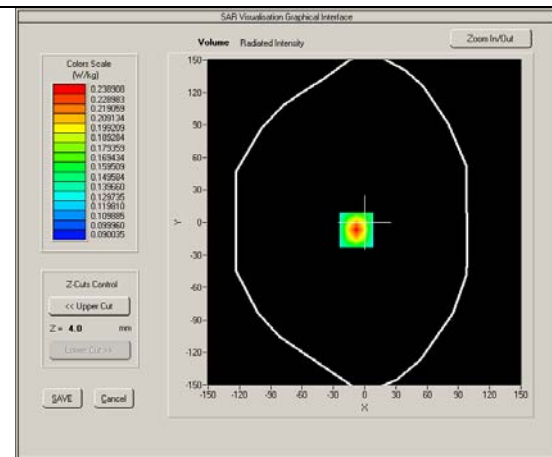
Test Date: May 18,2016

Medium(liquid type)	MSL_5200
Frequency (MHz)	5200.00
Relative permittivity (real part)	50.67
Conductivity (S/m)	5.13
E-Field Probe	SN 27/15 EPGO262
Crest factor	1.0
Conversion Factor	2.04
Sensor-Surface	4mm
Area Scan	dx=8mm dy=8mm
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm
Variation (%)	-0.660000
SAR 10g (W/Kg)	0.163386
SAR 1g (W/Kg)	0.244980

### SURFACE SAR



### VOLUME SAR



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## Annex A CALIBRATION REPORTS



### COMOSAR E-Field Probe Calibration Report

Ref : ACR.265.1.15.SATU.A

#### SIEMIC TESTING AND CERTIFICATION SERVICES

ZONE A,FLOOR 1,BUILDING 2,WAN YE LONG  
TECHNOLOGY PARK,SOUTH SIDE OF ZHOUSHI ROAD,  
SHIYAN STREET,BAO'AN DISTRICT, SHENZHEN 518108 ,  
GUANGDONG , P.R.C.

**MVG COMOSAR DOSIMETRIC E-FIELD PROBE**  
SERIAL NO.: SN 27/15 EPG0262

Calibrated at MVG US  
2105 Barrett Park Dr. - Kennesaw, GA 30144



Calibration Date: 07/09/2015

#### Summary:



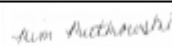
This document presents the method and results from an accredited COMOSAR Dosimetric E-Field Probe calibration performed in MVG USA using the CALISAR / CALIBAIR test bench, for use with a COMOSAR system only. All calibration results are traceable to national metrology institutions.

Test Report	16070501-FCC-H
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**COMOSAR E-FIELD PROBE CALIBRATION REPORT**

Ref: ACR.265.1.15.SATU.A

	<i>Name</i>	<i>Function</i>	<i>Date</i>	<i>Signature</i>
<i>Prepared by :</i>	Jérôme LUC	Product Manager	9/22/2015	
<i>Checked by :</i>	Jérôme LUC	Product Manager	9/22/2015	
<i>Approved by :</i>	Kim RUTKOWSKI	Quality Manager	9/22/2015	

	<i>Customer Name</i>
<i>Distribution :</i>	SIEMIC TESTING AND CERTIFICATION SERVICES

<i>Issue</i>	<i>Date</i>	<i>Modifications</i>
A	9/22/2015	Initial release



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## COMOSAR E-FIELD PROBE CALIBRATION REPORT

Ref: ACR.265.1.15.SATU.A

### 1 DEVICE UNDER TEST

Device Under Test	
Device Type	COMOSAR DOSIMETRIC E FIELD PROBE
Manufacturer	MVG
Model	SSE2
Serial Number	SN 27/15 EPGO262
Product Condition (new / used)	New
Frequency Range of Probe	0.7 GHz-6GHz
Resistance of Three Dipoles at Connector	Dipole 1: R1=0.222 MΩ Dipole 2: R2=0.200 MΩ Dipole 3: R3=0.200 MΩ

A yearly calibration interval is recommended.

### 2 PRODUCT DESCRIPTION

#### 2.1 GENERAL INFORMATION

MVG's COMOSAR E field Probes are built in accordance to the IEEE 1528, OET 65 Bulletin C and CEI/IEC 62209 standards.



Figure 1 – MVG COMOSAR Dosimetric E field Dipole

Probe Length	330 mm
Length of Individual Dipoles	2 mm
Maximum external diameter	8 mm
Probe Tip External Diameter	2.5 mm
Distance between dipoles / probe extremity	1 mm

### 3 MEASUREMENT METHOD

The IEEE 1528, OET 65 Bulletin C, CENELEC EN50361 and CEI/IEC 62209 standards provide recommended practices for the probe calibrations, including the performance characteristics of interest and methods by which to assess their affect. All calibrations / measurements performed meet the fore mentioned standards.

#### 3.1 LINEARITY

The evaluation of the linearity was done in free space using the waveguide, performing a power sweep to cover the SAR range 0.01W/kg to 100W/kg

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## COMOSAR E-FIELD PROBE CALIBRATION REPORT

Ref: ACR.265.1.15.SATU.A

### 3.2 SENSITIVITY

The sensitivity factors of the three dipoles were determined using a two step calibration method (air and tissue simulating liquid) using waveguides as outlined in the standards.

### 3.3 LOWER DETECTION LIMIT

The lower detection limit was assessed using the same measurement set up as used for the linearity measurement. The required lower detection limit is 10 mW/kg.

### 3.4 ISOTROPY

The axial isotropy was evaluated by exposing the probe to a reference wave from a standard dipole with the dipole mounted under the flat phantom in the test configuration suggested for system validations and checks. The probe was rotated along its main axis from 0 - 360 degrees in 15 degree steps. The hemispherical isotropy is determined by inserting the probe in a thin plastic box filled with tissue-equivalent liquid, with the plastic box illuminated with the fields from a half wave dipole. The dipole is rotated about its axis (0°–180°) in 15° increments. At each step the probe is rotated about its axis (0°–360°).

### 3.5 BOUNDARY EFFECT

The boundary effect is defined as the deviation between the SAR measured data and the expected exponential decay in the liquid when the probe is oriented normal to the interface. To evaluate this effect, the liquid filled flat phantom is exposed to fields from either a reference dipole or waveguide. With the probe normal to the phantom surface, the peak spatial average SAR is measured and compared to the analytical value at the surface.

## 4 MEASUREMENT UNCERTAINTY

The guidelines outlined in the IEEE 1528, OET 65 Bulletin C, CENELEC EN50361 and CEI/IEC 62209 standards were followed to generate the measurement uncertainty associated with an E-field probe calibration using the waveguide technique. All uncertainties listed below represent an expanded uncertainty expressed at approximately the 95% confidence level using a coverage factor of k=2, traceable to the Internationally Accepted Guides to Measurement Uncertainty.

Uncertainty analysis of the probe calibration in waveguide					
ERROR SOURCES	Uncertainty value (%)	Probability Distribution	Divisor	ci	Standard Uncertainty (%)
Incident or forward power	3.00%	Rectangular	$\sqrt{3}$	1	1.732%
Reflected power	3.00%	Rectangular	$\sqrt{3}$	1	1.732%
Liquid conductivity	5.00%	Rectangular	$\sqrt{3}$	1	2.887%
Liquid permittivity	4.00%	Rectangular	$\sqrt{3}$	1	2.309%
Field homogeneity	3.00%	Rectangular	$\sqrt{3}$	1	1.732%
Field probe positioning	5.00%	Rectangular	$\sqrt{3}$	1	2.887%

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**COMOSAR E-FIELD PROBE CALIBRATION REPORT**

Ref: ACR.265.1.15.SATU.A

Field probe linearity	3.00%	Rectangular	$\sqrt{3}$	1	1.732%
Combined standard uncertainty					5.831%
Expanded uncertainty 95 % confidence level k = 2					12.0%

## 5 CALIBRATION MEASUREMENT RESULTS

Calibration Parameters	
Liquid Temperature	21 °C
Lab Temperature	21 °C
Lab Humidity	45 %

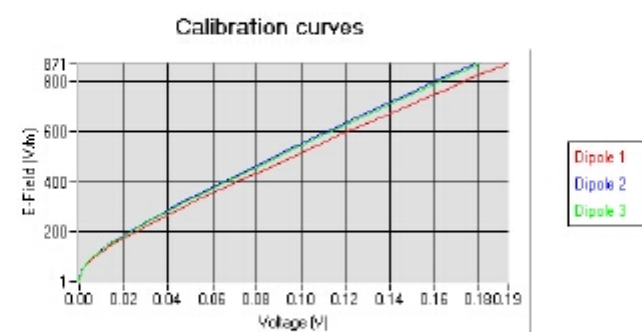
### 5.1 SENSITIVITY IN AIR

Normx dipole 1 ( $\mu\text{V}/(\text{V}/\text{m})^2$ )	Normy dipole 2 ( $\mu\text{V}/(\text{V}/\text{m})^2$ )	Normz dipole 3 ( $\mu\text{V}/(\text{V}/\text{m})^2$ )
0.78	0.70	0.72

DCP dipole 1 (mV)	DCP dipole 2 (mV)	DCP dipole 3 (mV)
92	90	90

Calibration curves  $e_i=f(V)$  ( $i=1,2,3$ ) allow to obtain H-field value using the formula:

$$E = \sqrt{E_1^2 + E_2^2 + E_3^2}$$

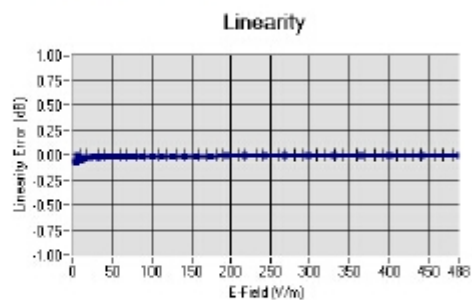




COMOSAR E-FIELD PROBE CALIBRATION REPORT

Ref: ACR.265.1.15.SATU.A

## 5.2 LINEARITY



Linearity  $\pm 1.78\%$  ( $\pm 0.08\text{dB}$ )

## 5.3 SENSITIVITY IN LIQUID

Liquid	Frequency (MHz $\pm$ 100MHz)	Permittivity	Epsilon (S/m)	ConvF
HL750	750	41.82	0.90	1.68
BL750	750	56.28	0.98	1.74
HL850	835	42.59	0.90	1.90
BL850	835	53.19	0.97	1.97
HL900	900	42.05	0.98	1.75
BL900	900	56.41	1.08	1.81
HL1800	1800	41.82	1.38	2.01
BL1800	1800	53.00	1.52	2.05
HL1900	1900	40.38	1.41	2.26
BL1900	1900	53.93	1.55	2.32
HL2000	2000	40.12	1.43	2.16
BL2000	2000	53.65	1.54	2.25
HL2450	2450	38.34	1.80	2.22
BL2450	2450	52.70	1.94	2.29
HL2600	2600	38.16	1.93	2.28
BL2600	2600	51.55	2.21	2.34
HL3500	3500	37.01	2.89	2.31
BL3500	3500	52.99	3.20	2.40
HL5200	5200	36.44	4.79	1.96
BL5200	5200	50.70	5.11	2.04
HL5400	5400	35.99	4.91	2.11
BL5400	5400	50.01	5.64	2.22
HL5600	5600	35.22	5.18	2.15
BL5600	5600	49.34	5.85	2.21
HL5800	5800	34.95	5.42	2.13
BL5800	5800	48.54	6.22	2.18

LOWER DETECTION LIMIT: 8mW/kg

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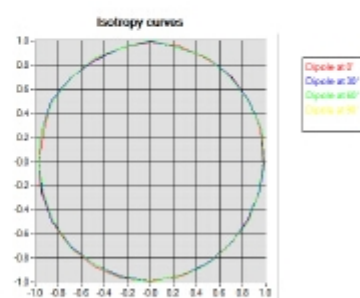
**COMOSAR E-FIELD PROBE CALIBRATION REPORT**

Ref: ACR.265.1.15.SATU.A

**5.4 ISOTROPY**

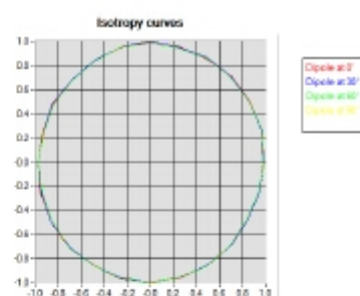
**HL5600 MHz**

- Axial isotropy: 0.04 dB
- Hemispherical isotropy: 0.05 dB



**HL5600 MHz**

- Axial isotropy: 0.04 dB
- Hemispherical isotropy: 0.07 dB



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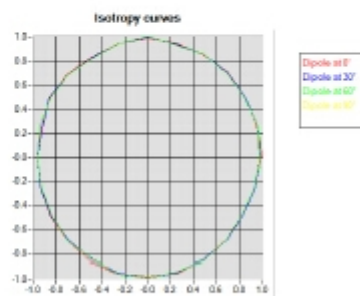


**COMOSAR E-FIELD PROBE CALIBRATION REPORT**

Ref: ACR.265.1.15.SATU.A

**HL5600 MHz**

- Axial isotropy: 0.06 dB
- Hemispherical isotropy: 0.10 dB





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COMOSAR E-FIELD PROBE CALIBRATION REPORT

Ref. ACR.265.1.15.SATU.A

6 LIST OF EQUIPMENT

Equipment Summary Sheet				
Equipment Description	Manufacturer / Model	Identification No.	Current Calibration Date	Next Calibration Date
Flat Phantom	MVG	SN-20/09-SAM71	Validated. No cal required.	Validated. No cal required.
COMOSAR Test Bench	Version 3	NA	Validated. No cal required.	Validated. No cal required.
Network Analyzer	Rhode & Schwarz ZVA	SN100132	02/2013	02/2016
Reference Probe	MVG	EP 94 SN 37/08	10/2014	10/2015
Multimeter	Keithley 2000	1188656	12/2013	12/2016
Signal Generator	Agilent E4438C	MY49070581	12/2013	12/2016
Amplifier	Aethercomm	SN 046	Characterized prior to test. No cal required.	Characterized prior to test. No cal required.
Power Meter	HP E4418A	US38261498	12/2013	12/2016
Power Sensor	HP ECP-E26A	US37181460	12/2013	12/2016
Directional Coupler	Narda 4216-20	01386	Characterized prior to test. No cal required.	Characterized prior to test. No cal required.
Waveguide	Mega Industries	069Y7-158-13-712	Validated. No cal required.	Validated. No cal required.
Waveguide Transition	Mega Industries	069Y7-158-13-701	Validated. No cal required.	Validated. No cal required.
Waveguide Termination	Mega Industries	069Y7-158-13-701	Validated. No cal required.	Validated. No cal required.
Temperature / Humidity Sensor	Control Company	11-661-9	8/2012	8/2015

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## **SAR Reference Dipole Calibration Report**

Ref : ACR.170.6.14.SATU.A

### **SIEMIC TESTING AND CERTIFICATION SERVICES**

**ZONE A,FLOOR 1,BUILDING 2,WAN YE LONG  
TECHNOLOGY PARK,SOUTH SIDE OF ZHOUSHI ROAD,  
SHIYAN STREET,BAO'AN DISTRICT, SHENZHEN 518108 ,  
GUANGDONG , P.R.C.**

### **SATIMO COMOSAR REFERENCE DIPOLE**

**FREQUENCY: 2450 MHZ**

**SERIAL NO.: SN 18/11 DIPJ155**

**Calibrated at SATIMO US  
2105 Barrett Park Dr. - Kennesaw, GA 30144**



**06/18/2014**

#### *Summary:*

This document presents the method and results from an accredited SAR reference dipole calibration performed in SATIMO USA using the COMOSAR test bench. All calibration results are traceable to national metrology institutions.

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**SAR REFERENCE DIPOLE CALIBRATION REPORT**

Ref: ACR.170.6.14.SATU.A

	<i>Name</i>	<i>Function</i>	<i>Date</i>	<i>Signature</i>
<i>Prepared by :</i>	Jérôme LUC	Product Manager	6/19/2014	<i>JS</i>
<i>Checked by :</i>	Jérôme LUC	Product Manager	6/19/2014	<i>JS</i>
<i>Approved by :</i>	Kim RUTKOWSKI	Quality Manager	6/19/2014	<i>Kim Rutkowski</i>

	<i>Customer Name</i>
<i>Distribution :</i>	SIEMIC Testing and Certification Services

<i>Issue</i>	<i>Date</i>	<i>Modifications</i>
A	6/19/2014	Initial release



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## 1 INTRODUCTION

This document contains a summary of the requirements set forth by the IEEE 1528, OET 65 Bulletin C and CEI/IEC 62209 standards for reference dipoles used for SAR measurement system validations and the measurements that were performed to verify that the product complies with the fore mentioned standards.

## 2 DEVICE UNDER TEST

Device Under Test	
Device Type	COMOSAR 2450 MHz REFERENCE DIPOLE
Manufacturer	Satimo
Model	SID2450
Serial Number	SN 18/11 DIPJ155
Product Condition (new / used)	used

A yearly calibration interval is recommended.

## 3 PRODUCT DESCRIPTION

### 3.1 GENERAL INFORMATION

Satimo's COMOSAR Validation Dipoles are built in accordance to the IEEE 1528, OET 65 Bulletin C and CEI/IEC 62209 standards. The product is designed for use with the COMOSAR test bench only.



**Figure 1 – Satimo COMOSAR Validation Dipole**

## 4 MEASUREMENT METHOD

The IEEE 1528, OET 65 Bulletin C and CEI/IEC 62209 standards provide requirements for reference dipoles used for system validation measurements. The following measurements were performed to verify that the product complies with the fore mentioned standards.

### 4.1 RETURN LOSS REQUIREMENTS

The dipole used for SAR system validation measurements and checks must have a return loss of -20 dB or better. The return loss measurement shall be performed against a liquid filled flat phantom, with the phantom constructed as outlined in the fore mentioned standards.

### 4.2 MECHANICAL REQUIREMENTS

The IEEE Std. 1528 and CEI/IEC 62209 standards specify the mechanical components and dimensions of the validation dipoles, with the dimensions frequency and phantom shell thickness dependent. The COMOSAR test bench employs a 2 mm phantom shell thickness therefore the dipoles sold for use with the COMOSAR test bench comply with the requirements set forth for a 2 mm phantom shell thickness.

## 5 MEASUREMENT UNCERTAINTY

All uncertainties listed below represent an expanded uncertainty expressed at approximately the 95% confidence level using a coverage factor of  $k=2$ , traceable to the Internationally Accepted Guides to Measurement Uncertainty.

### 5.1 RETURN LOSS

The following uncertainties apply to the return loss measurement:

Frequency band	Expanded Uncertainty on Return Loss
400-6000MHz	0.1 dB

### 5.2 DIMENSION MEASUREMENT

The following uncertainties apply to the dimension measurements:

Length (mm)	Expanded Uncertainty on Length
3 - 300	0.05 mm

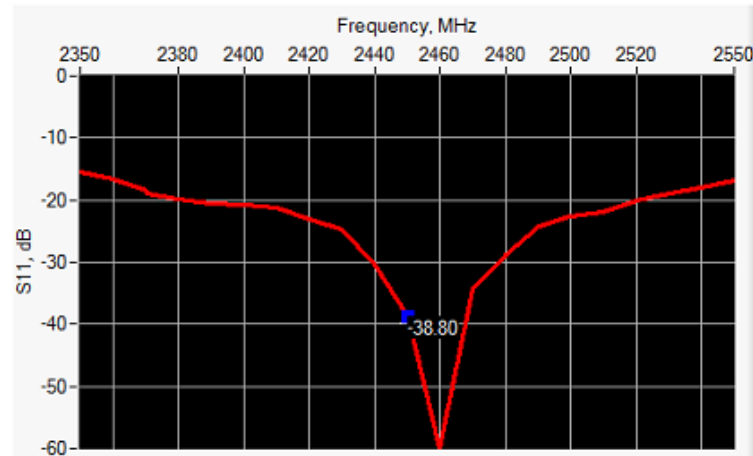
### 5.3 VALIDATION MEASUREMENT

The guidelines outlined in the IEEE 1528, OET 65 Bulletin C, CENELEC EN50361 and CEI/IEC 62209 standards were followed to generate the measurement uncertainty for validation measurements.

Scan Volume	Expanded Uncertainty
1 g	20.3 %
10 g	20.1 %

## 6 CALIBRATION MEASUREMENT RESULTS

### 6.1 RETURN LOSS AND IMPEDANCE



Frequency (MHz)	Return Loss (dB)	Requirement (dB)	Impedance
2450	-38.80	-20	$49.9 \Omega + 1.2 j\Omega$

### 6.2 MECHANICAL DIMENSIONS

Frequency MHz	L mm		h mm		d mm	
	required	measured	required	measured	required	measured
300	420.0 ±1 %.		250.0 ±1 %.		6.35 ±1 %.	
450	290.0 ±1 %.		166.7 ±1 %.		6.35 ±1 %.	
750	176.0 ±1 %.		100.0 ±1 %.		6.35 ±1 %.	
835	161.0 ±1 %.		89.8 ±1 %.		3.6 ±1 %.	
900	149.0 ±1 %.		83.3 ±1 %.		3.6 ±1 %.	
1450	89.1 ±1 %.		51.7 ±1 %.		3.6 ±1 %.	
1500	80.5 ±1 %.		50.0 ±1 %.		3.6 ±1 %.	
1640	79.0 ±1 %.		45.7 ±1 %.		3.6 ±1 %.	
1750	75.2 ±1 %.		42.9 ±1 %.		3.6 ±1 %.	
1800	72.0 ±1 %.		41.7 ±1 %.		3.6 ±1 %.	
1900	68.0 ±1 %.		39.5 ±1 %.		3.6 ±1 %.	
1950	66.3 ±1 %.		38.5 ±1 %.		3.6 ±1 %.	
2000	64.5 ±1 %.		37.5 ±1 %.		3.6 ±1 %.	
2100	61.0 ±1 %.		35.7 ±1 %.		3.6 ±1 %.	
2300	55.5 ±1 %.		32.6 ±1 %.		3.6 ±1 %.	
2450	51.5 ±1 %.	PASS	30.4 ±1 %.	PASS	3.6 ±1 %.	PASS
2600	48.5 ±1 %.		28.8 ±1 %.		3.6 ±1 %.	
3000	41.5 ±1 %.		25.0 ±1 %.		3.6 ±1 %.	
3500	37.0 ±1 %.		26.4 ±1 %.		3.6 ±1 %.	
3700	34.7 ±1 %.		26.4 ±1 %.		3.6 ±1 %.	

## 7 VALIDATION MEASUREMENT

The IEEE Std. 1528, OET 65 Bulletin C and CEI/IEC 62209 standards state that the system validation measurements must be performed using a reference dipole meeting the fore mentioned return loss and mechanical dimension requirements. The validation measurement must be performed against a liquid filled flat phantom, with the phantom constructed as outlined in the fore mentioned standards. Per the standards, the dipole shall be positioned below the bottom of the phantom, with the dipole length centered and parallel to the longest dimension of the flat phantom, with the top surface of the dipole at the described distance from the bottom surface of the phantom.

### 7.1 MEASUREMENT CONDITION

Software	OPENSAR V4
Phantom	SN 20/09 SAM71
Probe	SN 18/11 EPG122
Liquid	Head Liquid Values: $\epsilon_r'$ : 39.1 sigma : 1.78
Distance between dipole center and liquid	10.0 mm
Area scan resolution	$dx=8mm/dy=8mm$
Zoon Scan Resolution	$dx=8mm/dy=8m/dz=5mm$
Frequency	2450 MHz
Input power	20 dBm
Liquid Temperature	21 °C
Lab Temperature	21 °C
Lab Humidity	45 %

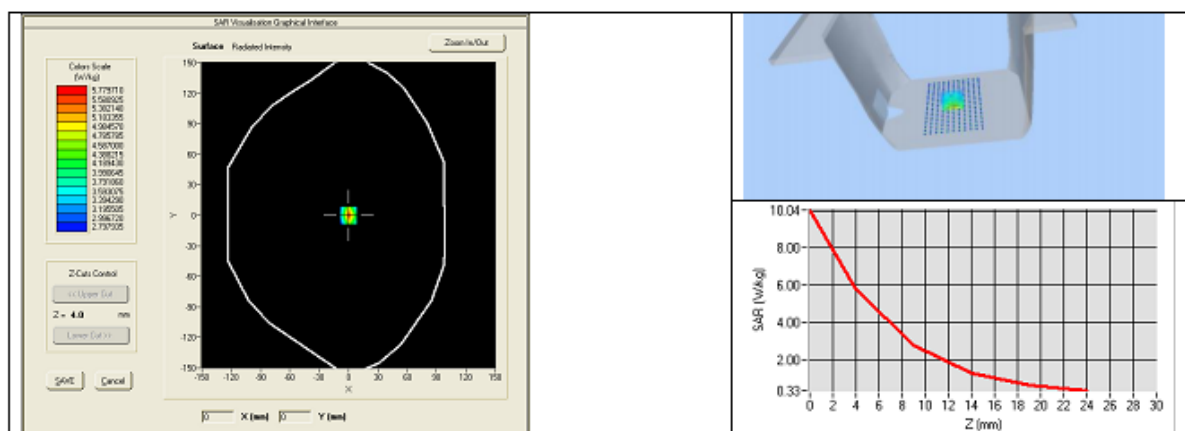
### 7.2 HEAD LIQUID MEASUREMENT

Frequency MHz	Relative permittivity ( $\epsilon_r'$ )		Conductivity ( $\sigma$ ) S/m	
	required	measured	required	measured
300	45.3 $\pm$ 5 %		0.87 $\pm$ 5 %	
450	43.5 $\pm$ 5 %		0.87 $\pm$ 5 %	
750	41.9 $\pm$ 5 %		0.89 $\pm$ 5 %	
835	41.5 $\pm$ 5 %		0.90 $\pm$ 5 %	
900	41.5 $\pm$ 5 %		0.97 $\pm$ 5 %	
1450	40.5 $\pm$ 5 %		1.20 $\pm$ 5 %	
1500	40.4 $\pm$ 5 %		1.23 $\pm$ 5 %	
1640	40.2 $\pm$ 5 %		1.31 $\pm$ 5 %	
1750	40.1 $\pm$ 5 %		1.37 $\pm$ 5 %	
1800	40.0 $\pm$ 5 %		1.40 $\pm$ 5 %	
1900	40.0 $\pm$ 5 %		1.40 $\pm$ 5 %	
1950	40.0 $\pm$ 5 %		1.40 $\pm$ 5 %	
2000	40.0 $\pm$ 5 %		1.40 $\pm$ 5 %	
2100	39.8 $\pm$ 5 %		1.49 $\pm$ 5 %	
2300	39.5 $\pm$ 5 %		1.67 $\pm$ 5 %	
2450	39.2 $\pm$ 5 %	PASS	1.80 $\pm$ 5 %	PASS
2600	39.0 $\pm$ 5 %		1.96 $\pm$ 5 %	
3000	38.5 $\pm$ 5 %		2.40 $\pm$ 5 %	
3500	37.9 $\pm$ 5 %		2.91 $\pm$ 5 %	

### 7.3 MEASUREMENT RESULT

The IEEE Std. 1528 and CEI/IEC 62209 standards state that the system validation measurements should produce the SAR values shown below (for phantom thickness of 2 mm), within the uncertainty for the system validation. All SAR values are normalized to 1 W forward power. In bracket, the measured SAR is given with the used input power.

Frequency MHz	1 g SAR (W/kg/W)		10 g SAR (W/kg/W)	
	required	measured	required	measured
300	2.85		1.94	
450	4.58		3.06	
750	8.49		5.55	
835	9.56		6.22	
900	10.9		6.99	
1450	29		16	
1500	30.5		16.8	
1640	34.2		18.4	
1750	36.4		19.3	
1800	38.4		20.1	
1900	39.7		20.5	
1950	40.5		20.9	
2000	41.1		21.1	
2100	43.6		21.9	
2300	48.7		23.3	
2450	52.4	55.06 (5.51)	24	24.17 (2.42)
2600	55.3		24.6	
3000	63.8		25.7	
3500	67.1		25	

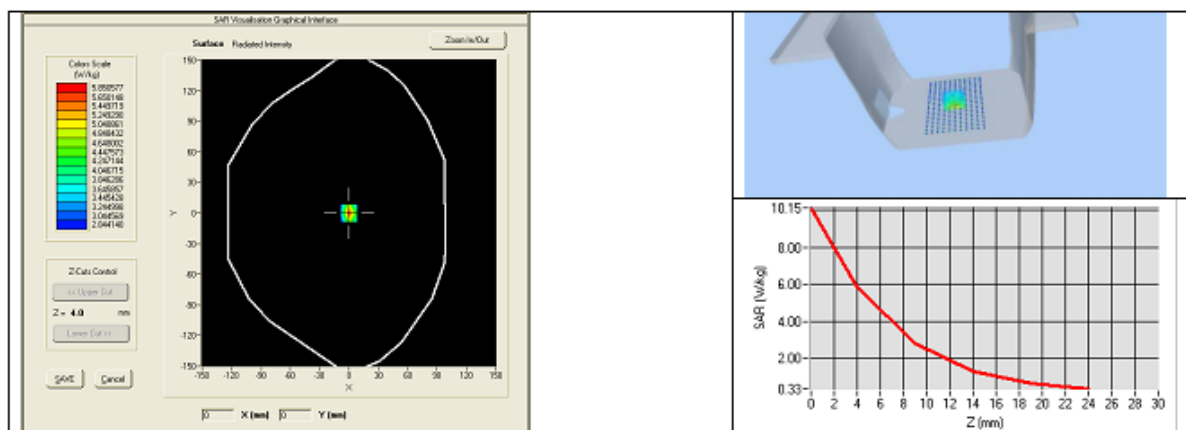




#### 7.4 BODY MEASUREMENT RESULT

Software	OPENSAR V4
Phantom	SN 20/09 SAM71
Probe	SN 18/11 EPG122
Liquid	Body Liquid Values: $\epsilon_{ps}' : 52.2$ $\sigma : 1.90$
Distance between dipole center and liquid	10.0 mm
Area scan resolution	$dx=8mm/dy=8mm$
Zoon Scan Resolution	$dx=8mm/dy=8m/dz=5mm$
Frequency	2450 MHz
Input power	20 dBm
Liquid Temperature	21 °C
Lab Temperature	21 °C
Lab Humidity	45 %

Frequency MHz	1 g SAR (W/kg/W)	10 g SAR (W/kg/W)
	measured	measured
2450	56.05 (5.60)	24.71 (2.47)





## 8 LIST OF EQUIPMENT

Equipment Summary Sheet				
Equipment Description	Manufacturer / Model	Identification No.	Current Calibration Date	Next Calibration Date
SAM Phantom	Satimo	SN-20/09-SAM71	Validated. No cal required.	Validated. No cal required.
COMOSAR Test Bench	Version 3	NA	Validated. No cal required.	Validated. No cal required.
Network Analyzer	Rhode & Schwarz ZVA	SN100132	02/2013	02/2016
Calipers	Carrera	CALIPER-01	12/2013	12/2016
Reference Probe	Satimo	EPG122 SN 18/11	Characterized prior to test. No cal required.	Characterized prior to test. No cal required.
Multimeter	Keithley 2000	1188656	12/2013	12/2016
Signal Generator	Agilent E4438C	MY49070581	12/2013	12/2016
Amplifier	Aethercomm	SN 046	Characterized prior to test. No cal required.	Characterized prior to test. No cal required.
Power Meter	HP E4418A	US38261498	12/2013	12/2016
Power Sensor	HP ECP-E26A	US37181460	12/2013	12/2016
Directional Coupler	Narda 4216-20	01386	Characterized prior to test. No cal required.	Characterized prior to test. No cal required.
Temperature and Humidity Sensor	Control Company	11-661-9	8/2012	8/2015





## **SAR Reference Waveguide Calibration Report**

Ref : ACR.170.8.14.SATU.A

### **SIEMIC TESTING AND CERTIFICATION SERVICES**

**ZONE A,FLOOR 1,BUILDING 2,WAN YE LONG  
TECHNOLOGY PARK,SOUTH SIDE OF ZHOUSHI ROAD,  
SHIYAN STREET,BAO'AN DISTRICT, SHENZHEN 518108 ,  
GUANGDONG , P.R.C.**

### **SATIMO COMOSAR REFERENCE WAVEGUIDE**

**FREQUENCY: 5000-6000 MHZ**

**SERIAL NO.: SN 24/11 WGA16**

**Calibrated at SATIMO US**

**2105 Barrett Park Dr. - Kennesaw, GA 30144**



**06/18/2014**

#### *Summary:*

This document presents the method and results from an accredited SAR reference waveguide calibration performed in SATIMO USA using the COMOSAR test bench. All calibration results are traceable to national metrology institutions.

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**SAR REFERENCE WAVEGUIDE CALIBRATION REPORT**

Ref: ACR.170.8.14.SATU.A

	<i>Name</i>	<i>Function</i>	<i>Date</i>	<i>Signature</i>
<i>Prepared by :</i>	Jérôme LUC	Product Manager	6/19/2014	
<i>Checked by :</i>	Jérôme LUC	Product Manager	6/19/2014	
<i>Approved by :</i>	Kim RUTKOWSKI	Quality Manager	6/19/2014	

	<i>Customer Name</i>
<i>Distribution :</i>	SIEMIC Testing and Certification Services

<i>Issue</i>	<i>Date</i>	<i>Modifications</i>
A	6/19/2014	Initial release

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## 1 INTRODUCTION

This document contains a summary of the requirements set forth by the IEEE 1528 and CEI/IEC 62209 standards for reference waveguides used for SAR measurement system validations and the measurements that were performed to verify that the product complies with the fore mentioned standards.

## 2 DEVICE UNDER TEST

Device Under Test	
Device Type	COMOSAR 5000-6000 MHz REFERENCE WAVEGUIDE
Manufacturer	Satimo
Model	SWG5500
Serial Number	SN 24/11 WGA16
Product Condition (new / used)	used

A yearly calibration interval is recommended.

## 3 PRODUCT DESCRIPTION

### 3.1 GENERAL INFORMATION

Satimo's COMOSAR Validation Waveguides are built in accordance to the IEEE 1528 and CEI/IEC 62209 standards.

## 4 MEASUREMENT METHOD

The IEEE 1528 and CEI/IEC 62209 standards provide requirements for reference waveguides used for system validation measurements. The following measurements were performed to verify that the product complies with the fore mentioned standards.

### 4.1 RETURN LOSS REQUIREMENTS

The waveguide used for SAR system validation measurements and checks must have a return loss of -8 dB or better. The return loss measurement shall be performed with matching layer placed in the open end of the waveguide, with the waveguide and matching layer in direct contact with the phantom shell as outlined in the fore mentioned standards.

### 4.2 MECHANICAL REQUIREMENTS

The IEEE 1528 and CEI/IEC 62209 standards specify the mechanical dimensions of the validation waveguide, the specified dimensions are as shown in Section 6.2. Figure 1 shows how the dimensions relate to the physical construction of the waveguide.

## 5 MEASUREMENT UNCERTAINTY

All uncertainties listed below represent an expanded uncertainty expressed at approximately the 95% confidence level using a coverage factor of  $k=2$ , traceable to the Internationally Accepted Guides to Measurement Uncertainty.

### 5.1 RETURN LOSS

The following uncertainties apply to the return loss measurement:

Frequency band	Expanded Uncertainty on Return Loss
400-6000MHz	0.1 dB

### 5.2 DIMENSION MEASUREMENT

The following uncertainties apply to the dimension measurements:

Length (mm)	Expanded Uncertainty on Length
3 - 300	0.05 mm

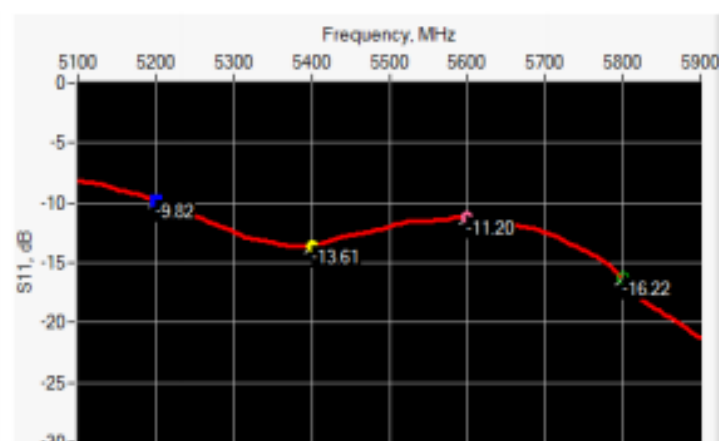
### 5.3 VALIDATION MEASUREMENT

The guidelines outlined in the IEEE 1528 and CEI/IEC 62209 standards were followed to generate the measurement uncertainty for validation measurements.

Scan Volume	Expanded Uncertainty
1 g	20.3 %
10 g	20.1 %

## 6 CALIBRATION MEASUREMENT RESULTS

### 6.1 RETURN LOSS



Frequency (MHz)	Return Loss (dB)	Requirement (dB)
5000-6000	< -8.18	-8



## 6.2 MECHANICAL DIMENSIONS

Frequency (MHz)	L (mm)		W (mm)		L <sub>c</sub> (mm)		W <sub>c</sub> (mm)		T (mm)	
	Require d	Measure d	Require d	Measure d	Require d	Measure d	Require d	Measure d	Require d	Measure d
5200	40.39 ± 0.13	PASS	20.19 ± 0.13	PASS	81.03 ± 0.13	PASS	61.98 ± 0.13	PASS	5.3*	PASS
5800	40.39 ± 0.13	PASS	20.19 ± 0.13	PASS	81.03 ± 0.13	PASS	61.98 ± 0.13	PASS	4.3*	PASS

\* The tolerance for the matching layer is included in the return loss measurement.

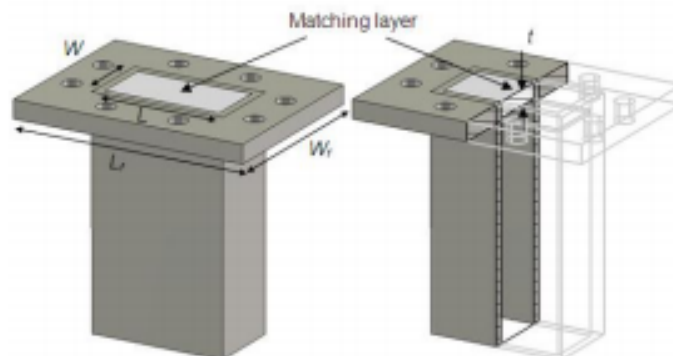


Figure 1: Validation Waveguide Dimensions

## 7 VALIDATION MEASUREMENT

The IEEE Std. 1528 and CEI/IEC 62209 standards state that the system validation measurements must be performed using a reference waveguide meeting the fore mentioned return loss and mechanical dimension requirements. The validation measurement must be performed with the matching layer placed in the open end of the waveguide, with the waveguide and matching layer in direct contact with the phantom shell.

### Measurement Condition

Software	OPENSAR V4
Phantom	SN 20/09 SAM71
Probe	SN 18/11 EPG122
Liquid	Head Liquid Values 5200 MHz: eps' :36.47 sigma : 4.91 Head Liquid Values 5400 MHz: eps' :36.83 sigma : 5.02 Head Liquid Values 5600 MHz: eps' :35.39 sigma : 5.49 Head Liquid Values 5800 MHz: eps' :34.91 sigma : 5.76
Distance between dipole waveguide and liquid	0 mm
Area scan resolution	dx=8mm/dy=8mm
Zoon Scan Resolution	dx=4mm/dy=4m/dz=2mm
Frequency	5200 MHz 5400 MHz 5600 MHz 5800 MHz
Input power	20 dBm
Liquid Temperature	21 °C
Lab Temperature	21 °C
Lab Humidity	45 %



## 7.1 HEAD LIQUID MEASUREMENT

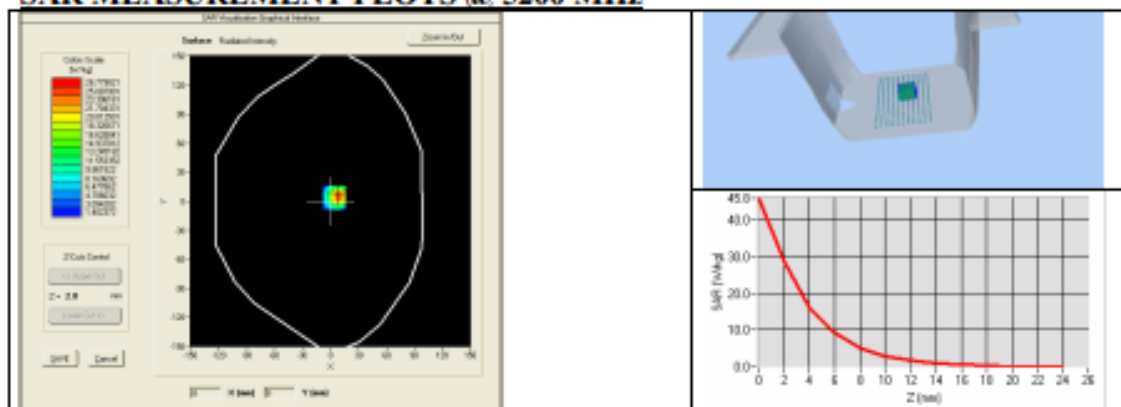
Frequency MHz	Relative permittivity ( $\epsilon_r$ )		Conductivity ( $\sigma$ ) S/m	
	required	measured	required	measured
5000	36.2 $\pm$ 10 %		4.45 $\pm$ 10 %	
5100	36.1 $\pm$ 10 %		4.56 $\pm$ 10 %	
5200	36.0 $\pm$ 10 %	PASS	4.66 $\pm$ 10 %	PASS
5300	35.9 $\pm$ 10 %		4.76 $\pm$ 10 %	
5400	35.8 $\pm$ 10 %	PASS	4.86 $\pm$ 10 %	PASS
5500	35.6 $\pm$ 10 %		4.97 $\pm$ 10 %	
5600	35.5 $\pm$ 10 %	PASS	5.07 $\pm$ 10 %	PASS
5700	35.4 $\pm$ 10 %		5.17 $\pm$ 10 %	
5800	35.3 $\pm$ 10 %	PASS	5.27 $\pm$ 10 %	PASS
5900	35.2 $\pm$ 10 %		5.38 $\pm$ 10 %	
6000	35.1 $\pm$ 10 %		5.48 $\pm$ 10 %	

## 7.2 MEASUREMENT RESULT

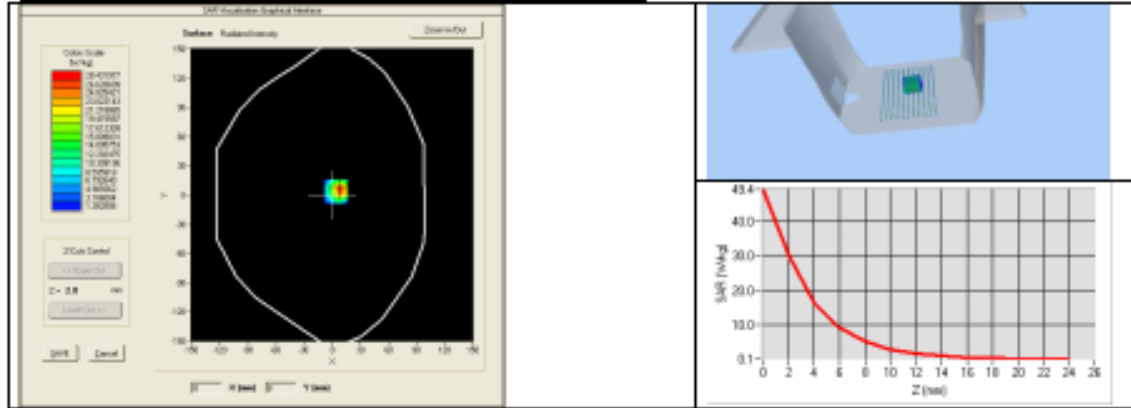
At those frequencies, the target SAR value can not be generic. Hereunder is the target SAR value defined by Satimo, within the uncertainty for the system validation. All SAR values are normalized to 1 W net power. In bracket, the measured SAR is given with the used input power.

Frequency (MHz)	1 g SAR (W/kg)		10 g SAR (W/kg)	
	required	measured	required	measured
5200	159.00	163.32 (16.33)	56.90	57.02 (5.70)
5400	166.40	170.07 (17.01)	58.43	58.55 (5.85)
5600	173.80	176.88 (17.69)	59.97	60.45 (6.04)
5800	181.20	182.74 (18.27)	61.50	61.72 (6.17)

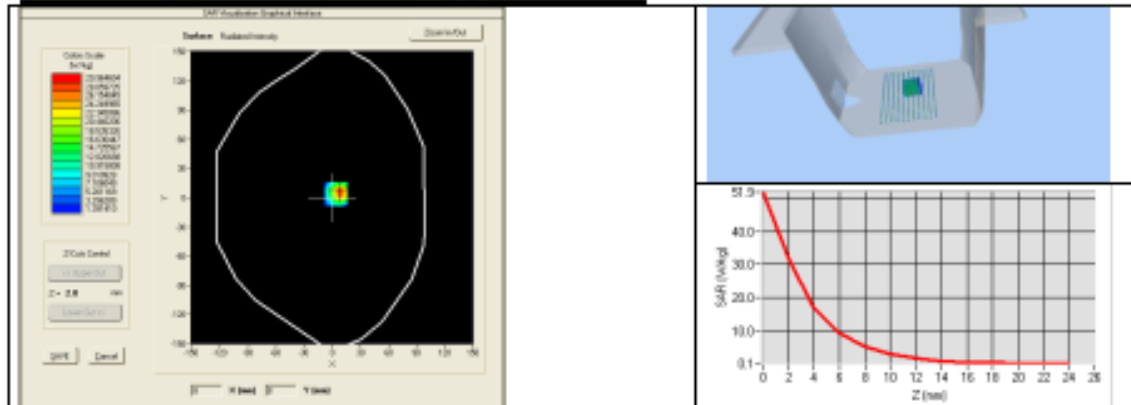
## SAR MEASUREMENT PLOTS @ 5200 MHz



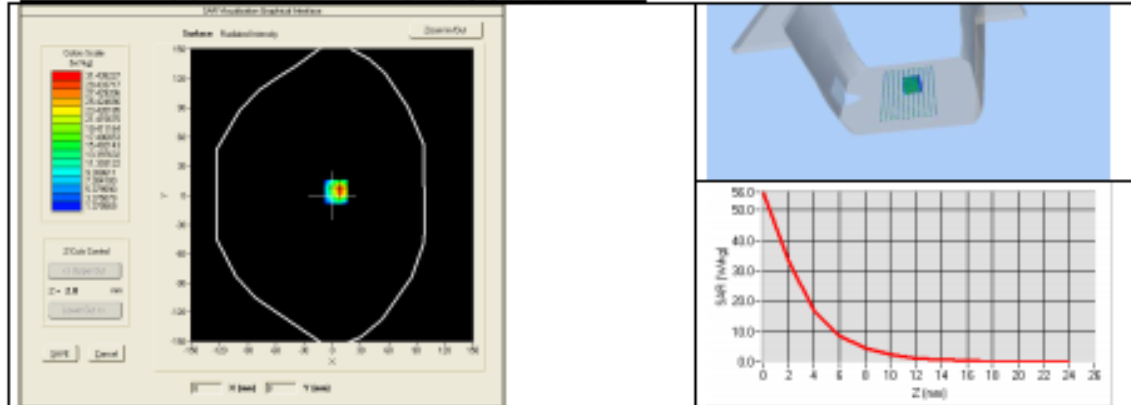
### SAR MEASUREMENT PLOTS @ 5400 MHz



### SAR MEASUREMENT PLOTS @ 5600 MHz



### SAR MEASUREMENT PLOTS @ 5800 MHz



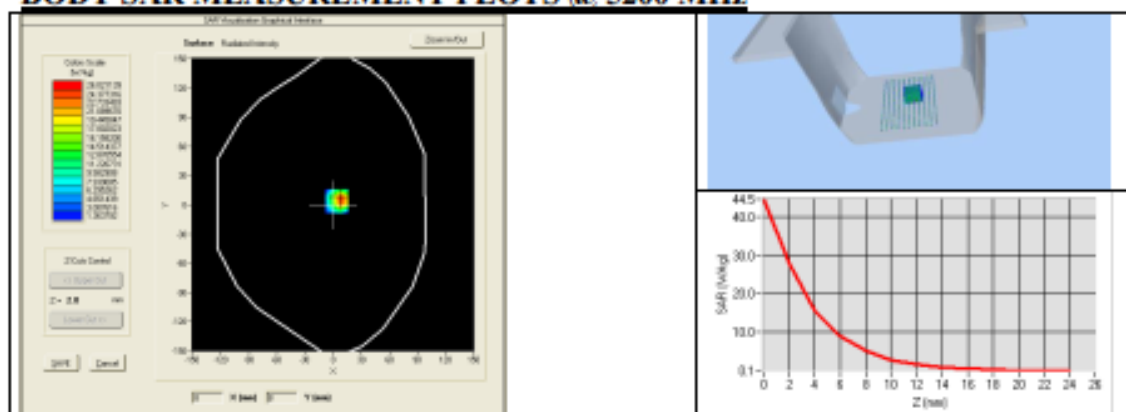


### 7.3 BODY MEASUREMENT RESULT

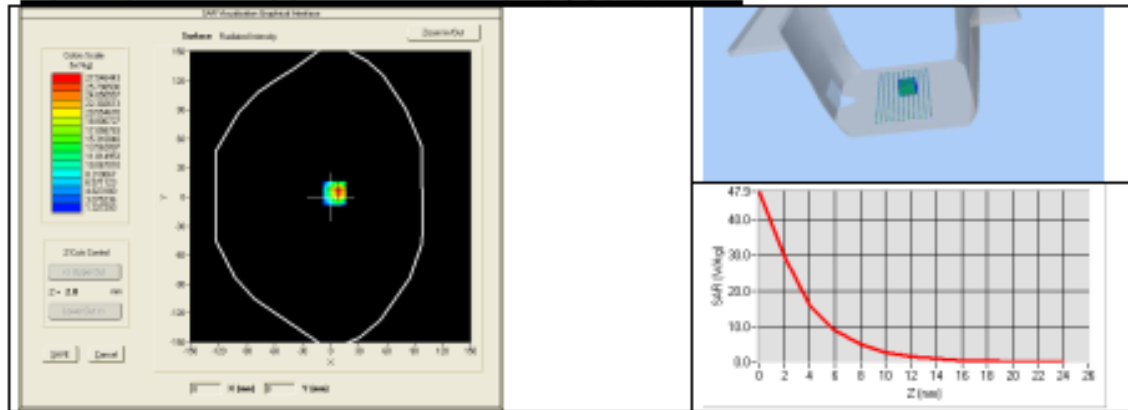
Software	OPENSAR V4
Phantom	SN 20/09 SAM71
Probe	SN 18/11 EPG122
Liquid	Body Liquid Values 5200 MHz: eps' :51.18 sigma : 4.84 Body Liquid Values 5400 MHz: eps' :48.35 sigma : 5.81 Body Liquid Values 5600 MHz: eps' :49.03 sigma : 6.17 Body Liquid Values 5800 MHz: eps' :47.18 sigma : 6.32
Distance between dipole waveguide and liquid	0 mm
Area scan resolution	dx=8mm/dy=8mm
Zoon Scan Resolution	dx=4mm/dy=4m/dz=2mm
Frequency	5200 MHz 5400 MHz 5600 MHz 5800 MHz
Input power	20 dBm
Liquid Temperature	21 °C
Lab Temperature	21 °C
Lab Humidity	45 %

Frequency (MHz)	1 g SAR (W/kg)	10 g SAR (W/kg)
	measured	measured
5200	158.88 (15.89)	55.44 (5.54)
5400	165.05 (16.51)	56.94 (5.69)
5600	171.26 (17.13)	58.30 (5.83)
5800	176.93 (17.69)	59.66 (5.97)

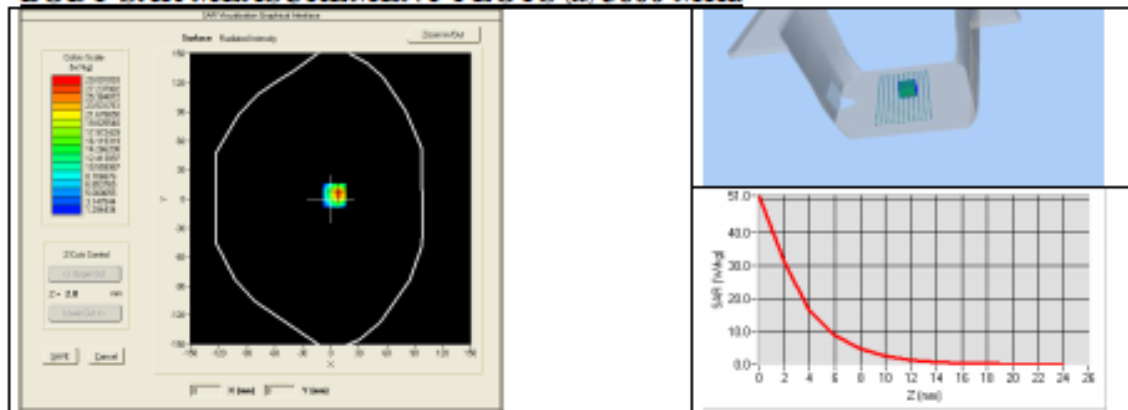
### BODY SAR MEASUREMENT PLOTS @ 5200 MHz



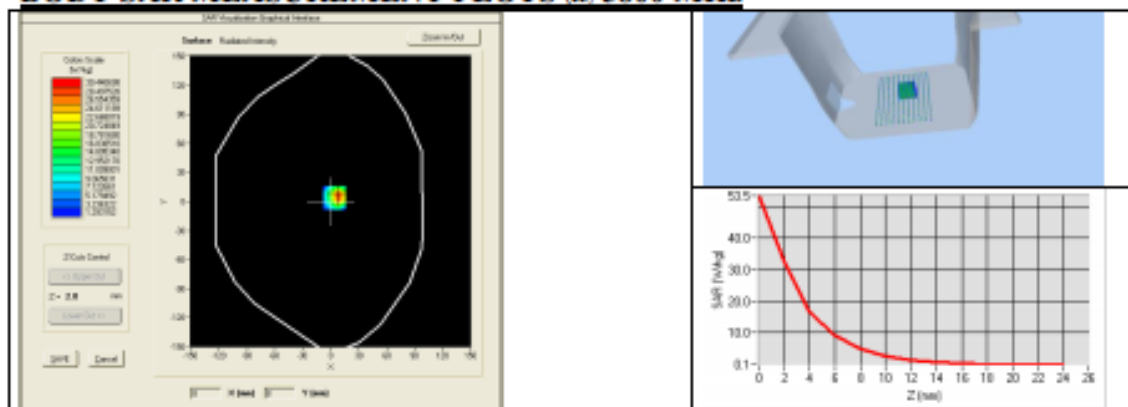
### BODY SAR MEASUREMENT PLOTS @ 5400 MHz



### BODY SAR MEASUREMENT PLOTS @ 5600 MHz



### BODY SAR MEASUREMENT PLOTS @ 5800 MHz



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## 8 LIST OF EQUIPMENT

Equipment Summary Sheet				
Equipment Description	Manufacturer / Model	Identification No.	Current Calibration Date	Next Calibration Date
Flat Phantom	Satimo	SN-20/09-SAM71	Validated. No cal required.	Validated. No cal required.
COMOSAR Test Bench	Version 3	NA	Validated. No cal required.	Validated. No cal required.
Network Analyzer	Rhode & Schwarz ZVA	SN100132	02/2013	02/2016
Calipers	Carrera	CALIPER-01	12/2013	12/2016
Reference Probe	Satimo	EPG122 SN 18/11	Characterized prior to test. No cal required.	Characterized prior to test. No cal required.
Multimeter	Keithley 2000	1188656	12/2013	12/2016
Signal Generator	Agilent E4438C	MY49070581	12/2013	12/2016
Amplifier	Aethercomm	SN 046	Characterized prior to test. No cal required.	Characterized prior to test. No cal required.
Power Meter	HP E4418A	US38261498	12/2013	12/2016
Power Sensor	HP ECP-E26A	US37181460	12/2013	12/2016
Directional Coupler	Narda 4216-20	01386	Characterized prior to test. No cal required.	Characterized prior to test. No cal required.
Temperature and Humidity Sensor	Control Company	11-661-9	8/2012	8/2015

## Annex B SAR System PHOTOGRAPHS



Liquid depth  $\geq 15\text{cm}$



## Annex C SETUP PHOTOGRAPHS

Body Setup Photo (LCD UP)



Body Setup Photo (LCD DOWN)



Body Setup Photo (Right EDGE)





**Body Setup Photo (Top EDGE)**



## Annex D EUT PHOTOGRAPHS

### EUT-Front Side View



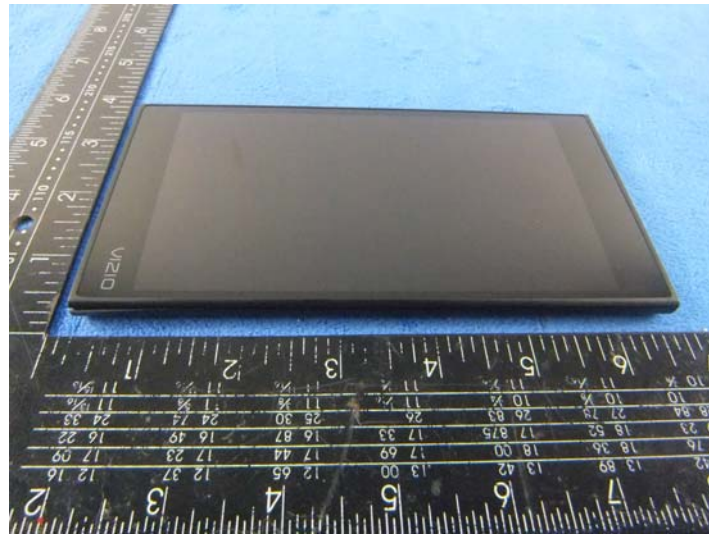
### EUT-Back Side View



### EUT-Left edge View



**EUT-Right edge View**



**EUT-Top edge View**



**EUT-Bottom edge View**

